

Non-linear Diffusion Problems, Solutions 2.

5.2.6 $\partial_t u(t, x, y) = d \Delta u(t, x, y) + r u(t, x, y),$

where $x \in [0, L_x]$ and $y \in [0, L_y]$. We pose boundary cond.

$$\partial_x u(t, 0, y) = 0 = \partial_x u(t, L_x, y); \quad \partial_y u(t, x, 0) = 0 = \partial_y u(t, x, L_y).$$

Let's try separation of variables: Plug the "ansatz"

$$u(t, x, y) := a(t) b(x) c(y)$$

into the diffusion eq. to get

$$a'(t) b(x) c(y) = d(a(t) b''(x) c(y) + a(t) b(x) c''(y)) + r a(t) b(x) c(y)$$

Divide by $a \cdot b \cdot c$ to obtain

$$\frac{a'(t)}{a(t)} = d \left(\frac{b''(x)}{b(x)} + \frac{c''(y)}{c(y)} \right) + r, \quad (\forall t, x, y). \quad (†)$$

This can only be true if there are constants λ, C_x, C_y such that

$$\frac{a'(t)}{a(t)} = \lambda, \quad \frac{b''(x)}{b(x)} = -C_x, \quad \frac{c''(y)}{c(y)} = -C_y,$$

and by (†) these also have to satisfy $\lambda = -d(C_x + C_y) + r.$

There will be further restrictions from the boundary cond.!



... Consider, for example,

$$b'(x) = -C_x b(x).$$

The solution is, generally, a combination

$$b(x) = A \cos(\sqrt{C_x} x) + B \sin(\sqrt{C_x} x).$$

However, " $\int_{x=0}^L b(0, y) = 0$ " implies B must be zero.

Also, " $\int_{x=L}^L b(L, y) = 0$ " implies

$$-\sin(\sqrt{C_x} L) = 0 \Leftrightarrow \sqrt{C_x} L = k_x \pi, \quad k_x = 0, 1, 2, \dots$$

$$\Leftrightarrow \underline{C_x = \left(\frac{k_x \pi}{L_x} \right)^2}$$

\Rightarrow The possible solutions can be numbered

$$b_{k_x}(x) = \cos\left(\frac{k_x \pi}{L_x} x\right), \quad k_x = 0, 1, 2, \dots$$

Same thing for $c(y)$, only different L_y :

$$c_{k_y}(y) = \cos\left(\frac{k_y \pi}{L_y} y\right), \quad k_y = 0, 1, 2, \dots$$

Once k_x, k_y are chosen, $\lambda(k_x, k_y)$ is determined:

$$\underline{\lambda(k_x, k_y) = r - d \left\{ \left(\frac{k_x \pi}{L_x} \right)^2 + \left(\frac{k_y \pi}{L_y} \right)^2 \right\}} \quad (*)$$

... Put it all together and get, for each pair (k_x, k_y) ,

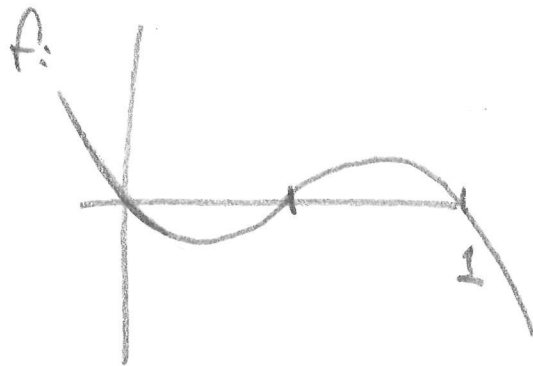
$$u_{k_x, k_y}(x, y) = e^{\lambda(k_x, k_y)t} \cdot \cos\left(\frac{k_x \pi}{L_x} x\right) \cos\left(\frac{k_y \pi}{L_y} y\right)$$

It is curious that the growth rate λ is determined by the ratios $\frac{k_x \pi}{L_x}$ and $\frac{k_y \pi}{L_y}$. In particular, it can not get "just any values".

The degeneracy of a particular λ is the number of pairs $(k_x, k_y) \in \mathbb{N}^2$ that solve $(*)$.

Thus, it can be seen that the density and degeneracy of possible λ 's increases as L_x or L_y does.

② $f(u) := \alpha(u - \frac{1}{2})(T - u)$



$$\begin{cases} u'(t) = v(t) \\ v'(t) = -f(u(t)) \end{cases}$$

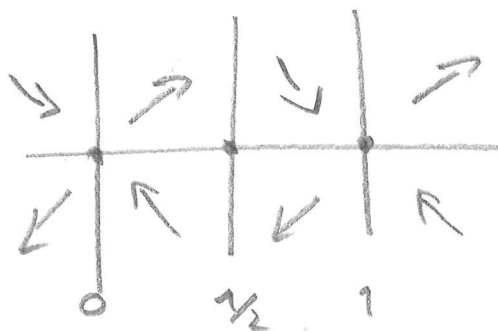
We have Hamiltonian from

$$u' = \frac{\partial H}{\partial v}(u, v) \Rightarrow H = \frac{1}{2}v^2 + \alpha(u)$$

$$v' = -\frac{\partial H}{\partial u}(u, v) \Rightarrow H = -\int_0^u f(w)dw + (3v)$$

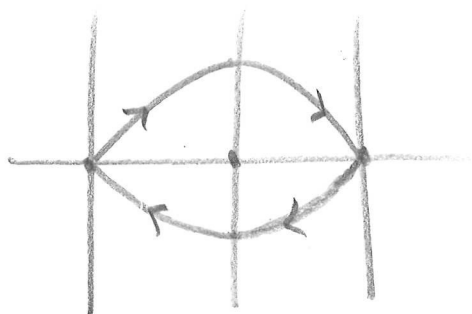
$\therefore H(u, v) = \frac{1}{2}v^2 + F(u)$, $F(u) = -\int_0^u f$, is a constant of motion.

i) Phase portrait: $u' = v$ & $v' = -f(u)$ tell us that the general flow pattern looks like

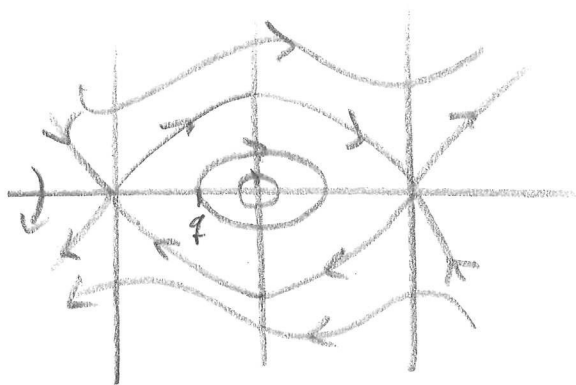


To be able to "connect the orbits" we must find the level sets of H .

Eg. Since $H(0, 0) = 0 = H(1, 0)$, and $H(u, 0) < 0$, for $0 < u < 1$, and considering the flow pattern we know that point $(0, 0)$ connects to $(1, 0)$ as follows:



Similarly, rest of the orbits don't have a choice but to look like:



i) To get solutions to the No-flux (BVP) (r) , we change $t \rightarrow \tau t$, and look for orbits that start from the w -axis (so that $\phi'(0) = v_0 = 0$) and end up, after time 1, to the w -axis (so that $\phi'(1) = v(1) = 0$). ϕ corresponds to u .

So we need the orbit time. It's obtained from this:

$E(q, 0) = E(u, v)$ for all u, v on the orbit starting from $(q, 0)$

$$\Leftrightarrow E_r(q) = \frac{1}{2} v^2 + E_r(u) \Leftrightarrow v = \frac{du}{dx} = \sqrt{2(E_r(q) - E_r(u))}$$

$$\Rightarrow x_r(u) = \int_q^u \frac{du}{\sqrt{2(E_r(q) - E_r(u))}}$$

Let $T_r(q)$ denote the time the orbit hits the w -axis:

$$T_r(q) = \int_q^{q^+} \frac{du}{\sqrt{2(E_r(q) - E_r(u))}}, \quad q \in [0, \frac{1}{2}]$$

Idea: To find the right orbits, for a fixed r , we must look for q such that either, $T_r(q) = 1$, or, $n T_r(q) = 1$ for some $n = 2, 3, \dots$. The latter correspond to orbits that travel ...

... more than half a round. The ^{sufficient} condition to have ANY suitable orbits of n half turns is

$$\inf_{\Gamma} T_{\Gamma}(q) < 1$$

Now, if T_{Γ} is monotone, then we find $\inf T_{\Gamma}$ as the limit

$$\lim_{q \rightarrow \frac{1}{2}} T_{\Gamma}(q) = \frac{\pi}{|f'(\frac{1}{2})|} = \frac{2\pi}{|r|}$$

as shown in lectures.

I'm going to "prove" by hand waving that T_{Γ} is monotone. Consider this:

$T_{\Gamma}(q_2) < T_{\Gamma}(q_1)$ for $q_2 < q_1$ would mean that the path travels a longer route, starting from q_2 , in less time.

By $u' = v$, the only way such a thing may happen is to "go high enough fast enough" (the flow to the right is stronger high up) So how fast must one go up ???

Well, consider $f(x) = -Cx$ linear. Then the solutions are all oscillating with same frequency, irrespective of q . Thus the linear case \dagger seems to be the limiting situation. So, what does weaker than linear mean here? It means concave on $(0, \frac{1}{2})$ and convex on $(\frac{1}{2}, 1)$. It requires a bit of meditation but it's clear that this will suffice. And, our \dagger fulfills it. \Rightarrow Monotone. "QED"

So, to put it together, if

$$\frac{h 2\pi}{\Gamma k} < 1 \Leftrightarrow r > \sqrt{2\pi h}$$

then there will be at least $2 \cdot n$ suitable orbits (2 comes from the choice of starting below or above $n = \frac{1}{2}$).

iii) As seen from the phase portrait, orbits starting from v axis will never return. So no solutions excepting the trivial $n=0$.

iv) They are the periodic orbits plus the connecting orbits between $(0,0)$ and $(1,0)$.

③ i) Assume ϕ is a solution to (BVP)(r):

$$\begin{cases} \phi'' + r\phi = 0 & (0 < x < 1) \\ \phi'(0) = 0 = \phi'(1) \end{cases},$$

and define

$$\tilde{\phi}(x) := \phi(1-x).$$

$$\text{Then } \partial_x^2 \tilde{\phi}(x) = \partial_x^2 \phi(1-x) = (-1)^2 \phi_{xx}(1-x) = \tilde{\phi}_{xx}(x)$$

and thus $\tilde{\phi}$, clearly, is also a solution to (BVP)(r).

ii) It should be clear enough both extended functions, ϕ and $\tilde{\phi}$, satisfy $\phi'' + r\phi$ on $\mathbb{R} \setminus \mathbb{Z}$. The thing to note is that the no-flux boundary cond. ensures the extensions will be differentiable once. Actually, it's even twice diff! For example around 0: $\forall \epsilon > 0$

$$\partial_x^2 \phi(-\epsilon) = \phi''(-\epsilon) = -r \phi(\phi(-\epsilon)) = -r \phi(\phi(\epsilon)) = \phi''(\epsilon)$$

$\phi(\epsilon) \otimes$

$\rightarrow \phi''$ is cont. at 0.

(*) It follows from our strategy of extension that always $\phi(-x) = \phi(x)$.

Next, ϕ is symmetric iff, by def., $\tilde{\phi}(x) = \phi(x) \forall x$.

That's the same as $\phi(1-x) = \phi(x)$. But, by 2-periodicity of our extension, $\phi(1-x) = \phi(-(1+x)) = \phi(1+x)$, which says ϕ is 1-periodic.

iii) $\phi_k(x) := f(kx)$ where $k \in \mathbb{N}$.

Now $\partial_x^2 \phi_k(x) = \partial_x^2 [f(kx)] = k^2 f''(kx)$. Thus

$$\partial_x^2 \phi_k(x) + k^2 r f(\phi_k(x)) = k^2 \underbrace{\{f''(kx) + r f(f(kx))\}}_{=0} = 0.$$

$\therefore \phi_k$ satisfies (BVP) (k r).

Let $k=2n$.

$$\Rightarrow \phi_{1k}(x+1) = f(2nx+2n) = f(2nx) = \phi_k(x). \text{ Done.}$$

iv) $\phi_{1/2}(x) := f(\frac{1}{2}x)$. As before, it's easily seen that

$$\partial_x^2 \phi_{1/2} + \frac{r}{4} f(\phi_{1/2}) = 0 \quad \sim \mathbb{R}.$$

For $\phi_{1/2}$ to satisfy the BC f must be symmetric, well actually we only need $\phi'(\frac{1}{2}) = 2\phi'_{1/2}(1) = 0$, which certainly follows if $\phi'(x) = \phi'(1-x)$ for $x \in [0,1]$.

For each cont. func. f there is a smallest period, unless it's constant. The most elementary way to see this is to assume, on the contrary, that for each δ , there is $\sigma < \delta$ such that $f(x+\sigma) = f(x)$. Now the cont. periodic func. like f will attain both its max., say at x_1 , and its min., at x_2 . And the case: By σ periodicity, these max. and min. are also attained on $x_1+n\sigma$, $x_2+m\sigma$, $n, m \in \mathbb{Z}$! Clearly, f cannot be cont. unless it's constant. (Exercise 11).

v) Because ... our extension trick only depended on the $x \in [0, 1]$ or \mathbb{R} . Thus we can still do the same $\tilde{f}(x) = f(1-x) + f(x+2) := f(x)$ ect.

vi) So, assume $f(\bar{x}) = 0$, $\bar{x} \in [0, 1]$. Then

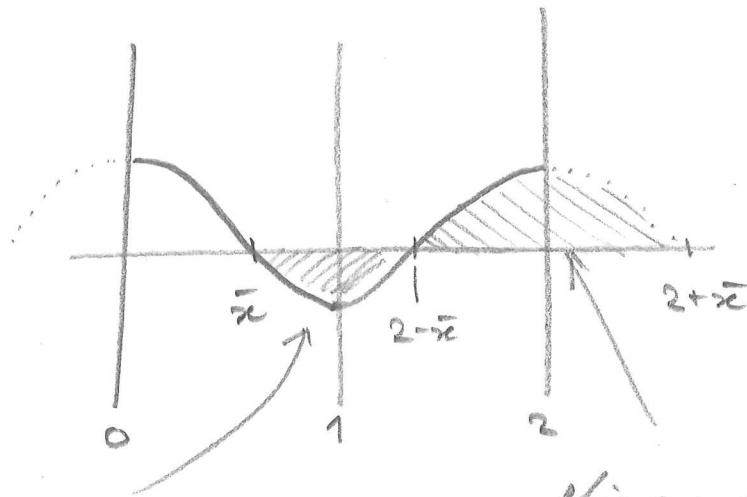
$$f(2-\bar{x}) = f(-\bar{x}) = f(\bar{x}) = 0 \text{ too.}$$

Now define $\varphi_1(x) := f(x+\bar{x})$, $\varphi_2(x) := f(x+2-\bar{x})$.

$$\text{Then } \varphi_1(0) = 0 = \varphi_1(2-2\bar{x})$$

$$\text{and } \varphi_2(0) = 0 = \varphi_2(2\bar{x})$$

Picture:



this corresponds to φ_1 .

this one corresponds to φ_2 .

$\Rightarrow \varphi_1$ is solution to (BVP) $(L = 2-2\bar{x})$ while
Bdy. cond.

φ_2 is solution to (BVP) $(L = 2\bar{x})$.
Bdy. cond.

These L can be adjusted to 1 at the cost of changing ν .