University of Helsinki / Department of Mathematics and Statistics SCIENTIFIC COMPUTING Exercise 08, 9.11.2015

N.B. The files mentioned in the exercises (if any) are available on the course homepage.

1. (a) Show that for a square matrix a, if λ is an eigenvalue of a (i.e. for some $x \neq 0$, $ax = \lambda x$), then $\lambda + c$ is an eigenvalue of a + c * I where I is the identity matrix of the same size as a.

(b) Let a_1 be a random $n \times n$ matrix, $a = a_1 + a_1^T$, and define t to be the least eigenvalue of a if it is < 0 and = 0 otherwise. Show that a - tI has nonnegative eigenvalues and that it is symmetric.

(c) Generate with (b) symmetric square matrices a with nonnegative eigenvalues and show that if [u, s, v] = svd(a) and ss = sqrt(s), w = u * ss, then $a = w * w^{T}$.

2. The vertices of a quadrilateral are (0,0), (p_1,p_2) , (1,0), (q_1,q_2) , where $p_2 < 0, q_2 > 0$. Generate such quadrilaterals and compute their areas. Show that Bretschneider's formula for the area holds:

$$K = \sqrt{(s-a)(s-b)(s-c)(s-d) - abcd\cos^2\alpha}$$

where α is the mean value of the angles at p and q and a, b, c, d are the sides, 2s = a + b + c + d. Hint: Use polyarea to check the formula.

3. Let B and C be $m \times n$ matrices with real entries and let A = B + iC. Relate the singular values of A to those of

$$\left[\begin{array}{cc} B & -C \\ C & B \end{array}\right]$$

Observe this gives an idea to reduce the computation of the SVD of complex $m \times n$ matrices to the case of real $2m \times 2n$ matrices.

4. Recall from linear algebra that if $\Delta \equiv ad - bc \neq 0$, then

Δ	a	b]	-1	d	-b	
	С	d	_	_ <i>c</i>	a	

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Consider the Newton method $x_{n+1} = x_n - J_f(x_n)^{-1} f(x_n)$ to solve the system

$$\left\{ egin{array}{cc} x_1^2+x_2^2-1&=0\ x_1^2-x_2^2&=0 \end{array}
ight.$$

with the initial point (0.5, 0.5). Use standard methods from linear algebra and multidimensional calculus, such as the above formula for matrix inverse, to compute the following expressions analytically and to print the numerical values $J_f(x_n)$, $J_f(x_n)^{-1}$, $T(x_n) \equiv J_f(x_n)^{-1}f(x_n)$ for the first three iteration steps.

5. For $t \in R \setminus \{0\}$, the pseudo-inverse is defined by $t^+ = 1/t$ and we set $0^+ = 0$. If s is a $m \times n$ diagonal matrix let s^+ be the $n \times m$ diagonal matrix obtained by applying this operation elementwise: $(s^+)_{i,j} = s^+_{i,j}$. For an $m \times n$ matrix a with a SVD $a = usv^T$ we define $a^+ = vs^+u^T$. Check for a number of random matrices whether and how well a^+ agrees with the MATLAB pseudo-inverse pinv(a).

6. Finding the root of a linear $n \times n$ system ax = b can be considered as a minimization problem for the function g(x) = |a * x - b| = norm(a * x - b). Use this idea to solve the problem a * x = b when a is $n \times n$ Hilbert matrix. Report for each n = 2: 9 the residual |ax - b| and |xnum - exact| when exact= ones(n.1) and b=a*exact.