

5. Unbounded operators

(See also Hall, chapter 9)

Defn 5.1. Graph of an operator.

The graph of any function $f: \mathbb{X} \rightarrow \mathbb{F}$ is the subset $\{(x, f(x))\} \subset \mathbb{X} \times \mathbb{F}$.

The graph of an operator $A: D \rightarrow \mathcal{H}$ is thus

$$\{(\psi, A\psi)\} \subset D \times \mathcal{H} \subset \mathcal{H} \times \mathcal{H}.$$

Note the unfortunate need for new notation; otherwise indistinguishable from a scalar product. A better choice, used sometimes in math. phys., is to use " $\langle \cdot, \cdot \rangle$ " for scalar product.

Reminder: * $\mathcal{H}_1 \times \mathcal{H}_2$ can be made into a Hilbert space by endowing it with a scalar product:

$$((\psi_1, \psi_2), (\phi_1, \phi_2)) := (\psi_1, \phi_1) + (\psi_2, \phi_2)$$

Proof: easy computation, since

$$\|(\psi_1, \psi_2)\|^2 = \|\psi_1\|^2 + \|\psi_2\|^2$$

The resulting Hilbert space is denoted by

$$\mathcal{H}_1 \oplus \mathcal{H}_2 \quad (= \text{external direct sum})$$

which is true also in the previous

sense of \oplus (= internal direct sum, defn. 2.8.)

after we identify $\mathcal{H}_1 \cong \{(\psi, 0) \mid \psi \in \mathcal{H}_1\}$
 $\mathcal{H}_2 \cong \{(0, \psi) \mid \psi \in \mathcal{H}_2\}.$

* For an operator A , its graph is def. as

$$G(A) := \{(\psi, A\psi) \mid \psi \in D(A)\} \subset \mathcal{H} \oplus \mathcal{H}.$$

Defn. 5.2. An operator A on \mathcal{H} is closed, if its graph is closed, i.e.,

$$G(A) = \overline{G(A)} \quad \leftarrow \text{topology of } \mathcal{H} \oplus \mathcal{H}$$

Observation 5.3. An operator A is closed if and only if (cc) holds:

(cc) For any sequence $x_n \in D(A)$, for which there are $x, \phi \in \mathcal{X}$ s.t. $x_n \rightarrow x$, and $Ax_n \rightarrow \phi$ in norm, we have $\phi = Ax$, $x \in D(A)$ and

Proof. Assume A closed. Let (x_n) be a sequence as in (cc). Then

$$\begin{aligned} & \| (x, \phi) - (x_n, Ax_n) \|^2 \\ &= \| x - x_n \|^2 + \| \phi - Ax_n \|^2 \xrightarrow{n \rightarrow \infty} 0, \end{aligned}$$

and thus $(x, \phi) \in \overline{G(A)} = G(A) \Rightarrow \phi = Ax, x \in D(A)$.
Therefore, (cc) holds.

For the converse, assume (cc) holds.

Let $(x, \phi) \in \overline{G(A)} \Rightarrow \exists \text{ seq. } (x_n, \phi_n) \in G(A)$
s.t. $\| (x, \phi) - (x_n, \phi_n) \| \rightarrow 0$.

But since then $\phi_n = Ax_n$ and $\| x - x_n \| \rightarrow 0$,
 $\| \phi - \phi_n \| \rightarrow 0$, (cc) implies that $\phi = Ax, x \in D(A)$.
 $\Rightarrow (x, \phi) = (x, Ax) \in G(A)$. Thus $G(A) = \overline{G(A)}$
and A is closed. \square

- * Clearly, $A \subset B \Leftrightarrow G(A) \subset G(B)$, and $A=B \Leftrightarrow G(A)=G(B)$.
- * Every $T \in \mathcal{B}(\mathcal{X})$ satisfies (cc), and is thus closed.

Defn. 5.4. An operator A is closable if it has a closed extension.

Thm. 5.5. If A is closable, then it has a unique smallest closed extension \overline{A} . In addition, $G(\overline{A}) = \overline{G(A)}$.

Proof. Let B be a closed extension of A .
 $\Rightarrow D(A) \subset D(B)$ and $\forall x \in D(A): Bx = Ax$.
Thus $G(A) \subset G(B) \Rightarrow \overline{G(A)} \subset \overline{G(B)} = G(B)$

Let

$$D' := \{ x \in \mathcal{X} \mid \exists \phi \in \mathcal{X} \text{ s.t. } (x, \phi) \in \overline{G(A)} \} \\ (= P_1 \overline{G(A)})$$

For any $\alpha_i \in \mathbb{C}$, $((x_i, \phi_i)) \in G(A)$,

we have $\psi_i \in D(A)$ and $\phi_i = A\psi_i$

$$\begin{aligned} \Rightarrow & \alpha_1 ((\psi_1, \phi_1)) + \alpha_2 ((\psi_2, \phi_2)) \\ & = ((\alpha_1 \psi_1 + \alpha_2 \psi_2, \alpha_1 \phi_1 + \alpha_2 \phi_2)) \\ & = ((\underbrace{\alpha_1 \psi_1 + \alpha_2 \psi_2}_{\in D(A)}, A(\alpha_1 \psi_1 + \alpha_2 \psi_2))) \in \mathcal{G}(A). \end{aligned}$$

Therefore, $\mathcal{G}(A)$ is a subspace $\Rightarrow \overline{\mathcal{G}(A)}$ is a subspace
 $\Rightarrow D' = P_1 \overline{\mathcal{G}(A)}$ is a subspace. (& independent of B)

In addition, if $((\psi, \phi)) \in \overline{\mathcal{G}(A)} \subset \mathcal{G}(B)$ then $\psi \in D(B)$ and $\phi = B\psi$.
 Thus $D'(D(B))$ and $\{((\psi, B\psi)) \mid \psi \in D'\} = \overline{\mathcal{G}(A)}$.

We define $A'_B = B|_{D'}$. By the above results,
 A'_B is an operator for which $\mathcal{G}(A'_B) = \overline{\mathcal{G}(A)}$.

In addition, $\psi \in D(A) \Rightarrow ((\psi, A\psi)) \in \mathcal{G}(A) \subset \overline{\mathcal{G}(A)}$

$\Rightarrow \psi \in D'$ and $A'_B \psi = B\psi = A\psi$. Thus A'_B is
 a closed extension of A , and $A \subset A'_B \subset B$.

Let B' be some other closed extension on A .

Then we can construct $A'_{B'}$ for which $\mathcal{G}(A'_{B'}) = \overline{\mathcal{G}(A)} = \mathcal{G}(A'_B)$.

Thus $A'_{B'} = A'_B$ and $A \subset A'_{B'} \subset B'$. Therefore, we can
 choose any B' , and define $\bar{A} = A'_B$. Then for
 any $B' \supset A$, closed, we have $A \subset \bar{A} \subset B'$,
 and \bar{A} is closed. Thus \bar{A} is a minimal closed
 extension of A , and it is obviously unique.

By construction, $\mathcal{G}(\bar{A}) = \overline{\mathcal{G}(A)}$. \square

Remarks * \bar{A} is called the closure of A .

* Bounded operators are closable.

* However, there are unbounded operators, which are not closable;
 it can even happen that $\mathcal{G}(A) = \mathcal{H} \oplus \mathcal{H}$.

* If A is a closed operator, a subspace
 $C \subset D(A)$ is called a core for A if
 the restriction R of A to C satisfies
 $\overline{R} = A$; in short, if $\overline{A|_C} = A$.

5.6. Defn.

Let A be a densely defined operator. Define

$$D^* := \{ \phi \in \mathcal{X} \mid \mathcal{N} \mapsto (\phi, A\mathcal{N}) \text{ is continuous } D(A) \rightarrow \mathbb{C} \}$$

$$= \{ \phi \in \mathcal{X} \mid \sup_{\substack{\mathcal{N} \in D(A) \\ \|\mathcal{N}\|=1}} |(\phi, A\mathcal{N})| < \infty \}$$

Suppose $\phi \in D^*$. Since $D(A)$ is a subspace, the map $\mathcal{N} \mapsto (\phi, A\mathcal{N})$ has a continuous (bounded) extension $\Lambda: \mathcal{X} \rightarrow \mathbb{C}$, and Λ is linear and bounded. (Hahn-Banach Thm. (Rudin, Funct. Anal., 3.6.) or as in Exercise 2.4.). Thus by 3.1.a)

$$\exists! \mathcal{N}_0 \in \mathcal{X} \text{ s.t. } \Lambda \mathcal{N} = (\mathcal{N}_0, \mathcal{N}).$$

Thus \mathcal{N}_0 is such that

$$(*) \quad (\mathcal{N}_0, \mathcal{N}) = (\phi, A\mathcal{N}) \quad \forall \mathcal{N} \in D(A).$$

Since $D(A)$ is dense, \mathcal{N}_0 is the only vector in \mathcal{X} which satisfies (*).

Therefore, we can define $A^*: D^* \rightarrow \mathcal{X}$ by $A^*: \phi \mapsto \mathcal{N}_0$, s.t. \mathcal{N}_0 solves (*).

Proposition: A^* is an operator.

Proof. $\alpha_1, \alpha_2 \in \mathbb{C}$ and $\phi_1, \phi_2 \in D^* \Rightarrow$
 if $\mathcal{N} \in D(A)$, then $|(\alpha_1 \phi_1 + \alpha_2 \phi_2, A\mathcal{N})|$
 $\leq |\alpha_1| |(\phi_1, A\mathcal{N})| + |\alpha_2| |(\phi_2, A\mathcal{N})|$
 $\Rightarrow \alpha_1 \phi_1 + \alpha_2 \phi_2 \in D^*$. $\therefore D^*$ subspace.

Also $(\alpha_1 A^* \phi_1 + \alpha_2 A^* \phi_2, \mathcal{N})$
 $= \alpha_1^* (A^* \phi_1, \mathcal{N}) + \alpha_2^* (A^* \phi_2, \mathcal{N})$
 $= \alpha_1^* (\phi_1, A\mathcal{N}) + \alpha_2^* (\phi_2, A\mathcal{N})$
 $= (\alpha_1 \phi_1 + \alpha_2 \phi_2, A\mathcal{N}) \quad \forall \mathcal{N} \in D(A),$
 \Rightarrow (by unig. of \mathcal{N}_0) $A^*(\alpha_1 \phi_1 + \alpha_2 \phi_2)$
 $= \alpha_1 A^* \phi_1 + \alpha_2 A^* \phi_2.$

$\therefore A^*$ is linear. \square

Summary : The adjoint A^* of a densely defined operator A is defined by:

$$D(A^*) := \{ \phi \in \mathcal{H} \mid \sup_{\substack{\psi \in D(A), \\ \|\psi\|=1}} |(\phi, A\psi)| < \infty \}$$

and for $\phi \in D(A^*)$, $A^*\phi$ is the unique solution to the equation

$$(A) \quad (A^*\phi, \psi) = (\phi, A\psi) \quad \forall \psi \in D(A).$$

Remarks :

- * If A is not densely defined, the solution to (A) is not unique: one can always add any vector in $D(A)^\perp$ to $A^*\phi$.

- * If $A \in \mathcal{B}(\mathcal{H})$, Let A_1^* denote its adjoint as defined in 3.2 and A_2^* the adjoint as def. above. Since $|(\phi, A\psi)| \leq \|\phi\| \|A\| \|\psi\|$ for $\|\psi\|=1$ it follows that $D(A_2^*) = \mathcal{H} = D(A_1^*)$. Also, if $\psi, \phi \in \mathcal{H}$, then $\phi \in D(A_2^*)$, $\psi \in D(A)$ and thus by (A) and 3.2.

$$(A_2^*\phi, \psi) = (\phi, A\psi) = (A\psi, \phi)^* = (\psi, A_1^*\phi)^* = (A_1^*\phi, \psi) \quad \forall \phi, \psi \in \mathcal{H}.$$

$$\Rightarrow A_1^*\phi = A_2^*\phi \quad \forall \phi \Rightarrow A_1^* = A_2^*.$$
 That is, the definitions of adjoint agree for $A \in \mathcal{B}(\mathcal{H})$.

- * We assumed $D(A)$ is dense to define A^* . However, $D(A^*)$ need not be dense. It can even happen that $D(A^*) = \{0\}$.

- * If $D(A)$ and $D(A^*)$ are both dense, we denote $A^{**} = (A^*)^*$.

5.7. Relations between closure and adjoint

Theorem Let A be a densely defined operator. Then all of the following are true:

- a) A^* is closed.
- b) A is closable $\Leftrightarrow D(A^*)$ is dense.
- c) If A is closable, then $\bar{A} = A^{**}$ and $(\bar{A})^* = A^*$.

Proof. Consider the map $V: \mathcal{H} \oplus \mathcal{H} \rightarrow \mathcal{H} \oplus \mathcal{H}$ defined by $V((\psi, \phi)) := ((-\phi, \psi))$. Obviously V is linear, and a bijection. Also $\|V((\psi, \phi))\|^2 = \|-\phi\|^2 + \|\psi\|^2 = \|(\psi, \phi)\|^2$ and thus (Exercise 3.4) V is unitary.

Since clearly $V^2 = -1$, we thus have $V^* = V^{-1} = -V$. Now, if $E \subset \mathcal{H} \oplus \mathcal{H}$ is a subset, also $V(E^\perp) = (V(E))^\perp$.

(Proof: V is unitary, thus $x \in V(E)^\perp \Leftrightarrow \forall y \in V(E) : (x, y) = 0 \Leftrightarrow \forall x' \in E : (x, Vx') = 0 \stackrel{V^* \text{ unit.}}{\Leftrightarrow} \forall x' \in E : (\underbrace{V^*x}_{=V^{-1}x}, \underbrace{V^*Vx'}_{=x'}) = 0 \Leftrightarrow V^{-1}x \in E^\perp \Leftrightarrow x \in V(E^\perp)$ \square)

On the other hand, $(\psi, \phi) \in V(G(A))^\perp \Leftrightarrow \forall (\psi', \phi') \in G(A) : (V(\psi', \phi'), (\psi, \phi)) = 0 \Leftrightarrow \forall \psi' \in D(A) : ((-A\psi', \psi'), (\psi, \phi)) = 0 \Leftrightarrow \forall \psi' \in D(A) : -(A\psi', \psi) + (\psi', \phi) = 0 \Leftrightarrow \forall \psi' \in D(A) : (\phi, \psi') = (\psi, A\psi') \Leftrightarrow \psi \in D(A^*), \phi = A^*\psi \Leftrightarrow (\psi, \phi) \in G(A^*)$

Therefore, $G(A^*) = V(G(A))^\perp =$ closed subset. $\Rightarrow A^*$ is a closed operator. \Rightarrow a).

To prove b), note that $G(A)$ is a subspace of $\mathcal{H} \oplus \mathcal{H}$ (see p. 44), and thus (Exercise 3.2.) $G(A) = (G(A)^\perp)^\perp = (V^*[V(G(A)^\perp)])^\perp = (V^*[(V_G(A)^\perp)]^\perp = (V^*[G(A^*)])^\perp = ((-V)[G(A^*)])^\perp = (V_G(A^*))^\perp$.

Thus if $D(A^*)$ is dense, we have $G(A^{**}) = V(G(A^*))^\perp = G(A) \Rightarrow A^{**}$ is a closed \rightarrow

extension of $A \Rightarrow A$ is closable

and $\mathcal{G}(\bar{A}) = \overline{\mathcal{G}(A)} = \mathcal{G}(A^{**}) \Rightarrow \bar{A} = A^{**}$.

Conversely, if $\mathcal{D}(A^*)$ is not dense $\Rightarrow \exists \psi_0 \in \mathcal{D}(A^*)^\perp$

with $\psi_0 \neq 0 \Rightarrow$ for any $((\psi, \phi)) \in \mathcal{G}(A^*)$, we have

$$((\psi, \phi), (\psi_0, 0)) = (\psi, \psi_0) = 0$$

$$\Rightarrow ((\psi_0, 0)) \in \mathcal{G}(A^*)^\perp$$

$$\Rightarrow ((0, \psi_0)) = \mathcal{V}((\psi_0, 0)) \in \mathcal{V}(\mathcal{G}(A^*)^\perp) = (\mathcal{V}\mathcal{G}(A^*))^\perp = \overline{\mathcal{G}(A)}.$$

If A is closable, $\mathcal{G}(\bar{A}) = \overline{\mathcal{G}(A)}$ and $((0, \psi_0)) \in \mathcal{G}(\bar{A})$

implies $\psi_0 = \bar{A}(0) = 0$, which would be a contradiction.

Thus A is not closable. \therefore b) holds.

For c), assume A is closable. We proved above that $\bar{A} = A^{**}$. Since A^* is closed,

$$\text{also } A^* = \overline{A^*} = (A^*)^{**} = ((A^*)^*)^* = (A^{**})^* = \bar{A}^*. \quad \square$$

5.8. Definition: An operator A is symmetric if

$$(\phi, A\psi) = (A\phi, \psi) \quad \forall \phi, \psi \in \mathcal{D}(A).$$

5.9. Definition: An operator A is self-adjoint if it is densely defined and $A^* = A$.

5.10. Thm: Let S, T be densely defined operators.

(Proof: Exercises

4.2. & 5.1.)

Then a) $S \subset T \Rightarrow T^* \subset S^*$

b) S symmetric $\Leftrightarrow S \subset S^*$

c) S symmetric $\Rightarrow S$ closable, and \bar{S} symmetric.

5.11. Defn. A densely defined operator S is called essentially self-adjoint, if S is symmetric and \bar{S} is self-adjoint.

5.12. Remark: 5.8. looks like the most natural generalization of the concept

of self-adjointness from bounded operators to densely defined ones. In Theorem 5.14, (Stone's theorem) we will find out why the definition in 5.6. is the one relevant to Q.M.

* Examples (some of the proofs later in exercises, see also Hall's book) :

Consider $\mathcal{H} := L^2([0,1])$ and

$$D := \{ \psi \in \mathcal{H} \mid \psi \text{ is differentiable at every point, and } \psi' : [0,1] \rightarrow \mathbb{C} \text{ is continuous} \}$$

If $\psi \in D$, obviously $\psi' \in \mathcal{H}$. Define operators A_0, A_1, A_2 by the formula

$$A_l \psi := -i \psi', \quad l = 0, 1, 2$$

using the following subsets of D as domains

$$D(A_0) := \{ \psi \in D \mid \psi(0) = 0 = \psi(1) \}$$

$$D(A_1) := \{ \psi \in D \mid \psi(0) = \psi(1) \}$$

$$D(A_2) := D.$$

Clearly, $A_0 \subset A_1 \subset A_2 \stackrel{5.10.}{\Rightarrow} A_2^* \subset A_1^* \subset A_0^*$, since each of the domains is dense in \mathcal{H} .

It turns out that

a) A_0 is symmetric but $\overline{A_0}$ is not self-adjoint. (Hall, Proposition 9.27; see c) below)

b) A_1 is symmetric and $\overline{A_1}$ is self-adjoint (Hall, end of Section 9.6.)

c) $A_2 \subset A_0^*$ (Hall, Lemma 9.28)

$\stackrel{5.2.}{\Rightarrow} \overline{A_0} \subset \overline{A_2} \subset A_0^*$. Since $\overline{A_0} \neq \overline{A_2}$ (Hall, p. 184), $\overline{A_0} \neq A_1^*$.

* However, the operator A' analogous to A_0 on $L^2(\mathbb{R})$,

$$D(A') := C_c^\infty(\mathbb{R}) \quad \text{and} \quad A' \psi := -i \psi' \quad (\psi \in C_c^\infty(\mathbb{R}) \subset L^2(\mathbb{R})),$$

is essentially self-adjoint on $L^2(\mathbb{R})$. (Hall, Prop. 9.29)

For Theorem 9.6, we need the following Lemma:

9.8. Lemma Suppose T is a densely defined closed operator on \mathcal{H} .

Then for any $\phi, \phi' \in \mathcal{H}$ there are unique $\eta \in D(T)$; $\eta' \in D(T^*)$ s.t.
 (*) $\begin{cases} -T\eta + \eta' = \phi \\ \eta + T^*\eta' = \phi' \end{cases}$

Proof: Consider the proof of Theorem 5.7.

There we defined the map $\mathcal{V}((\eta, \phi)) = ((-\phi, \eta))$, which was unitary on $\mathcal{H} \oplus \mathcal{H}$, and showed that $\mathcal{G}(T^*) = \mathcal{V}(\mathcal{G}(T))^\perp$. Also since now $\mathcal{G}(T)$ is closed, also $\mathcal{V}(\mathcal{G}(T))$ is a closed subspace, and thus by Ex. 3.2. $\Rightarrow \mathcal{V}(\mathcal{G}(T)) = [\mathcal{V}(\mathcal{G}(T))^\perp]^\perp = \mathcal{G}(T^*)^\perp$. Since $\mathcal{G}(T^*)$ is also a closed subspace, this implies (Theorem 2.11.) that

$$\mathcal{H} \oplus \mathcal{H} = \mathcal{G}(T^*) \oplus \mathcal{G}(T^*)^\perp = \mathcal{G}(T^*) \oplus \mathcal{V}(\mathcal{G}(T)).$$

Thus for any $((\phi, \phi')) \in \mathcal{H} \oplus \mathcal{H}$ there are unique $a \in \mathcal{G}(T^*)$, $b \in \mathcal{V}(\mathcal{G}(T))$ s.t. $((\phi, \phi')) = a + b$.
 $\Rightarrow \exists \eta \in D(T)$ and $\eta' \in D(T^*)$ s.t.
 $a = ((\eta', T^*\eta'))$, $b = ((-T\eta, \eta))$.
 \Rightarrow (*) holds. To see uniqueness, assume also $\tilde{\eta}$, and $\tilde{\eta}'$ satisfy (*), and def.
 $\tilde{a} = ((\tilde{\eta}', T^*\tilde{\eta}'))$, $\tilde{b} = ((-T\tilde{\eta}, \tilde{\eta})) = \mathcal{V}((\tilde{\eta}, T\tilde{\eta}))$
 Then $\tilde{a} \in \mathcal{G}(T^*)$, $\tilde{b} \in \mathcal{V}(\mathcal{G}(T))$ and
 $\tilde{a} + \tilde{b} = ((\phi, \phi')) \Rightarrow \tilde{a} = a, \tilde{b} = b \quad \square$

9.9. Corollary Suppose T is densely defined and closed operator. Then $R(1 + T^*T) = \mathcal{H}$.

Proof: Suppose $\phi' \in \mathcal{H}$ is given, and apply the lemma with $\phi = 0$. $\Rightarrow \exists \eta \in D(T)$, $\eta' \in D(T^*)$ s.t. $\eta' = T\eta$ and $\phi' = \eta + T^*\eta' = \eta + T^*T\eta$
 $\Rightarrow \eta \in D(1 + T^*T)$ and $\phi' = (1 + T^*T)\eta \quad \square$

The following result is also a corollary of the earlier result $G(T^*) = [NG(T)]^\perp$ proven in Thm 5.7.

It has also an easy direct proof, see Proposition 9.12. in Hall's book. (Note: in Hall's book "unbounded operator" means a densely defined operator, cf. Def. 3.1. of the book.)

Proposition: If T is a densely defined operator, then

$$\text{Ker}(T^*) = \text{R}(T)^\perp.$$

Proof. Since $G(T^*) = [NG(T)]^\perp$, this follows by checking that the following equalities hold:

$$\begin{aligned} \mathcal{N} \in \text{R}(T)^\perp &\stackrel{(*)}{\Leftrightarrow} (\mathcal{N}, 0) \in [NG(T)]^\perp = G(T^*) \\ &\Leftrightarrow \mathcal{N} \in \text{D}(T^*) \text{ and } T^*\mathcal{N} = 0 \Leftrightarrow \mathcal{N} \in \text{Ker}(T^*). \end{aligned}$$

Of these, only the first one $(*)$ does not follow immediately from the definitions.

To see $(*)$, note that $(\phi_1, \phi_2) \in NG(T) \Leftrightarrow -N(\phi_1, \phi_2) = (\phi_2, -\phi_1) \in G(T) \Leftrightarrow \phi_2 \in \text{D}(T) \text{ and } -\phi_1 = T\phi_2 \Leftrightarrow \exists \phi \in \text{D}(T) \text{ s.t. } \phi_1 = T\phi, \phi_2 = -\phi \Rightarrow \phi_1 \in \text{R}(T)$. Since always

$$\langle (\phi_1, \phi_2) | (\mathcal{N}, 0) \rangle_{\mathcal{R} \oplus \mathcal{R}} = \langle \phi_1 | \mathcal{N} \rangle_{\mathcal{R}}$$

clearly $\mathcal{N} \in \text{R}(T)^\perp \Rightarrow (\mathcal{N}, 0) \in [NG(T)]^\perp$. Also, if $\phi_1 \in \text{R}(T) \Rightarrow \exists \phi \in \text{D}(T) \text{ s.t. } \phi_1 = T\phi \Rightarrow (\phi_1, -\phi) \in NG(T)$. Hence, $(\mathcal{N}, 0) \in [NG(T)]^\perp \Rightarrow \langle \phi_1 | \mathcal{N} \rangle = 0 \forall \phi_1 \in \text{R}(T) \Rightarrow \mathcal{N} \in \text{R}(T)^\perp$. \square

5.13. Suppose the map $Q: I \rightarrow \mathcal{B}(\mathcal{H})$, $I \subset \mathbb{R}$ interval, is strongly continuous. $Q(t)$ is said to be strongly differentiable at t_0 for $\psi_0 \in \mathcal{H}$, if the following norm-lim. exists

$$\exists \lim_{\substack{t \rightarrow t_0 \\ t \in I}} \frac{1}{t-t_0} (Q(t)\psi_0 - Q(t_0)\psi_0) =: \frac{d}{dt} Q(t)\psi_0 \Big|_{t=t_0}$$

Defn. Suppose $(U(t))_{t \geq 0}$ is a strongly continuous unitary semi-group. Its infinitesimal generator is a map $A: D(A) \rightarrow \mathcal{H}$ defined using

$$D(A) := \{ \psi \in \mathcal{H} \mid U(t) \text{ is strongly differentiable at } t=0 \text{ for } \psi \}$$

and for any $\psi \in D(A)$

$$A\psi := \lim_{\varepsilon \rightarrow 0^+} \frac{i}{\varepsilon} (U(\varepsilon)\psi - \psi) = i \frac{d}{dt} U(t)\psi \Big|_{t=0}$$

5.14. Theorem (Stone)

Suppose $(U(t))_{t \geq 0}$ is a strongly continuous unitary semigroup, and let A denote its infinitesimal generator, defined as above. Then A is a densely defined self-adjoint operator on \mathcal{H} and $\forall t \geq 0$:

$$(Exp) \quad U(t) = e^{-itA} \quad (\text{defined via spectral decomposition of } A)$$

Denote $\psi(t) := U(t)\psi$ for $\psi \in \mathcal{H}$, $t \geq 0$.

Then a) $t \mapsto \psi(t)$ is norm-continuous.

b) If $\psi(0) \in D(A)$, then $\psi(t) \in D(A) \forall t \geq 0$ and

$$i \frac{d}{dt} \psi(t) = A\psi(t) = U(t)A\psi(0).$$

c) $\forall \psi(0) \in \mathcal{X} : \psi(t) = \lim_{\epsilon \rightarrow 0^+} \exp(-it \frac{1}{\epsilon}(U(\epsilon)-1)) \psi(0).$

Conversely, if A is self-adjoint, and $U(t) = e^{-itA}$, then $(U(t))_{t \geq 0}$ is a strongly continuous semigroup and A is its infinitesimal generator.

Proof : Functional calculus with spectral representations. (See the Appendix on page 55.) For complete proofs, see Rudin, Funct. Anal., Th. 13.35 and Th. 13.37 or Reed & Simon I, chapter VIII.4. or Teschl, chapter 3. \square or Hall, chapter 10.

Remarks : * The spectrum of a self-adjoint operator A , is a set $\sigma(A) \subset \mathbb{R}$. The spectral representation assigns to every Borel subset $\omega \subset \sigma(A)$ an orthogonal projection P_ω so that for any $\phi, \psi \in \mathcal{X}$ the map $\mu_{\phi, \psi} : \omega \mapsto (\phi, P_\omega \psi)$ is a Borel measure, and $\forall \phi \in \mathcal{X}, \psi \in D(A)$

$$(\phi, A\psi) = \int_{\sigma(A)} \lambda \mu_{\phi, \psi}(d\lambda) =: \int_{\sigma(A)} \lambda d(\phi, P_\lambda \psi)$$

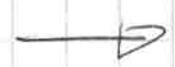
The definition in (Exp) means

$$\forall t \in \mathbb{R}, \phi, \psi \in \mathcal{X} :$$

$$(\phi, e^{-itA} \psi) =: \int_{\sigma(A)} e^{-it\lambda} d(\phi, P_\lambda \psi)$$

and the basic results of functional calculus show that then $D(e^{-itA}) = \mathcal{X}$ and e^{-itA} is unitary operator.

* If $\mathcal{X} = \mathbb{C}^N$, A is a self-adjoint matrix, with eigenvalues $\lambda_n \in \mathbb{R}$ and (orthonormal) collection of eigenvectors $e_n \in \mathbb{C}^N \dots$



... and the spectral definition means

$$(\phi, e^{-itA} \psi) := \sum_{n=1}^{\infty} e^{-it\lambda_n} (\phi, e_n)(e_n, \psi).$$

* If A is a bounded operator,

$$e^{-itA} = \sum_{n=0}^{\infty} \frac{1}{n!} (-itA)^n, \quad (*)$$

but for unbounded operators, using the sum is usually not a good idea. For instance, if A is self-adj, usually $D(A^2) \subset D(A)$ is a proper subset, and the sum in (*) makes sense only for so called analytic vectors; for ψ s.t.

$$\psi \in C^\infty(A) := \bigcap_{n=1}^{\infty} D(A^n) \text{ and } \sum_{n=0}^{\infty} \frac{1}{n!} \|A^n \psi\| t^n < \infty \text{ for some } t > 0.$$

* It is possible, that S is essentially self-adjoint, i.e., S is symmetric and \bar{S} is self-adjoint, but although $C^\infty(\bar{S})$ is dense, $C^\infty(S)$ is empty.

* However, by c), e^{-itA} is a strong limit of $\sum_{n=0}^{\infty} \frac{1}{n!} (-itA_\epsilon)^n$ where $A_\epsilon = \frac{1}{\epsilon}(U(\epsilon) - I)$ is a bounded operator.

5.15 Remark: Stone's theorem shows that the best we can do to understand the original Schrödinger equation $i \frac{d}{dt} \psi(t) = S\psi(t)$ on page 3 is to find a dense subspace of \mathcal{X} for which the right hand side makes sense, and then look for self-adjoint extensions of S. As we will see later, even if S is symmetric, any of the following can happen:
1) \bar{S} is the unique self-adjoint extension (S.A.E.)
2) There are (infinitely) many S.A.E.
3) There are no S.A.E.

- * If 1) happens, we should just be happy.
- * 2) means that we forgot to "put in all the physics" in the Schrödinger equation. Typical examples are boundary conditions.
- * 3) means that the (physical) system is not closed, and we are either forced to "leak" or "inject probability". (roughly speaking)

5.16. Examples: Three standard ways of defining operators on $\mathcal{H} = L^2(\Omega)$ when $\Omega \subset \mathbb{R}^d$, open subset: multiplication, integral, and differential operators.

1) Multiplication operators (potentials)

Let $V: \Omega \rightarrow \mathbb{C}$ be Lebesgue measurable.

The corresponding multiplication operator

M_V (also denoted \hat{V} or simply V)

is a mapping $D(M_V) \rightarrow \mathcal{H}$

defined by

$$(M_V \psi)(x) = V(x)\psi(x), \quad x \in \Omega$$

on

$$D(M_V) := \{\psi \in \mathcal{H} \mid V\psi \in L^2(\Omega)\}.$$

M_V has the following properties: (Ex. 5.2.)

a) M_V is a closed, densely defined operator.

b) $(M_V)^* = M_V^*$

c) M_V self-adjoint $\Leftrightarrow V(x) \in \mathbb{R}$ a.e. $x \in \Omega$.

* Thus every $V: \Omega \rightarrow \mathbb{R}$, which is Lebesgue measurable, generates a strongly cont. U.S.G. with $U_t = e^{-itM_V} = M_V(e^{-itV})$.