## Lecture 03: Non-autonomous linear systems

## 1 Non homogeneous linear systems

Let $A \in \operatorname{End}\left(\mathbb{R}^{n}\right)$, consider the initial data problem

$$
\begin{align*}
\dot{\phi}_{t} & =\mathrm{A} \phi_{t}+\boldsymbol{f}_{t} \\
\phi_{0} & =\boldsymbol{x}_{o} \tag{1.1}
\end{align*}
$$

Proposition 1.1. The unique solution of (1.1) is

$$
\begin{equation*}
\phi_{t}=e^{\mathrm{A} t} \boldsymbol{x}_{o}+\int_{0}^{t} d s e^{\mathbf{A}(t-s)} \boldsymbol{f}_{s} \tag{1.2}
\end{equation*}
$$

Proof. The solution is obtained using the method of variation of constants:

$$
\begin{equation*}
\boldsymbol{\phi}_{t}=e^{\mathrm{A} t} \boldsymbol{\psi}_{t} \tag{1.3}
\end{equation*}
$$

then

$$
\begin{equation*}
e^{\mathrm{A} t} \dot{\boldsymbol{\psi}}_{t}=\boldsymbol{f}_{t} \quad \Rightarrow \quad \dot{\boldsymbol{\psi}}_{t}=e^{-\mathrm{A} t} \boldsymbol{f}_{t} \tag{1.4}
\end{equation*}
$$

thus

$$
\begin{equation*}
\phi_{t}=e^{\mathrm{A} t}\left(\boldsymbol{x}_{o}+\int_{0}^{t} d s e^{-\mathrm{A} s} \boldsymbol{f}_{s}\right) \tag{1.5}
\end{equation*}
$$

Remark 1.1. The initial conditions are stored in the homogeneous part of the solution!!!

## 2 Linear non-autonomous dynamics

We consider the linear ordinary differential equation

$$
\begin{gather*}
\dot{\phi}_{t}=\mathrm{A}_{t} \cdot \phi_{t}  \tag{2.1a}\\
\phi_{t_{\mathrm{o}}}=\boldsymbol{x} \tag{2.1b}
\end{gather*}
$$

We suppose the vector field $\boldsymbol{f}(t, \boldsymbol{x})=\mathrm{A}_{t} \cdot \boldsymbol{x}$ driving (2.1a) to be smooth also in its time dependence

$$
\begin{equation*}
\boldsymbol{f} \in \mathrm{C}^{r}\left(\mathbb{R} \times \mathbb{R}^{n} ; \mathbb{R}^{n}\right) \tag{2.2}
\end{equation*}
$$

Hence we can express the solution of (2.1) in terms of the linear flow describing the fundamental solution of (2.1a)

$$
\begin{equation*}
\phi_{t}=\mathrm{F}_{t, t_{o}} \cdot \boldsymbol{x} \tag{2.3}
\end{equation*}
$$

Using "Picard"-iterations of (2.1a), the flow F is obtained as a time ordered exponential

$$
\begin{equation*}
\mathrm{F}_{t, t_{\mathrm{o}}}=1+\sum_{n>0} \int_{t_{\mathrm{o}}}^{t} d t_{n} \int_{t_{\mathrm{o}}}^{t_{n}} d t_{n-1} \ldots \int_{t_{\mathrm{o}}}^{t_{3}} d t_{2} \int_{t_{\mathrm{o}}}^{t_{2}} d t_{1} \mathrm{~A}_{t_{n}} \mathrm{~A}_{t_{n-1}} \ldots \mathrm{~A}_{t_{2}} \mathrm{~A}_{t_{1}}:=\mathcal{T}\left\{e^{\int_{t_{0}}^{t} d s \mathrm{~A}_{s}}\right\} \tag{2.4}
\end{equation*}
$$

If

$$
\begin{equation*}
\left[\mathrm{A}_{t}, \mathrm{~A}_{s}\right]=0 \quad \forall t, s \quad \Rightarrow \quad \mathrm{~F}_{t, t_{\mathrm{o}}}=e^{\int_{t_{\mathrm{o}}}^{t} d s \mathrm{~A}_{s}} \tag{2.5}
\end{equation*}
$$

in particular, the time-order exponential reduces to the ordinary one if the matrix $A$ is autonomous.

## Remark 2.1.

$$
\begin{equation*}
\mathrm{F}_{t, 0}=\mathrm{F}_{t, t_{\mathrm{o}}} \mathrm{~F}_{t_{\mathrm{o}}, 0} \quad \Rightarrow \quad \mathrm{~F}_{t, t_{\mathrm{o}}}=\mathrm{F}_{t, 0} \mathrm{~F}_{t_{\mathrm{o}}, 0}^{-1} \tag{2.6}
\end{equation*}
$$

thus also in the non-autonomous case it is enough to know $F_{t, 0}$ in order to reconstruct the flow for other initial times.
Proposition 2.1. The solution of (2.1) is unique
Proof. Suppose there exist two solutions $\phi_{t ; 1}$ and $\phi_{t ; 2}$

$$
\begin{equation*}
\phi_{t ; 1}=\phi_{t_{o} ; 1}+\int_{t_{o}}^{t} d s \mathrm{~A}_{s} \cdot \phi_{s ; 1} \quad i=1,2 \tag{2.7}
\end{equation*}
$$

Then

$$
\begin{equation*}
\left\|\phi_{t ; 1}-\phi_{t ; 2}\right\| \leq \int_{t_{o}}^{t} d s\left\|\mathrm{~A}_{s}\right\|\left\|\phi_{s ; 1}-\phi_{s ; 2}\right\| \leq a \int_{0}^{t} d s\left\|\phi_{s ; 1}-\phi_{s ; 2}\right\| \tag{2.8}
\end{equation*}
$$

where

$$
\begin{equation*}
a=\sup _{s, i, j}\left|A_{i j}(s)\right| \tag{2.9a}
\end{equation*}
$$

whence the claim.

### 2.1 Periodic case

Consider

$$
\begin{gather*}
\dot{\mathrm{F}}_{t, t_{\mathrm{o}}}=\mathrm{A}_{t} \mathrm{~F}_{t, t_{\mathrm{o}}}, \quad \mathrm{~A}_{t+T}=\mathrm{A}_{t}  \tag{2.10a}\\
\lim _{t \downarrow t_{\mathrm{o}}} \mathrm{~F}_{t, t_{\mathrm{o}}}=1 \tag{2.10b}
\end{gather*}
$$

Theorem 2.1 (Floquet). Let $\mathrm{A}_{t}=\mathrm{A}_{t+T}$ for all t. Then the principal solution of (2.1a) can be written as

$$
\begin{equation*}
\mathrm{F}_{t, t_{\mathrm{o}}}=\mathrm{P}_{t, t_{\mathrm{o}}} \mathrm{e}^{\mathrm{B}\left(t-t_{\mathrm{o}}\right)} \tag{2.11}
\end{equation*}
$$

where

$$
\begin{align*}
& \mathrm{P}_{t+T t_{\mathrm{o}}}=\mathrm{P}_{t t_{\mathrm{o}}} \quad \forall t \\
& \mathrm{P}_{t_{\mathrm{o}} t_{\mathrm{o}}}=1 \tag{2.12}
\end{align*}
$$

and B is a constant matrix.

Proof. The proof proceed in three steps

1. We first prove that

$$
\begin{equation*}
\mathrm{F}_{t+T, t_{\mathrm{o}}}=\mathrm{F}_{t, t_{\mathrm{o}}} \mathrm{~F}_{t_{\mathrm{o}}+T, t_{\mathrm{o}}} \tag{2.13}
\end{equation*}
$$

To this goal let us define the auxiliary matrix

$$
\begin{equation*}
\mathrm{G}_{t, t_{\mathrm{o}}}:=\mathrm{F}_{t+T, t_{\mathrm{o}}}=\mathrm{F}_{t+T, t_{\mathrm{o}}+T} \mathrm{~F}_{t_{\mathrm{o}}+T, t_{\mathrm{o}}} \tag{2.14}
\end{equation*}
$$

We see that it satisfies

$$
\begin{equation*}
\dot{\mathrm{G}}_{t, t_{\mathrm{o}}}=\dot{\mathrm{F}}_{t+T, t_{\mathrm{o}}}=\mathrm{A}_{t+T} \mathrm{~F}_{t+T, t_{\mathrm{o}}}=\mathrm{A}_{t} \mathrm{G}_{t, t_{\mathrm{o}}} \tag{2.15}
\end{equation*}
$$

which is the same as (2.10a), with boundary condition

$$
\begin{equation*}
\mathrm{G}_{t_{\mathrm{o}}, t_{\mathrm{o}}}:=\mathrm{F}_{t_{\mathrm{o}}+T, t_{\mathrm{o}}} \tag{2.16}
\end{equation*}
$$

Liouville theorem guarantees that

$$
\begin{equation*}
\operatorname{det} \mathrm{F}_{t, t_{\mathrm{o}}} \neq 0 \quad \forall t \tag{2.17}
\end{equation*}
$$

hence $\mathrm{F}_{t, t_{\mathrm{o}}}$ is invertible. We can therefore construct the flow

$$
\begin{equation*}
\tilde{\mathrm{F}}_{t, t_{\mathrm{o}}}=\mathrm{G}_{t, t_{\mathrm{o}}} \mathrm{~F}_{t_{\mathrm{o}}+T, t_{\mathrm{o}}}^{-1} \tag{2.18}
\end{equation*}
$$

which now satisfies both (2.10a), and (2.10a) including the initial condition. Since the hypotheses of the theorems of existence and uniqueness hold true, we must then have

$$
\begin{equation*}
\mathrm{G}_{t, t_{\mathrm{o}}} \mathrm{~F}_{t_{\mathrm{o}}+T, t_{\mathrm{o}}}^{-1} \equiv \mathrm{~F}_{t+T, t_{\mathrm{o}}+T}=\mathrm{F}_{t, t_{\mathrm{o}}} \quad \Rightarrow \quad \mathrm{~F}_{t+T, t_{\mathrm{o}}}=\mathrm{F}_{t, t_{\mathrm{o}}} \mathrm{~F}_{t_{\mathrm{o}}+T, t_{\mathrm{o}}} \tag{2.19}
\end{equation*}
$$

2. We now claim that there exists a matrix $B$ such that

$$
\begin{equation*}
\mathrm{F}_{t_{\mathrm{o}}+T, t_{\mathrm{o}}}=e^{\mathrm{B} T} \tag{2.20}
\end{equation*}
$$

To see this, let $\lambda_{i} \neq 0$ and $m_{i}, i=1, \ldots, m$ be respectively the eigenvalues of $\mathrm{F}_{t_{\mathrm{o}}+T, t_{\mathrm{o}}}$ and their algebraic multiplicities. Let

$$
\begin{equation*}
\mathrm{F}_{t_{\mathrm{o}}+T, t_{\mathrm{o}}}=\sum_{i=1}^{m}\left(\lambda_{i} \mathrm{P}_{i}+\mathrm{N}_{i}\right) \tag{2.21}
\end{equation*}
$$

be the decomposition of $\mathrm{F}_{t_{\mathrm{o}}+T, t_{\mathrm{o}}}$ into its semi-simple and nilpotent parts. Here $\mathrm{P}_{i}$ is the projector on the subspace spanned by the generalized eigenvectors associated to the eigenvalue $\lambda_{i}$ and $\mathrm{N}_{i}$ is the nilpotent component of $F$ acting on that subspace. We recall that

$$
\begin{equation*}
\mathrm{P}_{i} \mathrm{P}_{j}=\mathrm{P}_{j} \mathrm{P}_{i}=\delta_{i j} \mathrm{P}_{i} \tag{2.22}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathrm{N}_{i} \mathrm{~N}_{j}=\mathrm{N}_{j} \mathrm{~N}_{i}=\delta_{i j} \mathrm{~N}_{i}^{2} \tag{2.23}
\end{equation*}
$$

and that $\left[\mathrm{N}_{i}, \mathrm{P}_{j}\right]=0$. It follows that

$$
\begin{equation*}
\mathrm{B}=\frac{1}{T} \sum_{i=1}^{m}\left[\ln \left(\lambda_{i}\right) \mathrm{P}_{i}-\sum_{j=1}^{m_{i}} \frac{\left(-\mathrm{N}_{i}\right)^{j}}{j \lambda_{i}^{j}}\right] \tag{2.24}
\end{equation*}
$$

satisfies

$$
\begin{equation*}
e^{\mathrm{B} T}=\mathrm{F}_{t_{\mathrm{o}}+T, t_{\mathrm{o}}} \tag{2.25}
\end{equation*}
$$

Namely the chain of equality

$$
\begin{equation*}
\ln \left\{\sum_{i=1}^{m}\left(\lambda_{i} \mathrm{P}_{i}+\mathrm{N}_{i}\right)\right\}=\ln \left\{\sum_{i=1}^{m} \lambda_{i} \mathrm{P}_{i}\left(1+\frac{\mathrm{N}_{i}}{\lambda_{i}}\right)\right\}=\sum_{i=1}^{m}\left\{\ln \left(\lambda_{i}\right) \mathrm{P}_{i}+\ln \left(1+\frac{\mathrm{N}_{i}}{\lambda_{i}}\right)\right\} \tag{2.26}
\end{equation*}
$$

holds true owing to the
(2.22) and (2.23). The matrix B so determined is unique modulo a phase associated to the winding number of the imaginary part of the logarithms.
3. The third step consists in verifying that

$$
\begin{equation*}
\mathrm{P}_{t t_{\mathrm{o}}}=\mathrm{F}_{t, t_{\mathrm{o}}} e^{-\mathrm{B}\left(t-t_{\mathrm{o}}\right)} \tag{2.27}
\end{equation*}
$$

defines a periodic matrix. Namely we see that for all $\forall t \in \mathbb{R}$

$$
\begin{equation*}
\mathrm{P}_{t+T, t_{\mathrm{o}}}=\mathrm{F}_{t+T, t_{\mathrm{o}}} e^{-\mathrm{B}\left(t+T-t_{\mathrm{o}}\right)}=\mathrm{F}_{t, t_{\mathrm{o}}} e^{\mathrm{B} T} e^{-B\left(t+T-t_{\mathrm{o}}\right)}=\mathrm{P}_{t, t_{\mathrm{o}}} \tag{2.28}
\end{equation*}
$$

Finally, it is straightforward to check that

$$
\begin{equation*}
\mathrm{P}_{t_{\mathrm{o}}, t_{\mathrm{o}}}=\mathrm{F}_{t_{\mathrm{o}}, t_{\mathrm{o}}}=1 \tag{2.29}
\end{equation*}
$$

which completes the proof.

Floquet's theorem shows that the solution of (2.10) for $t_{\mathrm{o}}=0$ can be written as

$$
\begin{equation*}
\boldsymbol{x}_{t}=\mathrm{P}_{t 0} e^{\mathrm{B} t} \boldsymbol{x} \tag{2.30}
\end{equation*}
$$

Since $P_{t, t_{\mathrm{o}}}$ is periodic, the long-time behavior depends only on $B$. The eigenvalues of $B$ are called the characteristic exponents of the equation.

Definition 2.1 (monodromy). The matrix

$$
\begin{equation*}
\mathrm{M}=e^{\mathrm{B} T} \tag{2.31}
\end{equation*}
$$

## defined by Floquet's theorem is called the monodromy matrix.

The eigenvalues of the monodromy matrix, called the characteristic multipliers, are exponentials of the characteristic exponents times $T$. Computing the characteristic exponents is difficult in general, but the existence of the representation (2.30) is already useful to classify the possible behaviors near a periodic orbit.
Example 2.1. Let us illustrate how formula (2.24) comes about in an elementary example

$$
\mathrm{B}=\ln \left[\begin{array}{ll}
\lambda & 1  \tag{2.32}\\
0 & \lambda
\end{array}\right]=\ln \lambda+\ln \left[\begin{array}{cc}
1 & \frac{1}{\lambda} \\
0 & 1
\end{array}\right]
$$

Since

$$
\begin{equation*}
\ln (1+x)=-\sum_{n=1}^{\infty} \frac{(-x)^{n}}{n} \tag{2.33}
\end{equation*}
$$

then

$$
\ln \left[\begin{array}{cc}
1 & \frac{1}{\lambda}  \tag{2.34}\\
0 & 1
\end{array}\right]:=-\sum_{n=1}^{\infty} \frac{(-1)^{n}}{n}\left[\begin{array}{cc}
0 & \frac{1}{\lambda} \\
0 & 0
\end{array}\right]^{n}=\left[\begin{array}{cc}
0 & \frac{1}{\lambda} \\
0 & 0
\end{array}\right]
$$

owing to nilpotence.

### 2.2 Linear perturbation theory

Consider a family of linear ODE's

$$
\begin{align*}
& \dot{\boldsymbol{x}}_{t ; \mu}=\mathrm{A}_{t: \mu} \boldsymbol{x}_{t ; \mu} \\
& \dot{\boldsymbol{x}}_{0 ; \mu}=\boldsymbol{x}_{o} \tag{2.35}
\end{align*}
$$

where $\mathrm{A} \in \operatorname{End}\left(\mathbb{R}^{n}\right)$ smoothly depends on $\mu$. We want to study the solution in a neighborhood of some $\mu_{0}$. Let

$$
\begin{align*}
& \boldsymbol{x}_{t}^{\prime}:=\left.\partial_{\mu} \boldsymbol{x}_{t ; \mu}\right|_{\mu=\mu_{0}} \\
& \mathrm{~A}_{t}^{\prime}=\left.\partial_{\mu} \mathrm{A}_{t ; \mu}\right|_{\mu=\mu_{0}} \tag{2.36}
\end{align*}
$$

The equation for the variation is

$$
\begin{equation*}
\dot{\boldsymbol{x}}^{\prime}=\mathrm{A}_{t: \mu_{o}} \cdot \boldsymbol{x}_{t}^{\prime}+\mathrm{A}_{t: \mu_{o}}^{\prime} \boldsymbol{x}_{t ; \mu_{0}} \tag{2.37}
\end{equation*}
$$

the solution is

$$
\begin{equation*}
\boldsymbol{x}_{t}^{\prime}=\int_{0}^{t} d s \mathrm{~F}_{t 0: \mu_{o}} \mathrm{~F}_{s 0: \mu_{o}}^{-1} \mathrm{~A}_{s: \mu_{o}}^{\prime} \cdot \boldsymbol{x}_{s ; \mu_{0}} \tag{2.38}
\end{equation*}
$$

since

$$
\begin{equation*}
x_{0}^{\prime}=0 \tag{2.39}
\end{equation*}
$$

