

1. Green's formulae and all that

1.1. The fundamental thm. of calculus

Recall: if $f \in C^1[a, b]$, then

$$\int_a^b f' dx = f(b) - f(a)$$

involves values of f only at
end pts

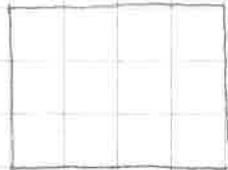


Does this have an analogue in \mathbb{R}^n , $n > 1$?

Ans: Yes!

To see what it is, let's start with a trivial example:

$$\Omega = [a, b] \times [c, d]$$



We want to compute

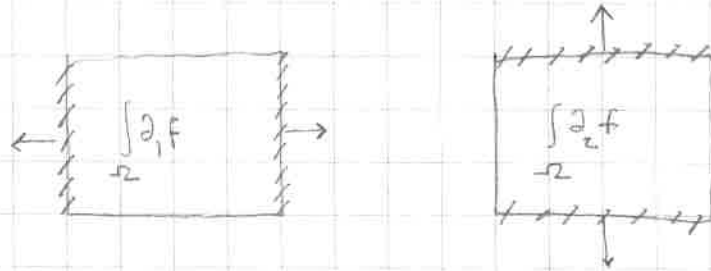
$$\int_{\Omega} \partial_1 f dx_1 dx_2 \quad \text{and} \quad \int_{\Omega} \partial_2 f dx_1 dx_2$$

$$\partial_i = \frac{\partial}{\partial x_i}$$

$$\int_{\Omega} \partial_1 f dx_1 dx_2 = \int_c^d \left(\int_a^b \frac{\partial f}{\partial x_1}(x_1, x_2) dx_1 \right) dx_2 = \int_c^d f(b, x_2) dx_2 - \int_c^d f(a, x_2) dx_2$$

Likewise

$$\int_{\Omega} \partial_2 f dx_1 dx_2 = \int_a^b f(x_1, d) dx_1 - \int_a^b f(x_1, c) dx_1$$



If $n = (n_1, n_2)$ the exterior unit normal to $\partial\Omega$ (except at corners), we can write

$$\int_{\Omega} \partial_1 f dx_1 dx_2 = \int_{\partial\Omega} n_1 f dS, \quad \int_{\Omega} \partial_2 f dx_1 dx_2 = \int_{\partial\Omega} n_2 f dS$$

↑ has direction $\neq (1, 0)$
↑ has direction $\neq (0, 1)$

This is not very convincing. Let's look at a triangle

$x_2 = -kx_1 + k$
 $dS = \sqrt{1 + \left(\frac{dx_2}{dx_1}\right)^2} dx_1 = \sqrt{1 + k^2} dx_1$
 $x_1 = -\frac{1}{k}x_2 + 1$
 $dS = \sqrt{1 + \left(\frac{1}{k}\right)^2} dx_2 = \frac{1}{k} \sqrt{1 + k^2} dx_2$

Let's compute:

$$\iint_T \partial_1 f dx_1 dx_2 = \int_0^k \left(\int_0^{-\frac{x_2}{k}+1} \partial_1 f dx_1 \right) dx_2 = \int_0^k f\left(-\frac{x_2}{k}+1, x_2\right) dx_2$$

$$+ \int_0^k f(0, x_2) dx_2$$

$$= \int_{\partial T_3} f \frac{k}{\sqrt{1+k^2}} dS - \int_{\partial T_2} f dS$$

Now $n = \begin{cases} -(1, 0) & \text{on } \partial T_2 \\ -(0, 1) & \text{on } \partial T_1 \\ (k, 1)/\sqrt{k^2+1} & \text{on } \partial T_3 \end{cases}$

Hence

$$\iint_T \partial_1 f dx_1 dx_2 = \int_{\partial T} f n_1 dS$$

Similarly

$$\iint_T \partial_2 f dx_1 dx_2 = \int_{\partial T} f n_2 dS$$

This holds for any triangle (we can allow change of coordinates)

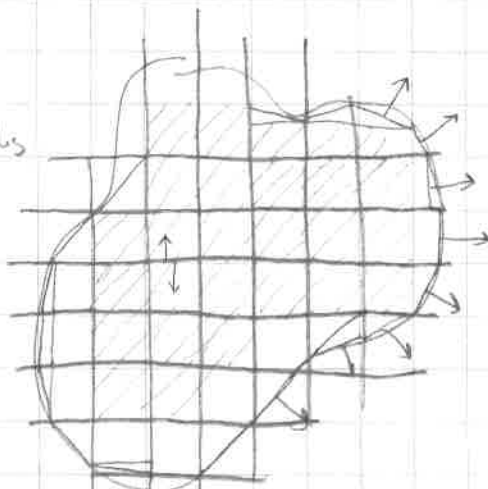
$$\iint_T \partial_i f dx = \int_{\partial T} f n_i dS$$

$$x_2 = -kx_1 + k \quad x_1 = \frac{x_2 - k}{-k} = -\frac{x_2}{k} + 1$$

Ans. domain

fill with small squares & triangles

integrals over common sides cancel (opposite normals)



Only integrals over free boundaries of triangles remain. Make this denser & denser: On the limit we get (8 gen. to higher dim.)

Prop. If $\Omega \subset \mathbb{R}^d$ is a C^k -domain ($k \geq 1$), then $\forall f \in C^1(\Omega) \cap C(\bar{\Omega})$,

$$\int_{\Omega} \frac{\partial f}{\partial x_k} dx = \int_{\partial \Omega} n_k f dS, \quad n = (n_1, \dots, n_d) \text{ ext. unit normal.}$$

1.2. Integration by parts.

We also have: Ω as above, $f, g \in C^1(\Omega) \cap C(\bar{\Omega})$,

$$\int_{\Omega} \frac{\partial f}{\partial x_k} g dx = \int_{\partial \Omega} n_k f g dS - \int_{\Omega} f \frac{\partial g}{\partial x_k} dS$$

Pf. Fund. thm of calc. \Rightarrow

$$\int_{\Omega} \frac{\partial f}{\partial x_k} g + f \frac{\partial g}{\partial x_k} dx = \int_{\Omega} \frac{\partial (fg)}{\partial x_k} dx = \int_{\partial \Omega} n_k fg dS \quad \square$$

1.3. Divergence thm.

Assume F is a C^1 vector field in Ω i.e.

$$F: \Omega \rightarrow \mathbb{R}^d, F = (F_1, \dots, F_d), F_k \in C^1(\Omega) \cap C(\bar{\Omega}).$$

Def. The divergence of F is

$$\operatorname{div} F(x) = \nabla \cdot F(x) = \sum_{k=1}^d \frac{\partial F_k(x)}{\partial x_k}.$$

Now we have

Thm. (Div. thm) If F is a C^1 -vector field in $\Omega \subset \mathbb{R}^d$,

Ω a d -domain, then

$$\int_{\Omega} \nabla \cdot F dx = \int_{\partial \Omega} \langle n, F \rangle dS$$

$$\langle n, F \rangle = n_1 F_1 + \dots + n_d F_d.$$

net flow of F
through $\partial \Omega$.

Pf. Fund. thm of calculus \Rightarrow

$$\int_{\Omega} \frac{\partial F_k}{\partial x_k} dx = \int_{\partial \Omega} n_k F_k dS.$$

Sum this over k . \square

It is a good idea to think what the condition $\nabla F = 0$ in Ω means.

Let U be any (small) subdomain with C^1 -bnd inside Ω .
Then

$$\int_{\partial U} \langle n, F \rangle dS = \int_U \nabla \cdot F dx = 0.$$

i.e. net flow of F through "any" surface inside Ω is 0!
i.e. no sinks or sources!

1.4. Gauss's thm.

Let $u \in C^2(\Omega) \cap C^1(\bar{\Omega})$, Ω as above.

Then gradient of u ,

$$F = \nabla u$$

is a C^1 -vector field in Ω .

Let's apply div-thm to this field. Now

$$\nabla \cdot F = \sum_k \frac{\partial F_k}{\partial x_k} = \sum_k \frac{\partial}{\partial x_k} \left(\frac{\partial u}{\partial x_k} \right) = \sum_k \frac{\partial^2 u}{\partial x_k^2} = \Delta u$$

i.e. div. thm \Rightarrow

$$\int_{\Omega} \Delta u \, dx = \int_{\Omega} \nabla \cdot F \, dx = \int_{\partial \Omega} \langle n, F \rangle \, dS = \int_{\partial \Omega} \langle n, \nabla u \rangle \, dS$$

$$= \int_{\partial \Omega} \frac{\partial u}{\partial n} \, dS$$

\uparrow normal deriv.

Hence we have proven Gauss-thm:

$$\int_{\Omega} \Delta u \, dx = \int_{\partial \Omega} \frac{\partial u}{\partial n} \, dS.$$

This tells us something about the solvability of the Neumann-problems for Δ :

$$(N-\Delta) \begin{cases} \Delta u = 0 \text{ in } \Omega \\ \frac{\partial u}{\partial n} \Big|_{\partial \Omega} = g \text{ on } \partial \Omega. \end{cases}$$

Remember that $(N-\Delta)$ is not uniquely solvable:

If u is a sol., then so is $u + \text{const.}$ $\uparrow \Omega$ const.

Also, if g is such that $(N-\Delta)$ has a solution, then Gauss \Rightarrow

$$\int_{\partial \Omega} g \, dS = \int_{\Omega} \Delta u \, dx = 0$$

(Not a coincidence!)

i.e. integral of g over $\partial \Omega$ must vanish!

\uparrow also (1-D) if $\partial \Omega$ conn.

(Let $\langle g \rangle = \int_{\partial \Omega} g \, dS / \int_{\partial \Omega} 1 \, dS$)

Then $\int_{\partial \Omega} (g - \langle g \rangle) \, dS = 0$

1.5 Green's theorems

Now assume Ω as above, $u, v \in C^1(\Omega) \cap C^0(\bar{\Omega})$.
Then

$$\int_{\Omega} \frac{\partial u}{\partial x_k} v \, dx = \int_{\partial \Omega} n_k \frac{\partial u}{\partial x_k} v \, dS - \int_{\Omega} \frac{\partial u}{\partial x_k} \frac{\partial v}{\partial x_k} \, dx.$$

Summing over k we get

$$\int_{\Omega} \Delta u v dx = \int_{\partial \Omega} \frac{\partial u}{\partial n} v dS - \int_{\Omega} \langle \nabla u, \nabla v \rangle dx$$

i.e. 1st Green's formula. Changing roles of u & v we also get

$$\int_{\Omega} u \Delta v dx = \int_{\partial \Omega} u \frac{\partial v}{\partial n} dS - \int_{\Omega} \langle \nabla u, \nabla v \rangle dx,$$

and subtracting these we get the 2nd Green's formula

$$\int_{\Omega} \Delta u \cdot v - u \Delta v dx = \int_{\partial \Omega} \frac{\partial u}{\partial n} v - u \frac{\partial v}{\partial n} dS.$$

So - summing up here are the four important formulas:

$$\int_{\Omega} \nabla \cdot F dx = \int_{\partial \Omega} \langle n, F \rangle dS \quad (\text{Divergence thm.})$$

$$\int_{\Omega} \Delta u dx = \int_{\partial \Omega} \frac{\partial u}{\partial n} dS \quad (\text{Gauss thm.})$$

$$\int_{\Omega} \Delta u \cdot v dx = \int_{\partial \Omega} \frac{\partial u}{\partial n} v dS - \int_{\Omega} \langle \nabla u, \nabla v \rangle dx \quad (1^{\text{st}} \text{ Green})$$

$$\int_{\Omega} \Delta u \cdot v - u \Delta v dx = \int_{\partial \Omega} \frac{\partial u}{\partial n} v - u \frac{\partial v}{\partial n} dS \quad (2^{\text{nd}} \text{ Green})$$

1.6. Representation thms.

Recall that the radial solutions of $\Delta u = 0$ are

$$u(x) = \begin{cases} e^{\ln|x|}, & d=2, \quad x \neq 0 \\ C|x|^{\frac{2-d}{2}}, & d=3,4,\dots, \quad x \neq 0 \end{cases} \quad \left[\begin{array}{l} \text{HW 2/Ex 2} \\ \text{So note that} \\ \text{these are not} \\ \text{def. at 0} \end{array} \right]$$

Def. The functions

$$\bar{\Phi}(x) = \begin{cases} -\frac{1}{2\pi} \ln|x|, & x \neq 0, \quad d=2, \\ \frac{1}{(d-2)\omega_d} |x|^{2-d}, & x \neq 0, \quad d=3,4,\dots \end{cases}$$

where $\omega_d = \text{area of } \{ |x|=1; x \in \mathbb{R}^d \}$

$$= d\pi^{d/2} / \Gamma\left(\frac{d}{2} + 1\right) \quad \left(\leftarrow \text{Euler's Gamma Fun.} \right)$$

are fundamental solutions of Δ in \mathbb{R}^d . Note

$$\begin{aligned} \omega_3 &= 3\pi^{3/2} / \Gamma(5/2) = 3\pi^{3/2} / \frac{3}{2} \Gamma(3/2) \\ &= 2\pi^{3/2} / \frac{1}{2} \Gamma(1/2) = \pi^{3/2} / \Gamma(1/2) = 4\pi^{3/2} / \pi^{1/2} = 4\pi \end{aligned}$$

i.e. $\bar{\Phi}(x) = \begin{cases} -\frac{1}{2\pi} \ln|x|, & x \neq 0, \quad d=2 \\ \frac{1}{4\pi} |x|^{-1}, & x \neq 0, \quad d=3 \end{cases} \quad \left(\begin{array}{l} \text{The important} \\ \text{cases!} \end{array} \right)$

The normalizations chosen are important for the following reason:

Thm. (Rep. thm.) If Ω is a bnd C^1 -domain ^{of $\mathbb{R}^d, d \geq 2$} and $u \in C^2(\Omega) \cap C^1(\bar{\Omega})$, then $\forall x \in \Omega$:

$$u(x) = \int_{\partial\Omega} \left\{ \Phi(x-y) \frac{\partial u(y)}{\partial n(y)} - \frac{\partial \Phi(x-y)}{\partial n(y)} u(y) \right\} dS(y) - \int_{\Omega} \Phi(x-y) \Delta u(y) dy, \quad x \in \Omega$$

Note that this is true for any function $u \in C^2(\Omega) \cap C^1(\bar{\Omega})$. If $\Delta u = 0$ in Ω we get a corollary:

Cor. (Rep. thm. for harmonic functions) If Ω is as above, and $u \in C^2(\Omega) \cap C^1(\bar{\Omega})$, and harmonic in Ω i.e.

$$\Delta u = 0 \text{ in } \Omega,$$

then $\forall x \in \Omega$:

$$u(x) = \int_{\partial\Omega} \left\{ \Phi(x-y) \frac{\partial u(y)}{\partial n(y)} - \frac{\partial \Phi(x-y)}{\partial n(y)} u(y) \right\} dS(y).$$

Hence: If one knows u & $\partial u / \partial n$ on $\partial\Omega$,

one knows explicitly u inside!

Is this useful? Not immediately. Why?

Well, you can't fix both $u|_{\partial\Omega}$ & $\partial_n u|_{\partial\Omega}$ for sols of harmonic functions!

Explanation Let $f \in C(\partial\Omega)$. The problem

$$(0) \quad \begin{cases} \Delta u = 0 \text{ in } \Omega \\ u|_{\partial\Omega} = f \text{ on } \partial\Omega \end{cases}$$

has at most one solution (We don't know yet if it even has a solution!).

If $g \neq \partial u / \partial n$ (u ^{unique} sol. of (0)), then there is no v s.t.

$$\begin{cases} \Delta v = 0 \text{ in } \Omega \\ v|_{\partial\Omega} = f, \quad \partial_n v|_{\partial\Omega} = g \end{cases}$$

and in particular if

$$w(x) := \int_{\partial\Omega} \left\{ \Phi(x-y) g(y) - \frac{\partial \Phi(x-y)}{\partial n(y)} f(y) \right\} dS(y),$$

either $w|_{\partial\Omega} \neq f$ or $\partial_n w \neq g$ (if those values even exist!).

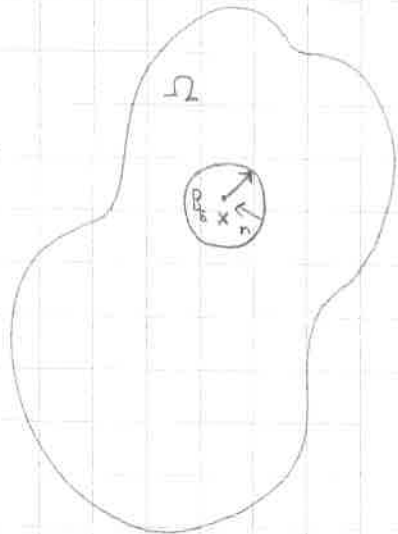
Proof of Rep. thm: Let $x \in \Omega$ be fixed and choose $\varepsilon > 0$ so small that

$$\overline{B_\varepsilon(x)} \subset \Omega$$

$$\text{Let } \Omega_\varepsilon = \Omega \setminus \overline{B_\varepsilon(x)}.$$

Note that Ω_ε is a C^1 -domain, and for the exterior unit normal we have

$$n = \begin{cases} n = \text{ext. unit normal of } \Omega \\ \text{on } \partial\Omega \\ \frac{x-y}{|x-y|} \text{ on } \partial B_\varepsilon(x) \end{cases}$$



Now

$$y \mapsto \Phi(x-y)$$

is harmonic in Ω_ε since $y \neq x$ in Ω_ε ! Hence Green \Rightarrow

$$\int_{\Omega_\varepsilon} \underbrace{\Delta \Phi(x-y) u(y) - \Phi(x-y) \Delta u(y)}_0 dy$$

$$= \int_{\partial\Omega_\varepsilon} \frac{\partial \Phi(x-y)}{\partial n(y)} u(y) - \Phi(x-y) \frac{\partial u}{\partial n(y)} dS(y)$$

i.e. we have

$$-\int_{\Omega_\varepsilon} \Phi(x-y) \Delta u(y) dy = \int_{\partial\Omega} + \int_{\partial B_\varepsilon} \frac{\partial \Phi(x-y)}{\partial n(y)} u(y) - \Phi(x-y) \frac{\partial u}{\partial n(y)} dS(y).$$

Now Dom. Conv. (Φ ^{loc.} integrable over \mathbb{R}^d)

$$\lim_{\varepsilon \rightarrow 0} \int_{\Omega_\varepsilon} \Phi(x-y) \Delta u(y) dy = \int_{\Omega} \Phi(x-y) \Delta u(y) dy \quad \text{Exc. the integral on } \Omega \text{ we want}$$

The integral over $\partial\Omega$ is exactly what it should.

Let's study $\int_{\partial B_\varepsilon} \dots dS$.

I. Let's ^{1st} look into

$$\int_{\partial B_\varepsilon(x)} \Phi(x-y) \frac{\partial u}{\partial n(y)} dS(y).$$

Now $|y-x| = \varepsilon$,

$$|\Phi(x-y)| = \begin{cases} C \ln \varepsilon \\ C \varepsilon^{2-d} \end{cases}$$

and area of $\partial B_\varepsilon(x) = \omega_d \varepsilon^{d-1}$; hence size $\frac{\partial u}{\partial n}$ unq. bnd,

$$\left| \int_{\partial B_\varepsilon(x)} \bar{\Phi}(x-y) \frac{\partial u(y)}{\partial n(y)} dS(y) \right| \leq \begin{cases} C \varepsilon \ln \varepsilon \rightarrow 0 & \text{as } \varepsilon \rightarrow +0 \\ & \text{if } d=2 \\ C \varepsilon^{d-1} \cdot \varepsilon^{2-d} = C \varepsilon \rightarrow 0 & \text{as } \varepsilon \rightarrow 0 \\ & \text{if } d \geq 3 \end{cases}$$

$$\therefore \lim_{\varepsilon \rightarrow +0} \int_{\partial B_\varepsilon} \bar{\Phi}(x-y) \frac{\partial u(y)}{\partial n(y)} dS(y) = 0$$

II We are still missing the term $u(x)$, and so it has to come from

$$\int_{\partial B_\varepsilon(x)} \frac{\partial \bar{\Phi}(x-y)}{\partial n(y)} u(y) dS(y).$$

Let's see why! We need to compute $\partial \bar{\Phi}(x-y) / \partial n(y)$.
Now

$$\nabla_x \bar{\Phi}(x-y) = \begin{cases} -\frac{1}{2\pi} \frac{x-y}{|x-y|^2} (-1) = \frac{1}{2\pi} \frac{x-y}{|x-y|^2}, & d=2 \\ \frac{1}{(d-2)\omega_d} \cdot (2-d) r^{1-d} \frac{x-y}{|x-y|} (-1), & d \geq 3 \end{cases}$$

$$= \begin{cases} \frac{1}{2\pi} \frac{x-y}{|x-y|}, & d=2 \\ \frac{1}{\omega_d} \frac{x-y}{|x-y|} r^{1-d}, & d \geq 3. \end{cases}$$

Also on $\partial B_\varepsilon(x)$ the ext. unit normal of Ω_ε is $\frac{y-x}{|x-y|}$, and hence if $d=2$, $x \in \partial B_\varepsilon(x)$ ($\Leftrightarrow |x-y| = \varepsilon$)

$$\frac{\partial \bar{\Phi}(x-y)}{\partial n(y)} = \left\langle \frac{y-x}{|x-y|}, \frac{1}{2\pi} \frac{x-y}{|x-y|^2} \right\rangle = -\frac{1}{2\pi \varepsilon}$$

and if $d \geq 3$, $|x-y| = \varepsilon$,

$$\frac{\partial \bar{\Phi}(x-y)}{\partial n(y)} = \left\langle \frac{y-x}{|x-y|}, \frac{1}{\omega_d} \frac{x-y}{|x-y|} r^{1-d} \right\rangle = -\frac{1}{\omega_d} \varepsilon^{1-d}$$

i.e. always

$$\frac{\partial \bar{\Phi}(x-y)}{\partial n(y)} = -\frac{1}{\omega_d} \varepsilon^{1-d},$$

and we have

$$\int_{\partial B_\varepsilon(x)} \frac{\partial \bar{\Phi}(x-y)}{\partial n(y)} u(y) dS(y) = -\frac{1}{\omega_d} \varepsilon^{1-d} \int_{|y-x|=\varepsilon} u(y) dS(y)$$

$$= -\frac{1}{\omega_d} \varepsilon^{1-d} \varepsilon^{d-1} \omega_d \frac{1}{|\partial B_\varepsilon(x)|} \int_{|y-x|=\varepsilon} u dS(y)$$

$$\xrightarrow{\varepsilon \rightarrow +0} -u(x).$$

Hence taking $\varepsilon \rightarrow +0$ in (**) we get

$$-\int_{\Omega} \bar{\Phi}(x-y) \Delta(y) dy = \int_{\partial \Omega} \frac{\partial \bar{\Phi}(x-y)}{\partial n(y)} u(y) - \bar{\Phi}(x-y) \frac{\partial u(y)}{\partial n(y)} dS(y) + u(x). \quad \square$$

1.7. Green's functions.

Assume Ω a bnd C^1 -domain, $u \in C^2(\Omega) \cap C^1(\bar{\Omega})$ harmonic in Ω . Then by Rep-thm:

$$(1) \quad u(x) = \int_{\partial\Omega} \Phi(x-y) \frac{\partial u(y)}{\partial n(y)} - \frac{\partial \Phi(x-y)}{\partial n(y)} u(y) dS(y).$$

Assume now $v \in C^2(\Omega) \cap C^1(\bar{\Omega})$ is also harmonic in Ω : then

$$(2) \quad 0 = \int_{\partial\Omega} v(y) \frac{\partial u(y)}{\partial n(y)} - \frac{\partial v(y)}{\partial n(y)} u(y) dS(y)$$

$$\left(\int_{\Omega} \underbrace{v \Delta u}_{0} - \underbrace{\Delta v}_{0} \cdot u \right) dy$$

|| Green 2nd

Subtracting (2) from (1) we get

$$u(x) = \int_{\partial\Omega} [\Phi(x-y) - v(y)] \frac{\partial u(y)}{\partial n(y)} - \frac{\partial [\Phi(x-y) - v(y)]}{\partial n(y)} u(y) dS(y)$$

∴ i.e. we may add any harmonic fnc to Φ and Rep-thm still holds! ∴

Why is this useful? Well, given a fixed x assume that we can find harmonic v_x s.t.

$$\uparrow \text{ i.e. } \Delta_y v_x(y) = 0 \text{ in } \Omega$$

s.t. $v_x(y) = \Phi(x-y) \quad \forall y \in \partial\Omega$. Then letting

$$G(x,y) = \Phi(x-y) - v_x(y) \quad \left[\begin{array}{l} \text{Dirichlet Green's} \\ \text{function for } \Omega \end{array} \right]$$

we have

↓ depends only on Dirichlet data?

$$(*) \quad u(x) = - \int_{\partial\Omega} \frac{\partial}{\partial n(y)} G(x,y) u(y) dS(y) \quad \nabla!$$

Does this solve all our Dirichlet problems? Well there are problems:

(a) How to find G i.e. $v_x(y)$ for given $x \in \Omega$? This is equivalent to solving another Dirichlet problem (actually one for every $x \in \Omega$):

$$\begin{cases} \Delta_y v_x(y) = 0 & \forall y \in \Omega \\ v_x = \Phi(x-\cdot) & \text{on } \partial\Omega. \end{cases}$$

Not a big help!

(b) Assume we want to solve

$$\begin{cases} \Delta u = 0 & \text{in } \Omega \\ u|_{\partial\Omega} = f. \end{cases}$$

Is $u(x) = - \int_{\partial\Omega} \frac{\partial}{\partial n(y)} G(x-y) f(y) dS(y)$ a solution?

Note that it is not obvious that $\Delta_x G(x-y) = 0$ and since $|\Phi(x-y)| \rightarrow \infty$ as $x \rightarrow y$, it is not obvious how to prove that

$$\lim_{x \rightarrow x_0} u(x) = f(x_0),$$

$\Omega \ni x \rightarrow x_0$
 $x_0 \in \partial\Omega$

1.7. Existence of G

This usually works only for domains with enough symmetries. One can prove that G exists in the general case, but there is usually no explicit formula! However sometimes this works.

Examine if $\Omega = \mathbb{R}_+^d = \{x \in \mathbb{R}^d; x_d > 0\}$ even if not bnd.

Let $x \in \Omega$, $x_d > 0$.

Let $\tilde{x} = (x_1, \dots, x_{d-1}, -x_d)$

"reflection of x w.r.t. $x_d = 0$ ".

Then $\Phi(\tilde{x}-y)$ is harmonic as a function of y if $y \neq \tilde{x}$ i.e.

$$\Delta_y \Phi(\tilde{x}-y) = 0 \text{ in } \Omega.$$

$$\text{Also if } x_d = 0 \Rightarrow x = \tilde{x} \Rightarrow \Phi(x-y) = \Phi(\tilde{x}-y).$$

Hence we may take (think why - !)

$$G(x-y) = \Phi(x-y) - \Phi(\tilde{x}-y)$$

Computing this expl. out is left to HW.

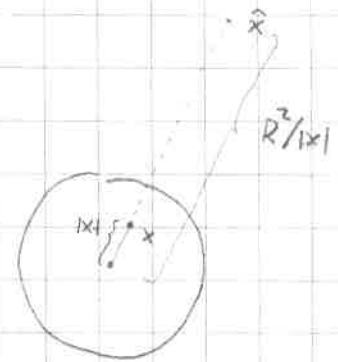
One can do in principle the same thing in $B_R(0)$:

Given $x \in B_R(0)$, let

$$\tilde{x} = \frac{R^2}{|x|^2} x,$$

$$|\tilde{x}| = R^2/|x| = R \left(\frac{R}{|x|} \right) > R$$

$$\begin{cases} \rightarrow \infty \text{ as } |x| \rightarrow 0 \\ \rightarrow R \text{ as } |x| \rightarrow R \end{cases}$$



This is the Kelvin-transform of x

Then we define again

$$G(x,y) = \Phi(x-y) - \left(\frac{R}{|x|} \right)^{d-2} \Phi(\tilde{x}-y).$$

You will show in HW4 that for $|y|=R$, $|x| < R$

$$\frac{\partial G(x,y)}{\partial n(y)} = \frac{1}{R^{d-2}} \frac{R^2 - |x|^2}{|x-y|^d}$$

and hence our guess for the solution of

$$\Delta u = 0 \text{ in } B_R(0), \quad u(x) = f(x) \text{ if } |x| = R$$

would be

$$u(x) = \frac{1}{R\omega_d} \int_{|y|=R} \frac{R^2 - |x|^2}{|x-y|^d} f(y) dS(y).$$

Now one can directly compute that

$$\Delta_x \left(\frac{R^2 - |x|^2}{|x-y|^d} \right) = 0 \quad \forall |x| < R, |y| = R.$$

so $\Delta u = 0$ in $B_R(0)$. One also has:

Prop. $\lim_{B_R(0) \ni x \rightarrow x_0} u(x) = f(x_0)$ for all $x_0 \in \partial B_R(0)$.

Pf. First an important observation: Since constant 1 is harmonic, we have (use (*) with $u \equiv 1$)

$$(**) \quad 1 = \frac{1}{R\omega_d} \int_{|y|=R} \frac{R^2 - |x|^2}{|x-y|^d} dS(y).$$

Fix $x_0 \in \partial B_R(0)$. Let $\varepsilon > 0$ and choose $\delta > 0$ s.t.

$$y \in \partial B_R(0), |y - x_0| < \delta \Rightarrow |f(y) - f(x_0)| < \varepsilon.$$

Now \Rightarrow

$$\varphi(x_0) = \frac{1}{R\omega_d} \int_{|y|=R} \frac{R^2 - |x_0|^2}{|x_0 - y|^d} \varphi(x_0) dS(y)$$



$$\Rightarrow u(x) - u(x_0) = \frac{1}{R\omega_d} \int_{|y|=R} \frac{R^2 - |x|^2}{|x-y|^d} (f(y) - f(x_0)) dS(y)$$

$$= \frac{1}{R\omega_d} \int_{\substack{|y|=R \\ |y-x_0| \geq \delta}} \frac{R^2 - |x|^2}{|x-y|^d} (f(y) - f(x_0)) dS(y) \\ + \int_{\substack{|y|=R \\ |y-x_0| < \delta}} \frac{R^2 - |x|^2}{|x-y|^d} (f(y) - f(x_0)) dS(y)$$

$$=: I_1(\delta) + I_2(\delta).$$

Now when $|x - x_0| < \delta/2$, we have

$$|y - x| \geq ||y - x_0| - |x_0 - x|| > \delta/2$$

and

$$\lim_{x \rightarrow x_0} \frac{1}{R\omega_d} \int_{\substack{|y|=R \\ |y-x_0| \geq \delta}} \frac{R^2 - |x|^2}{|x-y|^d} (f(y) - f(x_0)) dS(y) = 0 \quad (R^2 - |x|^2 \rightarrow 0!).$$

On the other hand,

$$|I_2(\delta)| \leq \frac{1}{R\omega_d} \int_{\substack{|y|=R \\ |y-x_0| < \delta}} \frac{R^2 - |x|^2}{|x-y|^d} \underbrace{|f(y) - f(x_0)|}_{< \varepsilon} dS(y)$$

$$< \varepsilon \frac{1}{R\omega_d} \int_{\substack{|y|=R \\ |y-x_0| < \delta}} \frac{R^2 - |x|^2}{|x-y|^d} dS(y) \leq \varepsilon \frac{1}{R\omega_d} \int_{|y|=R} \frac{R^2 - |x|^2}{|x-y|^d} dS(y) \\ = \varepsilon.$$

Since $\varepsilon > 0$ was arb., we have proven the claim! \square

2. Subharmonic functions and the Mean Value Property

2.1. Subharmonic functions - 1st def.

Let $\Omega \subset \mathbb{R}^d$ be open. A $u \in C^2(\Omega)$ is subharmonic if

$$(S_b) \quad \Delta u \geq 0 \text{ in } \Omega.$$

A function $u \in C^2(\Omega)$ is superharmonic if $-u$ is subharmonic.

$$(S_u) \quad \Delta u \leq 0 \text{ in } \Omega$$

We've seen ^{in HW!} that $\Delta u > 0$ in $\Omega \Rightarrow u$ has no local maxima.
 $\Delta u < 0$ " " " " " " " " minima.

To extend this to harmonic case $\Delta u = 0$ one needs information of mean values of sub & superharmonic functions.

Also these are needed in an ingenious pf. of solvability of Dirichlet-problems (not needing an explicit Green's function) due to O. Perron (1923)

2.2. Mean Value Property

Let $u \in C^2(\Omega) \cap C^1(\bar{\Omega})$ & Ω a bnd C^1 -domain.

As before

$$u(x) = \int_{\partial\Omega} \Phi(x-y) \frac{\partial u}{\partial n(y)} - \frac{\partial \Phi(x-y)}{\partial n(y)} u(y) dS(y) - \int_{\Omega} \Phi(x-y) \Delta u(y) dy$$

and if v harmonic, 2nd Green \Rightarrow

$$0 = \int_{\Omega} v(y) \frac{\partial u}{\partial n(y)} - \frac{\partial v(y)}{\partial n(y)} u(y) dS(y) - \int_{\Omega} v(y) \Delta u(y) dy.$$

Then we have for the Dir. Green's function (if it exists)

$$u(x) = - \int_{\partial\Omega} \frac{\partial G}{\partial n(y)}(x, y) u(y) dS(y) - \int_{\Omega} G(x, y) \Delta u(y) dy.$$

Let's choose $\Omega = B_R(x_0)$, $x = x_0$. Then

$$\begin{aligned} u(x_0) &= \frac{1}{\omega_d R^d} \int_{|y-x_0|=R} \frac{R^2 - |x-x_0|^2}{|y-x_0|^d} u(y) dS(y) \\ &\quad - \int_{|y-x_0| < R} G(x_0, y) \Delta u(y) dy. \\ &= \frac{1}{\omega_d R^d} \int_{|y-x_0|=R} u(y) dS(y) - \int_{|y-x_0| < R} G(x_0, y) \Delta u(y) dy \end{aligned}$$

What can we read from this?

Note that $R^{1-d}/\omega_d = 1/R^{d-1}\omega_d = 1/m(\partial B_R)$, and hence

$$\begin{aligned} \frac{R^{1-d}}{\omega_d} \int_{|y-x_0|=R} u(y) dS(y) &= \frac{1}{m(\partial B_R)} \int_{\partial B_R(x_0)} u dS(y) \\ &= \int_{\partial B_R(x_0)} u dS(y) = \text{average of } u \text{ over } \partial B_R(x_0). \\ &\quad \text{mean value} \end{aligned}$$

Hence, since $G(x,y) \geq 0$ (check this yourself!),

$$\begin{aligned} u(x_0) &= \int_{\partial B_R(x_0)} u dS(y) - \underbrace{\int_{B_R(x_0)} G(x,y) \Delta u(y) dy}_{\leq 0, \text{ if } \Delta u \geq 0} \\ &\geq 0, \text{ if } \Delta u \leq 0 \end{aligned}$$

Hence we have shown:

Prop. a) If $u \in C^2(\Omega)$ is subharmonic in Ω i.e. $\Delta u \leq 0$, then $\forall \overline{B_R(x_0)} \subset \Omega$ we have

$$u(x_0) \leq \int_{\partial B_R(x_0)} u dS(y)$$

b) If $u \in C^2(\Omega)$ is superharmonic in Ω i.e. $\Delta u \geq 0$ in Ω , then $\forall \overline{B_R(x_0)} \subset \Omega$ we have

$$u(x_0) \geq \int_{\partial B_R(x_0)} u dS(y)$$

c) If $u \in C^2(\Omega)$ is harmonic in Ω , then

$$u(x_0) = \int_{\partial B_R(x_0)} u dS(y),$$

So, u harmonic $\Rightarrow u(x_0) = \text{mean value of } u \text{ over balls centered at } x_0$
 subharmonic $\Rightarrow u(x_0) \leq$ —
 superharmonic $\Rightarrow u(x_0) \geq$ —

2.2. Generalization of sub/superharmonicity

Note that the mean value of u is well defined if integrals over $\partial B_R(x_0)$ exist. Hence we may drop the requirement that $u \in C^2(\Omega)$ and just define

Def. $\int_{\Omega} u \in C(\Omega)$
 $u: \Omega \rightarrow \mathbb{R}$ is subharmonic if $\forall x_0, R$ s.t. $\overline{B_R(x_0)} \subset \Omega$ we have

$$u(x_0) \leq \int_{\partial B_R(x_0)} u dS(y)$$

Similarly, $u \in C(\Omega)$ is superharmonic if $\forall x_0, R$ s.t. $\overline{B_R(x_0)} \subset \Omega$ we have

Of course this raises the question: how to define that u is harmonic if u a priori is only continuous. We will see in a moment that all these defs are in fact equivalent.

Lemma $\Omega \subset \mathbb{R}^d$, $d \geq 2$ bnd domain, if $u \in C(\bar{\Omega})$ is subharmonic in E , then either

• u is constant in Ω

or

• $u(x) < \sup_{\partial\Omega} u \quad \forall x \in \Omega$.

This is called strong maximum principle. Note that superharmonic functions satisfy a corresponding strong minimum principle.

Pf. $u \in C(\bar{\Omega})$ & Ω bnd $\Rightarrow \exists x_0 \in \bar{\Omega}$ s.t.

$$u(x_0) = \sup_{\bar{\Omega}} u.$$

Assume $u \neq u(x_0)$ (i.e. u not constant). If $x_0 \in \Omega$, then $\forall R > 0$ s.t. $\bar{B}_R(x_0) \subset \Omega$,

$$\sup_{\bar{\Omega}} u = u(x_0) = \int_{\partial B_R(x_0)} u \, dS$$

$$\Rightarrow u = u(x_0) \text{ in } \bar{B}_R(x_0).$$

Let $\mathcal{M} = \{x \in \Omega; u(x) = u(x_0)\}$.

Previous arg. $\Rightarrow \mathcal{M}$ open.

u cont. $\Rightarrow \mathcal{M}$ closed.

Ω connected $\Rightarrow \mathcal{M}$ is either $= \Omega$ or \emptyset .

If $\mathcal{M} = \Omega$, then u constant; hence $\mathcal{M} = \emptyset$ and

$$u(x) < \sup_{\bar{\Omega}} u \quad \forall x \in \Omega$$

and thus $\sup_{\bar{\Omega}} u = \max_{\bar{\Omega}} u = \max_{\partial\Omega} u$. \square

Def. $u \in C(\bar{\Omega})$ satisfies the mean value property (MVP) if

$$u(x_0) = \int_{\partial B_R(x_0)} u \, dS \quad \forall x_0 \in \Omega, R > 0 \text{ s.t. } \bar{B}_R(x_0) \subset \Omega.$$

Note: $u \in C^2(\Omega)$ & $\Delta u = 0$ in $\Omega \Rightarrow u$ sat. (MVP)!

Now we have:

Prop. $\Omega \subset \mathbb{R}^d$, $d \geq 2$ bnd domain. If u sat. (MVP) ^{in Ω} , then either u constant in Ω , or

$$|u(x)| < \sup_{\partial\Omega} |u| \quad \forall x \in \Omega.$$

Pf. u & $-u$ are subharmonic. \square

(In particular, (MVP) $\Rightarrow \max_{\bar{\Omega}} |u| = \max_{\partial\Omega} |u|$)

(slightly stronger version)

We can now give another pf of the uniqueness of the Dir. problem when Ω bnd domain:

$$\begin{cases} \Delta u = 0 & \text{in } \Omega \\ u|_{\partial\Omega} = f & \text{on } \partial\Omega \end{cases}, u \in C^2(\Omega) \cap C(\bar{\Omega})$$

Namely, if u_1 & u_2 are two sds, then $v = u_1 - u_2$ solves

$$\begin{cases} \Delta v = 0 & \text{in } \Omega \\ v|_{\partial\Omega} = (u_1 - u_2)|_{\partial\Omega} = 0 & \text{on } \partial\Omega \end{cases}$$

$$\text{hence } \max_{\Omega} |v| = \max_{\partial\Omega} |v| = 0 \Rightarrow v = 0 \text{ in } \Omega.$$

Finally, one can characterize harmonicity with (MVP):

Thm. The following are equiv.; let $\Omega \Subset \mathbb{R}^d$.

(a) $u \in C^2(\Omega)$ and $\Delta u = 0$ in Ω

(b) $u \in C(\Omega)$ and u satisfies (MVP).

Remark: Note that (b) assumes only the continuity of u .

Pf. (a) \Rightarrow (b) already done.

So, assume that $u \in C(\Omega)$ and (MVP) holds.

Fix $x_0 \in \Omega$ and $R > 0$ s.t. $\overline{B_R(x_0)} \subset \Omega$.

Using Poisson kernel, we can find $v \in C^2(B_R(x_0)) \cap C(\bar{B}_R)$ s.t.

$$\begin{cases} \Delta v = 0 & \text{in } B_R(x_0) \\ v = u & \text{on } \partial B_R(x_0) \end{cases}$$

Now u sat. (MVP), v sat. (MVP) since v harmonic $\Rightarrow w = u - v$ sat. (MVP) in $B_R(x_0)$.

$$\text{Hence Max. Principle } \Rightarrow \sup_{B_R(x_0)} |w| = \sup_{\partial B_R(x_0)} |w| = 0 \text{ i.e.}$$

$$u = v \text{ in } B_R(x_0) \Rightarrow \text{claim. } \square$$

We will return to sub (& super) harmonic functions bit later.

2.3. Harnack's inequality

Thm. (Harnack 1889) $\Omega \Subset \mathbb{R}^d$, $\Delta u = 0$ in Ω and $\underline{u} \geq 0$. Then

$$\forall x \in \overline{B_\rho(x_0)} \subset B_R(x_0) \subset \Omega$$

we have the inequality

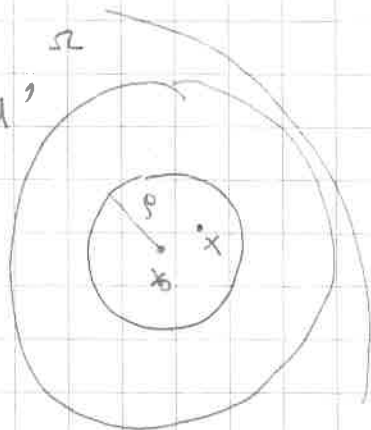
$$\left(\frac{R}{R+p}\right)^{d-2} \frac{R+p}{R+p} u(x_0) \leq u(x) \leq \left(\frac{R}{R-p}\right)^{d-2} \frac{R+p}{R-p} u(x_0)$$

"We can compare $u(x)$ to $u(x_0)$ ".

"If $u(x_0)$ small $\leadsto u(x)$ pretty small"

" $u(x_0)$ large $\leadsto u(x)$ - large"

Pf. We may make a translation s.t. $x_0 = 0$. Then



$$\begin{aligned} u(x) &= \text{Poisson kernel} \int_{\partial B_R} \frac{R^2 - |x|^2}{R \omega_d |x-y|^d} u(y) dS(y) \stackrel{(\Delta \text{ neg})}{\leq} \int_{\partial B_R} \frac{R^2 - |x|^2}{R \omega_d (|y|-|x|)^d} u(y) dS(y) \\ &= \frac{(R-|x|)^{d-2}}{(R+|x|)^{d-2}} \frac{1}{R \omega_d} \int_{\partial B_R} u(y) dS(y) = \left(\frac{R}{R-|x|}\right)^{d-2} \frac{R+|x|}{R-|x|} u(0) \\ &\stackrel{(\text{M.P.})}{=} \frac{R^{d-1}}{R \omega_d} u(0) \end{aligned}$$

Now $|x| < p \Rightarrow$

$$u(x) \leq \left(\frac{R}{R-p}\right)^{d-2} \frac{R+p}{R-p} u(0).$$

The other direction we leave as HW. \square

This has a dramatic consequence:

Thm. (Liouville's thm) Assume $u \geq 0$ and $\Delta u = 0$ in \mathbb{R}^d . Then u is constant.

Pf. Fix $x_0 \in \mathbb{R}^d$, $p > 0$. Then
Harnack \Rightarrow

$$u(x) \leq \left(\frac{R}{R-p}\right)^{d-2} \frac{R+p}{R-p} u(x_0) \quad \forall R > p$$

Letting $R \rightarrow \infty$ we get

$$u(x) \leq u(x_0).$$

Similarly the lower bound in Harnack gives

$$u(x_0) \leq u(x).$$

Hence $u(x) = u(x_0) \quad \forall x \in \mathbb{R}^d$. \square

Cor. If u harmonic & bnd. from below by a constant $\Rightarrow u = \text{const.}$

Pf. Choose $k \in \mathbb{R}$ s.t. $u(x) \geq k \quad \forall x \in \mathbb{R}^d$.
Then $v := u - k$ is harmonic, $v \geq 0$, in \mathbb{R}^d

$\Rightarrow v$ constant $(\Leftrightarrow) u$ constant. \square

2.4. Basic Properties of sub- and superharmonic functions

In the proof of the solvability of the Dirichlet-problem we need several further properties of sub- and superharmonic functions.

Def. If $\Omega \subset \mathbb{R}^d$, let

$$\delta(\Omega) := \{v \in C(\Omega); v \text{ subharmonic in } \Omega\}$$

$$\Sigma(\Omega) := \{ \text{" - " - ; " superharmonic " } \}$$

We have:

Prop. 2.4.1. If $v \in \delta(\Omega)$, and $\Omega' \subset \Omega$ then $v|_{\Omega'} \in \delta(\Omega')$.

Pf. Trivial \square

Prop. 2.4.2. If $v_i \in \delta(\Omega)$ ($v_i \in \Sigma(\Omega)$), $i=1, \dots, k$, then

$$v_1 + \dots + v_k \in \delta(\Omega) \text{ (or } \Sigma(\Omega)).$$

Pf. $v_1 + \dots + v_k \in C(\Omega)$ and for all $\overline{B_R(x_0)} \subset \Omega$,

$$v_1(x_0) + \dots + v_k(x_0) \leq \int_{\partial B_R(x_0)} v_1 dS + \dots + \int_{\partial B_R(x_0)} v_k dS$$

$$= \int_{\partial B_R(x_0)} (v_1 + \dots + v_k) dS.$$

Similarly for superharmonicity. \square

Prop. 2.4.2. If $v_1, \dots, v_k \in \delta(\Omega)$, then

$$\max\{v_1, \dots, v_k\} \in \delta(\Omega).$$

Pf. $\forall \overline{B_R(x_0)} \subset \Omega$ we have

$$v_i(x_0) \leq \int_{\partial B_R(x_0)} v_i dS \leq \int_{\partial B_R(x_0)} \max\{v_1, \dots, v_k\} dS$$

$$\Rightarrow \max\{v_1(x_0), \dots, v_k(x_0)\} \leq \int_{\partial B_R(x_0)} \max\{v_1, \dots, v_k\} dS. \square$$

Prop. 2.4.2. If $f: \mathbb{R} \rightarrow \mathbb{R}$ is convex & non-decreasing, then $v \in \delta(\Omega) \Rightarrow f \circ v \in \delta(\Omega)$.

Pf. f convex & non-dec. $\Rightarrow \forall \overline{B_R(x_0)} \subset \Omega$ we have

$$f(v(x_0)) \leq f\left(\int_{\partial B_R(x_0)} v dS\right) \stackrel{\text{Jensen}}{\leq} \int_{\partial B_R(x_0)} f(v) dS. \square$$

There is a very important construction that creates subharmonic modifications of harmonic functions:

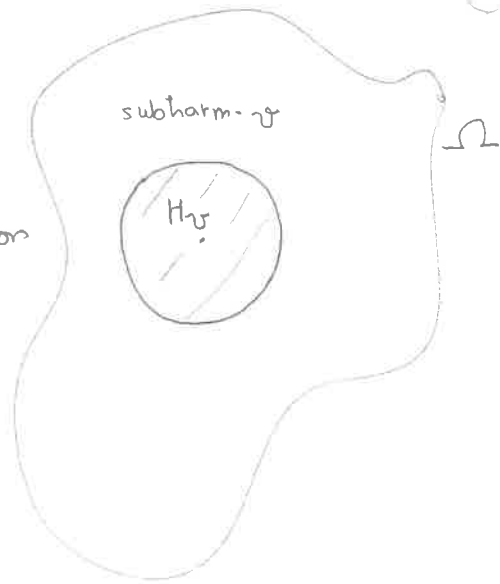
Assume $v \in \delta(\Omega)$, $\Omega \subset \mathbb{R}^d$ open.

Fix $B_p(\xi) \subset \Omega$ s.t. $\overline{B_p(\xi)} \subset \Omega$.

Solve using the Poisson kernel the Dirichlet problem

$$\Delta H = 0 \text{ in } B_p(\xi), \quad H|_{\partial B_p(\xi)} = v$$

H_v is the unique
harmonic extension
of v to $B_\rho(\xi)$



Define

$$v_{\rho, \xi} = \begin{cases} v & \text{in } \Omega \setminus B_\rho(\xi) \\ H_v & \text{in } B_\rho(\xi) \end{cases}$$

Then $v_{\rho, \xi}$ is continuous in Ω but usually not C^1 !

Now we have

Prop. (a) $v \leq v_{\rho, \xi}$ in Ω

(b) $v_{\rho, \xi} \in \delta(\Omega)$.

Pf. (a) Now $v \in \delta(B_\rho(\xi))$ and H_v harmonic

$\Rightarrow v - H_v \in \delta(B_\rho(\xi))$. Also $v - H_v|_{\partial B_\rho(\xi)} = 0$

Max.

$\Rightarrow v - H_v \leq 0$ in $B_\rho(\xi) \Leftrightarrow v \leq H_v$ in $B_\rho(\xi)$.

Princ.

(b) Let $\overline{B_R(x_0)} \subset \Omega$.

If $x_0 \in \Omega \setminus B_\rho(\xi)$, then

$$v_{\rho, \xi}(x_0) = v(x_0) \leq \int_{\partial B_R(x_0)} v dS \leq \int_{\partial B_R(x_0)} v_{\rho, \xi} dS.$$

Assume then $x_0 \in B_\rho(\xi)$.

Let's make a counter assumption: for some R , s.d.

$\overline{B_R(x_0)} \subset \Omega$ we have

$$v_{\rho, \xi}(x_0) > \int_{\partial B_R(x_0)} v_{\rho, \xi} dS.$$

Let

$$w = \begin{cases} v_{\xi, \rho} & \text{in } \Omega \setminus B_R(x_0) \\ H_{v_{\xi, \rho}} & \text{in } B_R(x_0) \end{cases}$$

We claim that

(*) $w \geq v_{x_0, R}$ in Ω .

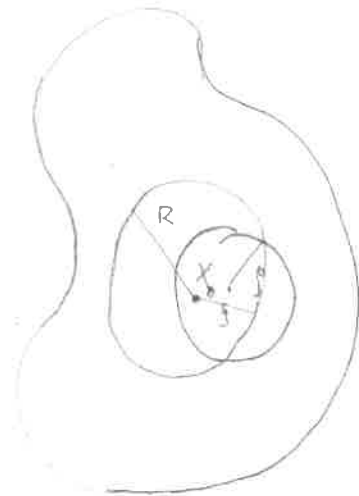
Now in $\Omega \setminus B_R(x_0)$,

$$w = v_{\xi, \rho} \geq v,$$

and on $\partial B_R(x_0)$,

$$w = H_{v_{\xi, \rho}}|_{\partial B_R} = v_{\xi, \rho}|_{\partial B_R(x_0)} \geq v|_{\partial B_R(x_0)} = v_{x_0, R}|_{\partial B_R}$$

and max. princ. gives (*).



w sat. (MVP) in $B_R(x_0)$,

$$(*) \quad w(x_0) = \int_{\partial B_R(x_0)} w dS = \int_{\partial B_R(x_0)} v_{p,\xi} dS < v_{p,\xi}(x_0)$$

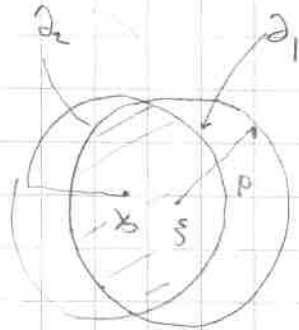
Counter exmpl.

$$\text{Now } v_{p,\xi} - w = H_v - H_{v_{p,\xi}} \text{ in } B_p(\xi) \cap B_R(x_0)$$

$$(**) \text{ i.e. } \Delta(v_{p,\xi} - w) = 0 \text{ in } B_p(\xi) \cap B_R(x_0)$$

$$\partial(B_p(\xi) \cap B_R(x_0)) = \partial_1 \cup \partial_2$$

(*), (**) $\Rightarrow v_{p,\xi} - w$ must have
a pos. maximum on $\partial_1 \cup \partial_2$.



$$(v_{p,\xi} - w)|_{\partial_1} = (v_{p,\xi} - H_{v_{p,\xi}})|_{\partial_1} = 0$$

$\Rightarrow \exists x^* \in \partial_2$ s.t.

$$v_{p,\xi}(x^*) > w(x^*) \geq v_{R,x_0}(x^*)$$

||

$v(x^*)$. Contradiction with (a). \square

2.5. Dir. problem.

(ESC)

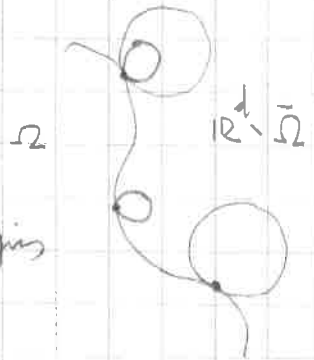
Def. $\Omega \subset \mathbb{R}^d$ satisfies the exterior sphere condition,

$\forall x^* \in \partial\Omega \exists$ ball $B_R(x^*) \subset \mathbb{R}^d \setminus \bar{\Omega}$ s.t.

$$\partial B_R(x^*) \cap \partial\Omega = \{x^*\}.$$

Note: Ω a C^1 -domain \Rightarrow
(ESC) holds.

HW: Come up with domains not satisfying
(ESC).



Thm. (Perron 1923 (Math. Z.)) Let $\Omega \subset \mathbb{R}^d$ be a bounded domain sat. (ESC). Then for all $\varphi \in C(\partial\Omega)$ there exists a unique $u \in C^2(\Omega) \cap C(\bar{\Omega})$ satisfying

$$\Delta u = 0 \text{ in } \Omega, \quad u|_{\partial\Omega} = \varphi.$$

Pf. Let

$$\delta(\varphi; \Omega) := \{v \in \delta(\Omega) \cap C(\bar{\Omega}); v|_{\partial\Omega} \leq \varphi\}$$

$$\Sigma(\varphi; \Omega) := \{v \in \Sigma(\Omega) \cap C(\bar{\Omega}); v|_{\partial\Omega} \geq \varphi\}$$

Observation 1

These sets are nonempty: Choose constants m and M

$$m \leq \varphi \leq M \quad \text{in } \partial\Omega.$$

constant fcn's

Then \sqrt{m} & M are harmonic $\Rightarrow m \in \delta(\varphi; \Omega)$,
 $M \in \Sigma(\varphi; M)$.

Observation 2 Assume u is a solution; if $v \in \delta(\varphi; \Omega)$,

Then $(v-u)|_{\partial\Omega} = 0$, $v-u$ subharmonic \Rightarrow

$$v-u \leq 0 \quad \text{in } \Omega \quad (\Leftrightarrow) \quad v \leq u.$$

Similarly, $w \in \Sigma(\varphi; \Omega) \Rightarrow u \leq w$.

Hence

^{a solution}
 if u exists, $v \leq u \leq w \quad \forall v \in \delta(\varphi; \Omega), w \in \Sigma(\varphi; \Omega)$.

Define now $u_- = \sup \{v; v \in \delta(\varphi; \Omega)\}$

$$u_+ = \inf \{w; w \in \Sigma(\varphi; \Omega)\}$$

Then if u exists,

$$u_- \leq u \leq u_+.$$

The Result will follow from the next two Lemmas:

Lemma a: u_- (& u_+) is harmonic in Ω

Lemma b: u_- (& u_+) $\in C(\bar{\Omega})$ and $u_{\pm}|_{\partial\Omega} = \varphi$.

The proofs are somewhat long & non-trivial.
 Let's start by proving Lemma a):

Pf. of Lemma a) Fix $x_0 \in \Omega$ & choose a sequence

$v_k \in \delta(\varphi; \Omega)$ s.t. (let $u_- = u$)

$$\lim_{k \rightarrow \infty} v_k(x_0) = u(x_0). \quad \left| (v_n) \text{ depends on } x_0! \right.$$

Let

$$V_n = \max \{v_1, \dots, v_n\}.$$

Then also $V_n \in \delta(\varphi; \Omega)$ and

$$V_n \leq V_{n+1} \quad \text{in } \Omega, \quad \lim_{n \rightarrow \infty} V_n(x_0) = u(x_0).$$

$\therefore (V_n)$ is an increasing sequence.

Assume

$$x_0 \in B_p(\xi) \subset \overline{B_p(\xi)} \subset \Omega.$$

Let $(V_n)_{p, \xi}$ be as defined above.

i.e. $(V_n)_{p, \xi} |_{\partial B_p(\xi)} = V_n$ & $(V_n)_{p, \xi}$ harmonic in $B_p(\xi)$.

Also,

$$\text{Max. Princ.} \Rightarrow \left| (V_n)_{p, \xi} - (V_{n+1})_{p, \xi} \right| |_{\partial B_p(\xi)} = (V_n - V_{n+1}) |_{\partial B_p(\xi)} \leq 0$$

$$\Rightarrow (V_n)_{p, \xi} \leq (V_{n+1})_{p, \xi}$$

i.e. $((V_n)_{p, \xi})$ is also increasing. Since

$$(V_n)_{p, \xi} \in \delta(\varphi; \Omega), \quad V_n \leq (V_n)_{p, \xi}$$

$$\text{and } u(x_0) = \sup \{ v(x_0); v \in \delta(\varphi; \Omega) \},$$

$$u(x_0) = \lim_{n \rightarrow \infty} V_n(x_0),$$

We also have

$$\lim_{n \rightarrow \infty} (V_n)_{p, \xi}(x_0) = u(x_0).$$

Hence \exists

$$\tilde{z}(x) = \lim_{n \rightarrow \infty} (V_n)_{p, \xi}(x)$$

A bad-idea-sequence
converges.

Now we have

Lemma C. \tilde{z} is harmonic in $B_p(\xi)$.

Let's postpone the pf. of Lemma C and see how this implies that u is harmonic.

We know

$$\tilde{z}(x_0) = u(x_0).$$

Fix $\tilde{x} \in B_p(\xi)$ and let $\{\tilde{v}_n\}, \{\tilde{V}_n\}$ be sequences s.t.

$$\tilde{v}_n \in \delta(\varphi; \Omega), \quad \tilde{v}_n(x) \rightarrow u(\tilde{x})$$

We repeat the construction at \tilde{x} !

$$\tilde{V}_n = \max \{ \tilde{v}_1, \dots, \tilde{v}_n, V_n \}$$

and construct $(\tilde{V}_n)_{p, \xi}$ as before.

Then Lemma C) $\Rightarrow \exists$ harmonic limit \tilde{z} ,

$$\tilde{z}(\tilde{x}) = u(\tilde{x}),$$

and since

$$\tilde{V}_n \geq V_n \Rightarrow (\tilde{V}_n)_{p, \xi} \geq (V_n)_{p, \xi}$$

we have $\hat{z} \geq z$ in $B_p(\xi)$.

Hence $\tilde{z} - z \geq 0$. Also, def. of u as $\sup \{ \dots \}$,
 $\text{in } B_\rho(\xi)$

$$u(x_0) = z(x_0) \leq \tilde{z}(x_0) \leq u(x_0),$$

and thus $z(x_0) = \tilde{z}(x_0)$. Max. Prins. $\Rightarrow \tilde{z} = z$ in $B_\rho(\xi)$,
 and thus

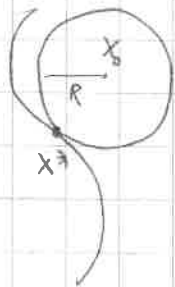
$$u(\tilde{x}) = \tilde{z}(\tilde{x}) = z(\tilde{x}) \quad \forall \tilde{x} \in B_\rho(\xi).$$

This proves Lemma a) (Mod Lemma c)).

Pf. of Lemma b): Fix $x^* \in \partial\Omega$ and let $B_R(x_0)$ be an
 exterior ball touching $\partial\Omega$ only at x^*

Let

$$H(x) = \begin{cases} \frac{1}{R^{d-2}} - \frac{1}{|x-x_0|^{d-2}} \\ \ln \frac{|x-x_0|}{R} \end{cases}$$



Then H is harmonic outside x_0 i.e. esp. in a neighborhood of
 Ω , and

$$\begin{cases} H(x) > 0 & \text{on } \partial\Omega \setminus \{x^*\}, \\ H(x^*) = 0 \end{cases}$$

Let $\varepsilon > 0$ and choose $\delta = \delta(\varepsilon)$ s.t.

$$|\varphi(x) - \varphi(x^*)| < \varepsilon \quad \text{if } x \in \partial\Omega, |x - x^*| < \delta.$$

We have yet another lemma:

Lemma d: \exists constant $C'_\varepsilon = C'_\varepsilon(\|\varphi\|_\infty, R, d, \delta(\varepsilon))$ s.t.

$$(\Leftarrow) \quad \forall x \in \partial\Omega: |\varphi(x) - \varphi(x^*)| < \varepsilon + C'_\varepsilon H(x).$$

Assume this for a moment:

Now $(\Leftarrow) \Rightarrow$

$$\varphi(x_*) - \varepsilon - C'_\varepsilon H \leq \varphi(x) \leq \varphi(x_*) + \varepsilon + C'_\varepsilon H$$

Hence

$$\varphi(x_*) + \varepsilon + C'_\varepsilon H \in \Sigma(\varphi; \Omega)$$

$$\varphi(x_*) - \varepsilon - C'_\varepsilon H \in \delta(\varphi; \Omega)$$

and thus

$$\varphi(x_*) - \varepsilon - C'_\varepsilon H \leq u(x) \leq \varphi(x_*) + \varepsilon + C'_\varepsilon H$$

\Leftrightarrow

$$|u(x) - \varphi(x_*)| \leq \varepsilon + C'_\varepsilon H.$$

Now when $x \rightarrow x^*$, we get $(H(x) \rightarrow \dots \text{ as } x \rightarrow x^*)$ ⁴³

$$\limsup_{x \rightarrow x^*} |u(x) - \varphi(x^*)| \leq \varepsilon$$

and since $\varepsilon > 0$ was arbitrary,

$$\lim_{x \rightarrow x^*} |u(x) - \varphi(x^*)| = 0.$$

So we need supplementary lemmas c and d; c will be proven in HW - it relies on Ascoli-Arzelà.

Let's prove lemma d:

Assume $\forall^{\delta} |x - x^*| < \delta$. Then since $H \geq 0$

$$|\varphi(x) - \varphi(x^*)| < \varepsilon < C_{\varepsilon} H(x),$$

Let then $|x - x^*| \geq \delta$. Now $\forall x \in \partial\Omega$,

$$|\varphi(x) - \varphi(x^*)| \leq 2 \sup_x |\varphi(x)| \frac{H(x)}{(\min_{\partial\Omega \cap \{|x-x^*| \geq \delta\}} H(x))}$$

when $\min_{\partial\Omega \cap \{|x-x^*| \geq \delta\}} H(x) > 0$.

Let $C_{\varepsilon} = \frac{2 \sup |\varphi(x)|}{\min_{\partial\Omega \cap \{|x-x^*| \geq \delta\}} H(x)}$. Then $|\varphi(x) - \varphi(x^*)| \leq C_{\varepsilon} H < \varepsilon + C_{\varepsilon} H$. \square

Function $\varphi \geq 0$ is subharmonic in $\mathbb{R}^d \setminus \bar{\Omega}$ (at $\infty = \infty$ at x_0) and $H(x) = 0 \Leftrightarrow x = x^*$.
 $x \in \partial\Omega$

Any function like this is called a barrier function at x^* , and the \exists of boundary values only need barriers at all boundary pts.

3. Heat equation

3.1. Basic questions: Heat eqn (or Diffusion eqn) with constant diffusion coefficient $k > 0$ is

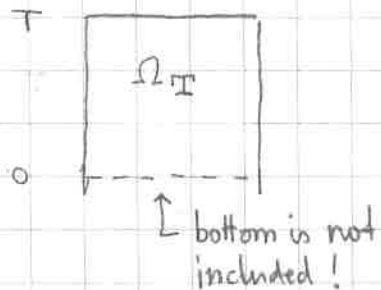
$$u_t - k \Delta u = 0, \quad t \in \mathbb{R}, \quad x \in \mathbb{R}^d.$$

Since we may rescale time $t' = kt$, $\frac{\partial u}{\partial t} = \frac{\partial u}{\partial t'} \frac{\partial t'}{\partial t} = k \frac{\partial u}{\partial t'}$, we may always assume $k=1$, and this is the equation we are going to study.

Some notations:

• If $\Omega \subset \mathbb{R}^d$, $T > 0$, let

$$\Omega_T = \Omega \times (0, T],$$



• If $\Omega = \mathbb{R}^d$, $T > 0$, let

$$S_T = \mathbb{R} \times (0, T]$$



The classical problems are the following:

Let $\mathcal{H}(\Omega_T) = \{u: \Omega_T \rightarrow \mathbb{R}; u_t, \partial^2 u / \partial x_i \partial x_j \in C(\Omega_T) \forall i, j\}$
and sim. for S_T

a) Dir.-problem: find $u \in C(\overline{\Omega_T}) \cap \mathcal{H}(\Omega_T)$ s.t.

$$\begin{cases} u_t - \Delta u = 0 & \text{in } \Omega_T \\ u|_{\partial\Omega \times [0, T]} = g \in C(\partial\Omega \times [0, T]) \\ u|_{t=0} = u_0 \in C(\overline{\Omega}) \end{cases}$$

b) Neumann-problem:

Like Dirichlet-problem, but 2nd cond is replaced by $u \in C^1(\overline{\Omega_T}) \cap \mathcal{H}(\Omega_T)$,

$$\partial_n u|_{\partial\Omega \times [0, T]} = h \in C(\partial\Omega \times [0, T])$$

c) Cauchy-problems (Initial Value problem / Characteristic Cauchy problem)

Find $u \in \mathcal{H}(S_T) \cap C(\overline{S_T})$ s.t.

$$\begin{cases} \partial_t u - \Delta u = 0 & \text{in } S_T \\ u|_{t=0} = f & \text{on } \mathbb{R}^d \end{cases}$$

We will mostly consider a) & c).

3.2- The fundamental Solution

Note that if $u(x, t)$ is a solution, so is $u(hx, h^2 t)$ for all h . Hence, let

$$\xi = |x|^2/t \quad \leftarrow \text{invariant under scalings } (x, t) \mapsto (hx, h^2 t),$$

so let's separate variables in ξ and t :

$$u(x, t) = h(t) f(\xi).$$

Then

$$\partial_t u(x, t) = h'(t) f(\xi) + h(t) f'(\xi) \left(-\frac{|x|^2}{t^2} \right)$$

$$\partial_{x_i} u(x, t) = h(t) f'(\xi) \frac{\partial(|x|^2/t)}{\partial x_i} = 2x_i h(t) f'(\xi) / t$$

$$\partial_{x_i x_i} u(x, t) = 2h' f' / t + 4x_i^2 h(t) f''(\xi) / t^2$$

$$\Delta u(x, t) = 2dh' f' / t + 4|x|^2 h f'' / t^2$$

and hence

$$\begin{aligned} \partial_t u = \Delta u &\Leftrightarrow t h'(t) f(\xi) - h(t) \xi f'(\xi) \\ &= 2dh' f' + 4\xi h f'' \end{aligned}$$

$$\begin{aligned} \Leftrightarrow t h'(t) f(\xi) - 2dh' f' &= 4\xi h(t) f''(\xi) + h(t) \xi f'(\xi) \\ &= h(t) \xi (4f''(\xi) + f'(\xi)) \end{aligned}$$

Choose now f s.t.

$$4f'' + f' = 0 \quad \text{i.e.} \quad f'(\xi) = \hat{C} e^{-\xi/4} \Rightarrow f(\xi) = C e^{-\xi/4}.$$

Plug this into left hand side:

$$t h'(t) e^{-\xi/4} + 2dh e^{-\xi/4} = 0$$

$$\Leftrightarrow t h' + \frac{dh}{2} = 0 \Leftrightarrow \int \frac{dh}{h} = -\int \frac{dt}{2t} = -\ln t \quad \text{initial}$$

$$\text{i.e.} \quad \begin{cases} f(\xi) = C_1 e^{-\xi/4} \\ h(t) = C_2 t^{-1/2} \end{cases}$$

and we have shown that

$$C t^{-1/2} e^{-|x|^2/4t}$$

is a solution $\forall t > 0$.

Def. $\Gamma(x, t) = \frac{1}{(4\pi t)^{d/2}} e^{-|x|^2/4t}$ is the fundamental solution of the heat eqn. i.e. the heat kernel

Note: See Ex. 6

$$\frac{1}{(4\pi(t-s))^{d/2}} \int e^{-|x-y|^2/4(t-s)} dy = 1 \quad \forall 0 \leq s < t \quad \forall x \in \mathbb{R}^{2d}$$

Existence of a

3.3. Solution for an initial value problem: $\Omega = \mathbb{R}^d$

Thm. Assume $f \in L^\infty(\mathbb{R}^d) \cap C(\mathbb{R}^d)$. Let $\forall x \in \mathbb{R}^d, t > 0$,

$$(i) \quad u(x, t) = \frac{1}{(4\pi t)^{d/2}} \int_{\mathbb{R}^d} e^{-|x-y|^2/4t} f(y) dy.$$

Then $u \in C^\infty(\mathbb{R}^d \times \mathbb{R}_+)$, $\Delta u(x, t) = \partial_t u(x, t) \forall t > 0$
and uniformly on compact subsets of \mathbb{R}^d ,

$$\lim_{t \rightarrow +0} u(x, t) = f(x).$$

Hence (ii) is a solution of the initial value problem

$$\begin{cases} \partial_t u - \Delta u = 0 & \text{in } t > 0 \\ u|_{t=0} = f \end{cases}$$

Pf. Since all derivatives of $e^{-|x-y|^2/4t} \frac{d/2}{t}$ are of the form $P(\frac{1}{t}, x) e^{-|x-y|^2/4t}$, P a polynomial,

and these are ^{abs.} integrable $\forall t > 0$, we can take all derivatives inside integral; hence $u \in C^\infty\{t > 0\}$.
Also $\forall t > 0$

$$\partial_t u - \Delta u = \int_{\mathbb{R}^d} \underbrace{(\partial_t - \Delta_x) \left\{ \frac{1}{(4\pi t)^{d/2}} e^{-|x-y|^2/4t} \right\}}_{=0} f(y) dy = 0$$

so u solves the heat eqn. Hence it only remains to check the initial value: recall that $\forall t > 0$

$$\frac{1}{(4\pi t)^{d/2}} \int_{\mathbb{R}^d} e^{-|x-y|^2/4t} dy = 1,$$

hence

$$u(x, t) - f(x) = \frac{1}{(4\pi t)^{d/2}} \int_{\mathbb{R}^d} e^{-|x-y|^2/4t} \{f(y) - f(x)\} dy.$$

Let $\varepsilon > 0$ and choose $\delta > 0$ s.t.

$$|x-y| < \delta \Rightarrow |f(y) - f(x)| < \varepsilon.$$

Now

$$\frac{1}{(4\pi t)^{d/2}} \int_{|x-y| < \delta} e^{-|x-y|^2/4t} |f(y) - f(x)| dy$$

$$< \varepsilon \frac{1}{(4\pi t)^{d/2}} \int_{|x-y| < \delta} e^{-|x-y|^2/4t} dy < \varepsilon \frac{1}{(4\pi t)^{d/2}} \int_{\mathbb{R}^d} e^{-|x-y|^2/4t} dy = \varepsilon$$

and

$$\lim_{t \rightarrow +0} \frac{1}{(4\pi t)^{d/2}} \int_{|x-y| > \delta} e^{-|x-y|^2/4t} |f(y) - f(x)| dy \rightarrow 0$$

since $\lim_{t \rightarrow +0} t^{-n} e^{-a/4t} = 0 \forall a > \delta > 0$ + (by Monotone Convergence!)

$\forall \varepsilon > 0$ arb. \Rightarrow claim - \square

Uniqueness is much more subtle ∇

3.4. Existence of a solution for an initial value problem: Ω bnd.

Let now $\Omega \subset \mathbb{R}^d$, and consider the problems

$$\begin{cases} \partial_t^2 u - \Delta_x u = 0 & \text{in } \Omega \times \mathbb{R}_+ \\ u(x, t) = 0, \quad t > 0, x \in \partial\Omega \\ u(x, 0) = f(x), \end{cases}$$

\downarrow 2 deriv. in x
 \downarrow 1 u - in t

where $\overset{\text{a priori}}{f} \in C(\bar{\Omega})$ and $u \in C^{2,1}(\Omega \times \mathbb{R}_+)$

Let's separate variables:

$$u(x, t) = X(x) T(t).$$

Then

$$X(x) T'(t) = \partial_t^2 u = \Delta_x u = \Delta X(x) T(t)$$

and assuming $T, X \neq 0$ we have

$$\frac{T''(t)}{T(t)} = \frac{\Delta X(x)}{X(x)} = \text{const} = \lambda$$

Hence

$$\begin{cases} T' = \lambda T, \quad t > 0 \\ \Delta X = \lambda X, \quad \text{in } \Omega, \quad X|_{\partial\Omega} = 0. \end{cases}$$

The 1st one is easy:

$$T(t) = C e^{-\lambda t}, \quad t > 0.$$

The 2nd is highly nontrivial for general Ω ; even the existence of $X \neq 0$ sat. $\Delta X = \lambda X$ in Ω is not clear. Such X are called eigenvalues of Δ in Ω . Let's start by (Dirichlet)

taking $d=1$ and $\Omega = [0, \pi]$.

$$(EV) \quad \frac{d^2 X}{dx^2} = \lambda X, \quad X(0) = X(\pi) = 0$$

Now for $\lambda > 0$ (EV) has only trivial sol $X=0$:

$$\begin{cases} \frac{d^2 X}{dx^2} = \lambda X \Leftrightarrow X = C_1 e^{\sqrt{\lambda}x} + C_2 e^{-\sqrt{\lambda}x} \\ X(\pi) = C_1 e^{\sqrt{\lambda}\pi} + C_2 e^{-\sqrt{\lambda}\pi} = 0 = X(0) = C_1 + C_2 \Leftrightarrow C_1 = C_2 = 0 \end{cases} \quad \left| \begin{array}{cc} e^{\sqrt{\lambda}\pi} & e^{-\sqrt{\lambda}\pi} \\ 1 & 1 \end{array} \right| = \frac{\sqrt{\lambda}\pi - 1}{e - 1}$$

Also for $\lambda = 0$:

$$\begin{cases} X'' = 0 \Leftrightarrow X(x) = ax + b \\ X(\pi) = a\pi + b = 0 = X(0) = b \Leftrightarrow a = b = 0. \end{cases}$$

Hence our only hope is $\lambda < 0$:

$$\text{Then } X'' + \lambda X = 0 \Leftrightarrow X(x) = C_1 e^{i\sqrt{|\lambda|x}} + C_2 e^{-i\sqrt{|\lambda|x}}$$

$$\begin{cases} X(\pi) = C_1 e^{i\sqrt{|\lambda|}\pi} + C_2 e^{-i\sqrt{|\lambda|}\pi} = 0 \\ X(0) = C_1 + C_2 = 0 \end{cases}$$

$$X(0) = C_1 + C_2 = 0$$

$$\begin{vmatrix} e^{i\sqrt{|\lambda|}\pi} & e^{-i\sqrt{|\lambda|}\pi} \\ 1 & 1 \end{vmatrix} = e^{i\sqrt{|\lambda|}\pi} - e^{-i\sqrt{|\lambda|}\pi} = 2i \sin(\pi\sqrt{|\lambda|})$$

$$\neq 0 \quad \sqrt{|\lambda|}\pi \neq m\pi \Leftrightarrow |\lambda| \neq m^2.$$

non-trivial sol^s

i.e. we can have only if $\lambda = \lambda_n = -m^2$.

$$\text{Then } C_1 e^{i\sqrt{|\lambda_n|}\pi} + C_2 e^{-i\sqrt{|\lambda_n|}\pi} = C_1 e^{im\pi} - C_2 e^{-im\pi} = 0 \Leftrightarrow C_1 = C_2.$$

Hence the eigensolutions are

$$\begin{cases} X_n(x) = C(e^{imx} - e^{-imx}) = C' \sin mx, \quad m > 0 \\ T_n(t) = C e^{-m^2 t} \end{cases}$$

and we can look for the general sol. in as a series

$$u(x, t) = \sum_{n>0} a_n e^{-m^2 t} \sin(mx) \text{ for some } a_n \in \mathbb{R}.$$

When does this work?

Cond. 1. The series has to converge so fast (i.e. a_n

have to go to 0 as $m \rightarrow \infty$) that one can differentiate this twice in x & once in t .

Cond. 2. Formally:

$$u(x, 0) = \sum_{n>0} a_n \sin(mx) = f(x).$$

Hence we have to be able to decompose f into a series in terms of $\sin(mx)$ i.e. Fourier sine-series!

Let's worry about Cond. 2 1st. This leads into

3.5. Fourier-series: Crash course.

Let $f \in L^1([-\pi, \pi])$ and ask a general question: when can one write

$$(F) \quad f(x) = \sum_{n=-\infty}^{\infty} a_n e^{inx}$$

for some $a_n \in \mathbb{C}$ & c.b. $\sum_{n=-\infty}^{\infty} a_n e^{inx}$ converges in some sense & "=" holds, at least a.e.?

Now formally

$$\int_{-\pi}^{\pi} f(x) e^{-ikx} dx = \sum_{n=-\infty}^{\infty} a_n \int_{-\pi}^{\pi} e^{i(n-k)x} dx.$$