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P.1

## Computational methods for Integral Equations

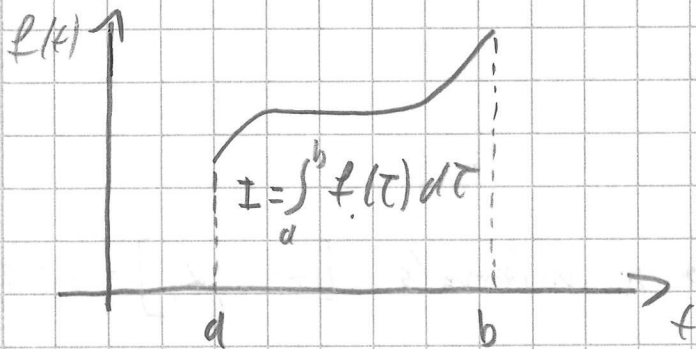
I Numerical Integration

We seek to compute the Riemann Integral

$$I(f) := I_a^b(f) := \int_a^b f(t) dt$$

Where  $f$  is piecewise continuous on  $[a, b] \subset \mathbb{R}$ .

$$f \in C([a, b])$$



The procedure of numerical integration is referred to as numerical quadrature.

1) Quadrature formulas

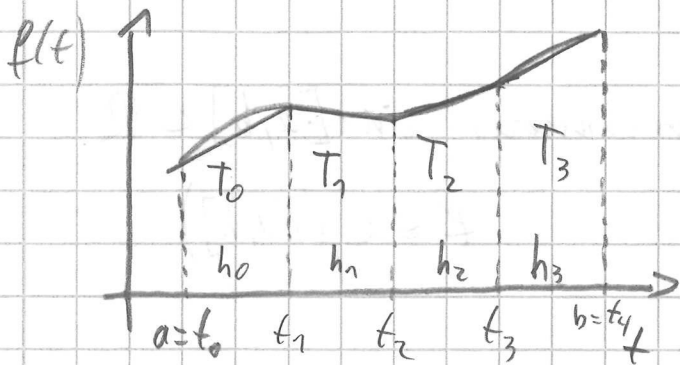
def  $I_a^b = I: (C([a, b]) \rightarrow \mathbb{R}, f \mapsto \int_a^b f(x) dx,$   
with  $a < b$ .

$I$  is linear and positive, i.e.

$$f \geq 0 \Rightarrow I(f) \geq 0.$$

In the following we construct a positive linear functional  $\hat{I}: C([a,b]) \rightarrow \mathbb{R}$ ,  $f \mapsto \hat{I}(f)$  such that  $\hat{I}(f) - I(f)$  is "small".

Example: The trapezoidal rule.



We divide  $[a, b]$  into  $n$  intervals  $[t_{i-1}, t_i]$ ,  $i=1, \dots, n$ , with length  $h_i := t_i - t_{i-1}$  and

$$a = t_0 < t_1 < \dots < t_n = b.$$

We approximate  $I(f)$  by the sum

$$T^{(n)} := \sum_{i=1}^n T_i, \quad T_i = \frac{h_i}{2} (f(t_{i-1}) + f(t_i)).$$

Compare to the Riemann sums (upper and lower)

$$R_u^{(n)} = \sum_{i=1}^n h_i \min_{t \in [t_{i-1}, t_i]} f(t) \quad \text{and}$$

$$R_o^{(n)} = \sum_{i=1}^n h_i \max_{t \in [t_{i-1}, t_i]} f(t).$$

Then  $R_u^{(n)} \leq T^{(n)} \leq R_o^{(n)}$ , convergence  $\checkmark$  follows for  $f \in C([a,b])$  and  $n \rightarrow \infty$ .

Definition 1

We denote the sum

$$\tilde{I}(f) = (b-a) \sum_{i=0}^n \lambda_i f(t_i)$$

for computing an integral as quadrature formula.

With the nodes  $t_0, \dots, t_n$  and weights  $\lambda_0, \dots, \lambda_n$  such that  $\sum_{i=0}^n \lambda_i = 1$ .

Note that  $\tilde{I}$  positive  $\Leftrightarrow \lambda_i \geq 0 \quad \forall i=0, \dots, n$

2. Newton-Cotes formulas

We first replace  $f$  by an approximation  $\tilde{f}$  and see how to find  $\tilde{I}$ , such that

$$\tilde{I}(f) = I(\tilde{f}).$$

Given ~~for~~  $t_0, \dots, t_n$ , then we set the interpolation polynomial

$$\tilde{f}(t) := \sum_{i=0}^n f(t_i) L_{i,n}(t).$$

Where  $L_{i,n} \in \mathbb{P}_n$  is the  $i$ th Lagrange polynomial for the nodes  $t_j$ , i.e.  $L_{i,n}(t_j) = \delta_{ij}$

$$\left[ \mathbb{P}_n := \left\{ p: [a,b] \rightarrow \mathbb{R} : p(x) = \sum_{i=0}^n a_i x^i, a_i \in \mathbb{R} \quad \forall i=0, \dots, n \right\} \right.$$

Space of polynomials of order  $n$

Then it follows

$$\hat{I}(f) = (b-a) \sum_{i=0}^n \lambda_{i,n} f(t_i)$$

with

$$\lambda_{i,n} = \frac{1}{b-a} \int_a^b L_{i,n}(t) dt \quad \text{depending only on } t_0, \dots, t_n$$

### Lemma 2

Given <sup>n+1</sup> pairwise different nodes  $t_0, \dots, t_n$ , then there is exactly one quadrature formula

$$\hat{I}(f) = (b-a) \sum_{i=0}^n \lambda_i f(t_i) \quad (*)$$

that is exact for all polynomials  $p \in \mathbb{P}_n$

Proof:

For the Lagrange polynomials  $L_{i,n} \in \mathbb{P}_n$  given for the nodes  $t_i$  we have by definition

optional

$$I(L_{i,n}) = \hat{I}(L_{i,n}) = (b-a) \sum_{j=0}^n \lambda_{j,n} L_{i,n}(t_j)$$

$$(*) \Rightarrow \quad = (b-a) \sum_{j=0}^n \lambda_j \delta_{ij} = (b-a) \lambda_j$$

$$\Rightarrow \lambda_i = I(L_{i,n}) / (b-a) = \lambda_{i,n} \quad \square$$

## Comp. meth. Int. eq

For the special case of equidistant nodes,

$$h_i = h = \frac{b-a}{n}, \quad t_i = a + i \cdot h, \quad i = 0, \dots, n$$

we get the Newton-Cotes formulas,

The weight can be computed independent of the interval

by substituting  $s := \frac{t-a}{h}$  as follows

$$\lambda_{i,n} = \frac{1}{b-a} \int_a^b \prod_{\substack{j=0 \\ j \neq i}}^n \frac{t-t_j}{t_i-t_j} = \frac{1}{n} \int_0^n \prod_{\substack{j=0 \\ j \neq i}}^n \frac{s-j}{i-j} ds$$

We get the following common formulas

n	$\lambda_{0,n} \dots \lambda_{n,n}$	Error	Name
1	$\frac{1}{2} \quad \frac{1}{2}$	$\frac{h^3}{12} f''(\tau)$	Trapezoidal rule
2	$\frac{1}{6} \quad \frac{4}{6} \quad \frac{1}{6}$	$\frac{h^5}{90} f^{(4)}(\tau)$	Simpson's rule
3	$\frac{1}{8} \quad \frac{3}{8} \quad \frac{3}{8} \quad \frac{1}{8}$	$\frac{3h^5}{80} f^{(4)}(\tau)$	Simpson's 3/8 rule
4	$\frac{7}{90} \quad \frac{32}{90} \quad \frac{12}{90} \quad \frac{32}{90} \quad \frac{7}{90}$	$\frac{8h^7}{945} f^{(6)}(\tau)$	Boole's rule

optional

### 3. Gaussian quadrature (short)

compute  $I(f) := \int_a^b w(t) f(t) dt$  with a positive weight function  $w(t)$ .

We construct quadrature formula that is exact, i.e.

$$\hat{I}_n(f) = I(f), \text{ for } f \in \mathbb{P}_{2n+1}$$

$\Rightarrow$  nodes  $x_i$  need to be chosen specifically

Gauss-Legendre:  $w(x) = 1$

$$[a, b] = [-1, 1]$$

Chebyshev-Gauss:  $w(x) = \frac{1}{\sqrt{1-x^2}}$

$$\text{Interval: } (-1, 1)$$

Gauss-Hermite:  $w(x) = e^{-x^2}$

$$\text{Interval: } (-\infty, \infty)$$

The approximation error is generally given by

$$\int_a^b w f - \hat{I}_n(f) = \frac{f^{(2n+2)}(\xi)}{(2n+2)!} (P_{n+1}, P_{n+1})$$

$P_n$  is the monic orthogonal polynomial (associated with  $w$ ) of order  $n$ .

II The Nyström method

We want to solve the Fredholm integral equation of the second kind,

$$(1) \quad \lambda x(t) - \int_a^b K(t,s) x(s) ds = y(t), \quad t \in [a,b]$$

by ~~means~~ applying numerical quadrature.

Let  $K(t,s)$  be continuous for all  $t,s \in [a,b]$ .

First divide  $[a,b]$  into  $n$  intervals:

$$t_0 = a, t_1, \dots, t_n = b$$

$$a = t_0, t_1, \dots, t_n = b$$

$$s_0 = a, s_1, \dots, s_n = b$$

$$a = s_0, s_1, \dots, s_n = b$$

Then we discretize the integral in (1) and get

$$\lambda x(t) - \sum_{j=0}^n w_j K(t, s_j) x(s_j) = y(t)$$

Second we divide this into  $n+1$  equations for  $t_0, \dots, t_n$

$$(2) \Rightarrow \lambda x(t_i) - \sum_{j=0}^n w_j K(t_i, s_j) x(s_j) = y(t_i), \quad i=0, \dots, n$$

$\Rightarrow n+1$  linear equations for  $n+1$  unknown.

$$\text{Compute } \bar{X}_n = [x(t_0), x(t_1), \dots, x(t_n)]$$

Originally, this is understood as an interpolation.

Then define

Given a solution  $\bar{z}_n$  to (2), then define

$$z(t) = \frac{1}{\lambda} \left( y(t) + \sum_{j=0}^n w_j K(t, s_j) z_j \right),$$

with which is an interpolation formula at the node points  $t_j$

## 1. Convergence of the Nyström method

optional The error is governed by the integration error of the chosen quadrature formula and can be expressed

$$\text{as } \|(\mathcal{K} - \mathcal{K}_n)x\|_{\infty} = \max_{t \in [a, b]} \left| \int_a^b k(t, s) x(s) ds - \sum_{j=0}^n w_j k(t, s_j) x(s_j) \right|$$

### Examples

For the trapezoidal rule we have

$$(\mathcal{K} - \mathcal{K}_n)x(s) = -\frac{(b-a)^3}{12} \left( \frac{\partial^2 k(t, \xi) x(\xi)}{\partial s^2} \right)_{t=s}, \quad t \in [a, b]$$



## 2. Algorithmic implementation

We want to represent (1) as discrete matrix vector equation:

$$(3) \quad (\lambda I - \bar{K}) \bar{x} = \bar{y}, \quad \text{with } I \text{ the unit identity matrix.}$$

$$\text{and } \bar{K} \in \mathbb{R}^{(n+1) \times (n+1)}, \quad \bar{x} \in \mathbb{R}^{n+1}, \quad \bar{y} \in \mathbb{R}^{n+1}.$$

The main task is to build  $\bar{K}$  as follows.

- 1.) set value of  $n$
- 2.) Partition interval  $[a, b]$  into  $n$  intervals, compute  $w$ .
- 3.) for  $i = 0 : n$
- 4.) for  $j = 0 : n$
- 5.) set  $\bar{K}_{i+1, j+1} = K(t_i, s_j) \cdot w_j$
- 6.) ~~set  $x$~~  end
- 7.) set  $y_j = y(t_i)$
- 8.) end

And we are left to solve the matrix vector equation (3). In MATLAB by

$$\bar{x} = (\lambda I - \bar{K}) \backslash \bar{y}$$