# Linear algebra and matrices II Department of Mathematics and Statistics Autumn 2011 Exercise sheet 5

Exercises due date: Mon 5.12.2011 at 17.00 Corrections due date: Fri 9.12.2011 at 17.00

The core ideas of these excercises are

- Injective and surjective linear mappings
- Isomorphisms
- Determinants
- Finding eigenvalues and eigenvectors

#### Exercise I

It can be proven that  $A \in \mathbb{R}^{n \times n}$  is invertible if and only if  $\det(A) \neq 0$ .

Let

$$A = \begin{bmatrix} -2 & 0 & 0 \\ 4 & 6 & 0 \\ -3 & 7 & 2 \end{bmatrix} \quad B = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{bmatrix}, \quad \text{ja} \quad C = \begin{bmatrix} 5 & 3 & 0 & 6 \\ 4 & 6 & 4 & 12 \\ 0 & 2 & -3 & 4 \\ 0 & 1 & -2 & 2 \end{bmatrix}.$$

- 1. Basing on the determinant, decide whether A is invertible.
- 2. Basing on the determinant, decide whether B is invertible.
- 3. Basing on the determinant, decide whether C is invertible.
- 4. Is matrix  $3CB^T$  invertible?

## Exercise II

Let us consider the linear mapping  $f : \mathbb{R}^2 \to \mathbb{R}^3$ ,  $f(\bar{x}) = \begin{bmatrix} 7x_1 & x_1 + x_2 & 3x_2 - x_1 \end{bmatrix}^T$ . In exercise 2 of exercise sheet 4 it was shown that f is an injection.

- 5. Show that f is not a surjection.
- 6. MWhy doesn't this contradict theorem 4.2.15?

# Exercise III

Let  $A \in \mathbb{R}^{n \times n}$ . It can be proven that  $\lambda$  is an eigenvalue for A if and only if

$$\det(A - \lambda I) = 0.$$

By calculating det $(A - \lambda I)$  we get a polynomial of the *n*th degree where  $\lambda$  is the variable. This polynomial is called the characteristic polynomial of A. The eigenvalues are therefore the zeroes of this polynomial. Let  $A = \begin{bmatrix} 4 & 1 & 1 \end{bmatrix}$ 

$$\begin{bmatrix} 3 & -1 \\ -2 & 2 \end{bmatrix}, B = \begin{bmatrix} 1 & 6 \\ -1 & 2 \end{bmatrix} \text{ ja } C = \begin{bmatrix} 4 & 1 & 1 \\ 0 & 7 & 0 \\ 0 & 0 & 7 \end{bmatrix}$$

7. Find the eigevalues and the corresponding eigenvectors for A.

- 8. Find the eigevalues and the corresponding eigenvectors for B.
- 9. Find the eigevalues and the corresponding eigenvectors for C.

#### Exercise IV

- 10. Let  $A \in \mathbb{R}^{n \times n}$ . Show that A is invertible if and only if the number 0 is not an eigenvalue of A.
- 11. Let A be invertible and  $\lambda$  be and eigenvalue for A. Show that  $\lambda^{-1}$  is an eigenvalue for  $A^{-1}$ .

#### Exercise V

12. Define some isomorphism between the space  $\mathbb{R}^2$  and the plane

$$T = \{ \bar{x} \in \mathbb{R}^3 : x_1 - 2x_2 + 4x_3 = 0 \}$$

(Hint: First find the generators for the plane.)

#### Exercise VI

Let us consider the linear mapping  $L \colon \mathbb{R}^2 \to \mathbb{R}^2$ ,  $L(\bar{x}) = [x_1 + 2x_2 \quad 4x_1 + 3x_2]^T$ and the vectors  $\bar{a}_1 = [1 \ 2]^T$ ,  $\bar{a}_2 = [1 \ -1]^T$  and  $\bar{v} = [3 \ 0]^T$ .

- 13. Show that  $S = \{\bar{a}_1, \bar{a}_2\}$  is a basis for vector space  $\mathbb{R}^2$ .
- 14. Find the coordinate vectors with respect to S of  $\bar{a}_1$ ,  $\bar{a}_2$  and  $\bar{v}$  in other words find  $[\bar{a}_1]_S$ ,  $[\bar{a}_2]_S$  and  $[\bar{v}]_S$ .
- 15. Find vectors  $L(\bar{a}_1)$ ,  $L(\bar{a}_2)$  and  $L(\bar{v})$ . What have the coordinate vectors  $[L(\bar{a}_1)]_S$ ,  $[L(\bar{a}_2)]_S$  and  $[L(\bar{v})]_S$ ?

16. Find a matrix B such that

$$B[\bar{a}_1]_S = [L(\bar{a}_1)]_S$$
 and  $B[\bar{a}_2]_S = [L(\bar{a}_2)]_S$ .

17. Calculate  $B[\bar{v}]_S$ . What do you notice?

Up to this point we have always written the matrix of a linear mapping with respect to the natural basis. Using another basis may prove itself useful too, though. It can be proven that for matrix B of the previous exercise

$$[L(\bar{v})]_S = B[\bar{v}]_S$$

for each vector  $\bar{v}$  in the domain. Multiplying by *B* returns therefore the values for the mapping when all vectors are expressed as coordinate vectors with respect to basis *S*.

Notice that the columns of B are the image vectors of the vectors in basis S written with respect to S:

$$B = [[L(\bar{a}_1)]_S \quad [L(\bar{a}_2)]_S].$$

This result can be generalized to any linear mapping.

The matrix B is called the matrix of linear mapping L with respect to basis S. Such a matrix is indicated as  $M(L; S \leftarrow S)$  in the lectures handouts.

## Exercise VII

18–19. Do the MATLAB-exercises available on the course's web page - you can do them for instance in room C128. It is convenient to copy the commands straight from text of the exercises.