Inverse problems course, Exercise 1 (for the week starting on January 30, 2017)
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Related book sections (Mueller \& Siltanen 2012): 2.1.1, 2.1.2, 3.5 and 4.2.

## Theoretical exercises:

T1. Define a function $g: \mathbb{R} \rightarrow \mathbb{R}$ by

$$
g(x)= \begin{cases}1 & \text { for }-0.1 \leq x \leq 0.1 \\ 0 & \text { otherwise }\end{cases}
$$

Compute the function $g * g$ analytically (by hand), where

$$
(g * g)(x)=\int_{-\infty}^{\infty} g\left(x^{\prime}\right) g\left(x-x^{\prime}\right) d x^{\prime} .
$$

Outside which interval $[a, b] \subset \mathbb{R}$ is $(g * g)(x)=0$ ?
T2. Assume that the $n \times n$ matrix $U$ is orthogonal: $U U^{T}=I=U^{T} U$.
(a) Show that $\left\|U^{T} y\right\|=\|y\|$ for any $y \in \mathbb{R}^{n}$.
(b) Take $n=2$, let $U$ be as above and let $x, y \in \mathbb{R}^{2}$. Show that the angle between the vectors $x$ and $y$ is the same than the angle between the vectors $U x$ and $U y$.

T3. Let $A$ be a real-valued $n \times n$ matrix.
(a) Show that the matrix $A^{T} A$ is symmetric.
(b) Show that if $\lambda$ is an eigenvalue of $A^{T} A$, then $\lambda \geq 0$.

T4. Let $A$ be a real-valued $n \times n$ matrix. Recall from basic linear algebra that a symmetric matrix can be diagonalized and its eigenvectors can be chosen to be orthonormal. Denote the eigenvalues of $A^{T} A$ by

$$
d_{1}^{2} \geq d_{2}^{2} \geq \cdots \geq d_{r}^{2}>d_{r+1}^{2}=d_{r+1}^{2}=\cdots=d_{n}^{2}=0
$$

and the corresponding orthonormal eigenvectors by $V^{(1)}, V^{(2)}, \ldots, V^{(n)}$. Insert the eigenvectors as columns to a matrix called $V$. Also, write $V=\left[V_{1} V_{2}\right]$ with

$$
V_{1}=\left[V^{(1)} V^{(2)} \cdots V^{(r)}\right], \quad V_{2}=\left[V^{(r+1)} V^{(r+2)} \cdots V^{(n)}\right] .
$$

Then

$$
V^{T} A^{T} A V=\left[\begin{array}{cc}
\Sigma^{2} & 0 \\
0 & 0
\end{array}\right],
$$

where the $r \times r$ matrix $\Sigma$ is defined by $\Sigma^{2}=\operatorname{diag}\left(d_{1}^{2}, \ldots, d_{r}^{2}\right)$. Here $V_{1}^{T} A^{T} A V_{1}=$ $\Sigma^{2}$. Show that $A V_{2}=0$. Now define a $n \times r$ matrix $U_{1}$ by $U_{1}=A V_{1} \Sigma^{-1}$. Show that $U_{1}^{T} U_{1}=I$. Therefore the columns of $U_{1}$ are orthonormal. Show that we can define an orthonormal $n \times n$ matrix in the form $U=\left[U_{1} U_{2}\right]$. Finally, derive the SVD by showing that

$$
U^{T} A V=\left[\begin{array}{ll}
\Sigma & 0 \\
0 & 0
\end{array}\right] .
$$

Hint: use the block forms of the matrices.

## Matlab exercises:

M1. Let the point spread function $p \in \mathbb{R}^{5}$ and the vector $\mathbf{f} \in \mathbb{R}^{16}$ be defined by

$$
\begin{aligned}
p & =\left[p_{-2}, p_{-1}, p_{0}, p_{1}, p_{2}\right]^{T}=\left[\frac{1}{16}, \frac{3}{16}, \frac{1}{2}, \frac{3}{16}, \frac{1}{16},\right]^{T}, \\
\mathbf{f} & =\left[\mathbf{f}_{1}, \mathbf{f}_{2}, \mathbf{f}_{3}, \mathbf{f}_{4}, \mathbf{f}_{5}, \mathbf{f}_{6}, \mathbf{f}_{7}, \mathbf{f}_{8}, \mathbf{f}_{9}, \mathbf{f}_{10}, \mathbf{f}_{11}, \mathbf{f}_{12}, \mathbf{f}_{13}, \mathbf{f}_{14}, \mathbf{f}_{15}, \mathbf{f}_{16}\right]^{T} \\
& =[0,0,0,0,1,1,0,0,0,0,0,0,0,0,0,0]^{T} .
\end{aligned}
$$

Note the non-standard indexing of the vector $p$. Define the discrete convolution vector $(p * \mathbf{f}) \in \mathbb{R}^{16}$ by

$$
\begin{equation*}
(p * \mathbf{f})_{j}=\sum_{\ell=-2}^{2} p_{\ell} \mathbf{f}_{j-\ell}, \quad 1 \leq j \leq 16 \tag{1}
\end{equation*}
$$

where we use the following definition for out-of-bounds indices:

$$
\begin{equation*}
\mathbf{f}_{j-\ell}=0 \quad \text { for } j-\ell<1 \text { and } j-\ell>16 . \tag{2}
\end{equation*}
$$

Boundary condition (2) is called zero extension.
(a) Use a for-loop to calculate the vector $p * \mathbf{f}$ straight from definition (1) using the boundary condition (2).
(b) Use the command convmtx for building a convolution matrix $A$. Calculate the vector $p * \mathbf{f}$ as $A \mathbf{f}$. Check that you get the same result than in (a).
(b) Use the command conv2 to calculate the vector $p * \mathbf{f}$. Check that you get the same result than in (a).

M2. Periodic boundary conditions are defined by

$$
\begin{array}{lll}
\mathbf{f}_{0}=\mathbf{f}_{16}, & \mathbf{f}_{-1}=\mathbf{f}_{15}, & \mathbf{f}_{-2}=\mathbf{f}_{13}, \\
\mathbf{f}_{17}=\mathbf{f}_{1}, & \mathbf{f}_{18}=\mathbf{f}_{2}, & \mathbf{f}_{19}=\mathbf{f}_{3},  \tag{3}\\
& \cdots
\end{array}
$$

(a) Use a for-loop to calculate the vector $p * \mathbf{f}$ straight from definition (1) using the boundary condition (3).
(b) Use the command convmtx for building a convolution matrix $A$. Modify the convolution matrix so that it implements the periodic boundary conditions (3). Calculate the vector $p * \mathbf{f}$ as $A \mathbf{f}$. Check that you get the same result than in (a).
(b) Use Fast Fourier Transform (FFT) to calculate the vector $p * \mathbf{f}$ with the periodic boundary conditions (3). In principle this approach takes the simple form

$$
\begin{equation*}
\operatorname{ifft}(f f t(p) \cdot f f t(f)), \tag{4}
\end{equation*}
$$

where • stands for element-wise vector product. However, in (4) the vectors $p$ and $\mathbf{f}$ have to have the same length, so you need to "zero-pad" vector $p$ so that it has 16 elements. In the zero-padding process you need to be careful with the location of the centerpoint of the PSF. Studying the command fftshift may help you.
Check that you get the same result than in (a).

