Linear algebra and matrices II
Department of Mathematics and Statistics
Autumn 2011
Exercise sheet 5
Exercises due date: Mon 5.12.2011 at 17.00
Corrections due date: Fri 9.12.2011 at 17.00

The core ideas of these excercises are

- Injective and surjective linear mappings
- Isomorphisms
- Determinants
- Finding eigenvalues and eigenvectors


## Exercise I

It can be proven that $A \in \mathbb{R}^{n \times n}$ is invertible if and only if $\operatorname{det}(A) \neq 0$.

Let

$$
A=\left[\begin{array}{ccc}
-2 & 0 & 0 \\
4 & 6 & 0 \\
-3 & 7 & 2
\end{array}\right] \quad B=\left[\begin{array}{cccc}
0 & 1 & 0 & 0 \\
2 & 0 & 0 & 0 \\
0 & 0 & 0 & -1 \\
0 & 0 & 1 & 0
\end{array}\right], \quad \text { ja } \quad C=\left[\begin{array}{cccc}
5 & 3 & 0 & 6 \\
4 & 6 & 4 & 12 \\
0 & 2 & -3 & 4 \\
0 & 1 & -2 & 2
\end{array}\right] .
$$

1. Basing on the determinant, decide whether $A$ is invertible.
2. Basing on the determinant, decide whether $B$ is invertible.
3. Basing on the determinant, decide whether $C$ is invertible.
4. Is matrix $3 C B^{T}$ invertible?

## Exercise II

Let us consider the linear mapping $f: \mathbb{R}^{2} \rightarrow \mathbb{R}^{3}, f(\bar{x})=\left[\begin{array}{lll}7 x_{1} & x_{1}+x_{2} & 3 x_{2}-\end{array}\right.$ $\left.x_{1}\right]^{T}$. In exercise 2 of exercise sheet 4 it was shown that $f$ is an injection.
5. Show that $f$ is not a surjection.
6. MWhy doesn't this contradict theorem 4.2.15?

## Exercise III

Let $A \in \mathbb{R}^{n \times n}$. It can be proven that $\lambda$ is an eigenvalue for $A$ if and only if

$$
\operatorname{det}(A-\lambda I)=0
$$

By calculating $\operatorname{det}(A-\lambda I)$ we get a polynomial of the $n$th degree where $\lambda$ is the variable. This polynomial is called the characteristic polynomial of $A$. The eigenvalues are therefore the zeroes of this polynomial. Let $A=$ $\left[\begin{array}{rr}3 & -1 \\ -2 & 2\end{array}\right], B=\left[\begin{array}{rr}1 & 6 \\ -1 & 2\end{array}\right]$ ja $C=\left[\begin{array}{lll}4 & 1 & 1 \\ 0 & 7 & 0 \\ 0 & 0 & 7\end{array}\right]$.
7. Find the eigevalues and the corresponding eigenvectors for $A$.
8. Find the eigevalues and the corresponding eigenvectors for $B$.
9. Find the eigevalues and the corresponding eigenvectors for $C$.

## Exercise IV

10. Let $A \in \mathbb{R}^{n \times n}$. Show that $A$ is invertible if and only if the number 0 is not an eigenvalue of $A$.
11. Let $A$ be invertible and $\lambda$ be and eigenvalue for $A$. Show that $\lambda^{-1}$ is an eigenvalue for $A^{-1}$.

## Exercise V

12. Define some isomorphism between the space $\mathbb{R}^{2}$ and the plane

$$
T=\left\{\bar{x} \in \mathbb{R}^{3}: x_{1}-2 x_{2}+4 x_{3}=0\right\}
$$

(Hint: First find the generators for the plane.)

## Exercise VI

Let us consider the linear mapping $L: \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}, L(\bar{x})=\left[\begin{array}{ll}x_{1}+2 x_{2} & 4 x_{1}+3 x_{2}\end{array}\right]^{T}$ and the vectors $\bar{a}_{1}=\left[\begin{array}{ll}1 & 2\end{array}\right]^{T}, \bar{a}_{2}=\left[\begin{array}{ll}1 & -1\end{array}\right]^{T}$ and $\bar{v}=\left[\begin{array}{ll}3 & 0\end{array}\right]^{T}$.
13. Show that $S=\left\{\bar{a}_{1}, \bar{a}_{2}\right\}$ is a basis for vector space $\mathbb{R}^{2}$.
14. Find the coordinate vectors with respect to $S$ of $\bar{a}_{1}, \bar{a}_{2}$ and $\bar{v}$ - in other words find $\left[\bar{a}_{1}\right]_{S},\left[\bar{a}_{2}\right]_{S}$ and $[\bar{v}]_{S}$.
15. Find vectors $L\left(\bar{a}_{1}\right), L\left(\bar{a}_{2}\right)$ and $L(\bar{v})$. What hare the coordinate vectors $\left[L\left(\bar{a}_{1}\right)\right]_{S},\left[L\left(\bar{a}_{2}\right)\right]_{S}$ and $[L(\bar{v})]_{S}$ ?
16. Find a matrix $B$ such that

$$
B\left[\bar{a}_{1}\right]_{S}=\left[L\left(\bar{a}_{1}\right)\right]_{S} \quad \text { and } \quad B\left[\bar{a}_{2}\right]_{S}=\left[L\left(\bar{a}_{2}\right)\right]_{S} .
$$

17. Calculate $B[\bar{v}]_{S}$. What do you notice?

Up to this point we have always written the matrix of a linear mapping with respect to the natural basis. Using another basis may prove itself useful too, though. It can be proven that for matrix $B$ of the previous exercise

$$
[L(\bar{v})]_{S}=B[\bar{v}]_{S}
$$

for each vector $\bar{v}$ in the domain. Multiplying by $B$ returns therefore the values for the mapping when all vectors are expressed as coordinate vectors with respect to basis $S$.

Notice that the columns of $B$ are the image vectors of the vectors in basis $S$ written with respect to $S$ :

$$
B=\left[\left[L\left(\bar{a}_{1}\right)\right]_{S} \quad\left[L\left(\bar{a}_{2}\right)\right]_{S}\right] .
$$

This result can be generalized to any linear mapping.
The matrix $B$ is called the matrix of linear mapping $L$ with respect to basis $S$. Such a matrix is indicated as $M(L ; S \leftarrow S)$ in the lectures handouts.

## Exercise VII

18-19. Do the MATLAB-exercises available on the course's web page - you can do them for instance in room C128. It is convenient to copy the commands straight from text of the exercises.

