# INTRODUCTION TO DYNAMICAL SYSTEMS AND CHAOTIC **SYSTEMS**

#### **EXERCISE 4**

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#### 1. Speed Up the Basics

For the following linear systems, plot the phase portrait and classify all fixed points.

- (1)  $\dot{x} = y$ ,  $\dot{y} = -2x 3y$ ,
- (2)  $\dot{x} = 5x + 10y, \ \dot{y} = -x y,$
- (4)  $\dot{x} = 5x + 2y, \ \dot{y} = -17x 5y,$
- (3)  $\dot{x} = 3x 4y, \ \dot{y} = x y,$ (5)  $\dot{x} = 4x 3y, \ \dot{y} = 8x 6y,$ (5)  $\dot{x} = 4x - 3y, \ \dot{y} = 8x - 6y,$
- (6)  $\dot{x} = y, \, \dot{y} = -x 2y.$

## 2. Damped Harmonic Oscillator

The damped harmonic oscillator is given by the equation

$$m\ddot{x} + b\dot{x} + kx = 0$$

where m > 0 denotes the mass of the particle, b > 0 is a friction constant, and k > 0 describes the strength of the potential field.

- (1) Rewrite the equation as a linear two-dimensional system. You may also want to get rid of one of the constants, preferably m.
- (2) What type of fixed point is the origin depending on the parameters? Sketch the phase portrait in each case.
- (3) Find a one-dimensional system that arguably describes well the case with high friction.

# 3. Phase Portraits

For the following non-linear systems, sketch the vector field and the phase portrait. In particular, what are the fixed points and what is their type?

Hint: You may want to conform your sketched portraits using the computer.

(1)  $\dot{x} = x - y, \, \dot{y} = 1 - e^x,$ 

- (2)  $\dot{x} = x x^3, \ \dot{y} = -y,$ (4)  $\dot{x} = x^2 y, \ \dot{y} = x y.$
- (3)  $\dot{x} = x(x-y), \ \dot{y} = y(2x-y),$

What are stable and unstable manifolds in each case?

## 4. Working Backwards

For each of the following cases, find and sketch a phase portrait that satisfies the given property

- (1) These are precisely two saddle fixed points and a single trajectory that connects them (heteroclinic).
- (2) There are precisely two saddle fixed points and not a single trajectory connects them (no heteroclinic).

Optional: Find (simple) equations for the phase portraits.

Date: 2nd Oct. 2015.

## 5. Linearization is not Enough, Example 1

Consider the system  $\dot{x} = xy$ ,  $\dot{y} = x^2 - y$ .

- (1) Show that the origin is the only fixed point.
- (2) What type of fixed point is the origin? Sketch the vector field around the origin.
  - 6. Linearization is not Enough, Example 2

Consider the system  $\dot{x} = -x^3 - y$ ,  $\dot{y} = x$ .

- (1) Show that the origin is the only fixed point.
- (2) What type of fixed point is the origin? Sketch the vector field around the origin.