# INTRODUCTION TO DYNAMICAL SYSTEMS AND CHAOTIC SYSTEMS

### **EXERCISE 6**

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#### 1. Epidemic

The following simple model for the evolution of an epidemic was proposed by Kermack and McKendrick in 1972. It consider the number of healthy people x and the number of sick people y subject to the equation

$$\dot{x} = -kxy, \qquad \qquad \dot{y} = kxy - ly$$

with constants k, l > 0.

- (1) Discuss the equation in the group. Try to argue for the terms but also keep in mind that certain effects are not represented in the equation.
- (2) Find and classify all fixed points.
- (3) Sketch the nullclines and the vector field.
- (4) Find a conserved quantity. It may help to find a differential equation of dy/dx and solve it.
- (5) Under what initial condition  $(x_0, y_0)$  does y increase initially. (This could be called an *epidemic*.) What happens as  $t \to \infty$ ?

## 2. Vector Fields of Gradient Systems

Show that the trajectory of a gradient system  $\dot{\mathbf{x}} = -\nabla V$  always crosses any equipotential  $\{\mathbf{x} \mid V(\mathbf{x}) = \alpha\}$  with  $\alpha \in \mathbb{R}$  at a right angle.

Sketch the vector field for the following gradient systems with

(1) 
$$V(x,y) = x^2 + y^2$$
, (2)  $V(x,y) = x^2 - y^2$ , (3)  $V(x,y) = e^x \sin y$ .

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$$V(x,y) = x^2 - y^2$$
,

$$(3) V(x,y) = e^x \sin y.$$

### 3. Is it a Gradient System?

Find the gradient for the following system

$$\dot{x} = y^2 + y\cos x, \qquad \qquad \dot{y} = 2xy + \sin x,$$

that is, find a function  $V: \mathbb{R}^2 \to \mathbb{R}$  satisfying  $\dot{\mathbf{x}} = -\nabla V$ . Optional: Why is this system indeed a gradient system?

# 4. Limit Cycle

Consider the following system

$$\dot{x} = x - y - x(x^2 + 5y^2),$$
  $\dot{y} = x + y - y(x^2 + y^2).$ 

- (1) The origin is clearly a fixed point. What kind of fixed point?
- (2) Rewrite the system in polar coordinates. Hint: Recall that for the radius r and the angle  $\theta$  you have  $r\dot{r} = x\dot{x} + y\dot{y}$ and  $\dot{\theta} = (x\dot{y} - y\dot{x})/r^2$ .

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- (3) Determine the maximal radius  $r_0$  and the minimal radius  $R_0$  such that no trajectories can leave the corresponding annulus  $\{(x,y) \mid r_0^2 \leq x^2 + y^2 < R_0^2\}$ .
- (4) Conclude that the system has a limit cycle within the annulus.

### 5. Approximate Limit Cycle

For a constant  $\mu > 0$  consider the equation  $\ddot{x} + \mu f(x)\dot{x} + x = 0$  with the **non-smooth** function f given by f(x) = -1 whenever |x| < 1 and f(x) = 1 otherwise.

(1) Show that the system can be equivalently transformed into

$$\dot{x} = \mu(y - F(x)), \qquad \qquad \dot{y} = -x/\mu$$

with the continuous, piecewise linear function

$$F(x) := \begin{cases} x + 2 & , x \le -1, \\ -x & , |x| \le 1, \\ x - 2 & , x \ge 1. \end{cases}$$

- (2) Sketch the nullclines and the vector field.
- (3) Show that the system exhibits relaxation oscillations for  $\mu \gg 1$ .
- (4) For  $\mu \gg 1$  find the limit cycle and estimate its period.