## SOBOLEV SPACES. (spring 2016)

## **MODEL SOLUTIONS FOR SET 9**

**Exercise 1.** Consider maps  $f = (u, v, w) \in C^{\infty}(\mathbb{R}^3; \mathbb{R}^3)$  with differential matrix

$$Df(x) = \begin{pmatrix} u_x & u_y & u_z \\ v_x & v_y & v_z \\ w_x & w_y & w_z \end{pmatrix}$$

Show that the 2×2 minor  $L(Df) := \det \begin{pmatrix} v_y & v_z \\ w_y & w_z \end{pmatrix} = v_y w_z - v_z w_y$  is a null-Lagrangian.

**Solution 1.** It is sufficiently simple to compute the Euler-Lagrange equations for the expression  $L(Df) = v_y w_z - v_z w_y$ . We obtain that

$$\begin{aligned} -\nabla \cdot D_{P^1} L(Df) + D_{z^1} L(Df) &= 0 \\ -\nabla \cdot D_{P^2} L(Df) + D_{z^2} L(Df) &= -\nabla \cdot (0, w_z, -w_y) + 0 = -w_{zy} + w_{yz} = 0 \\ -\nabla \cdot D_{P^3} L(Df) + D_{z^3} L(Df) &= -\nabla \cdot (0, -v_z, v_y) + 0 = v_{zy} - v_{yz} = 0 \end{aligned}$$

There is no dependence of z (the variable in whose place you put the function f) in L(Df), so the derivatives  $D_{z^i}L(Df)$  vanish above. The expression  $D_{P^i}L(Df)$  denotes a gradient of the function

$$L(Df) = L \begin{pmatrix} u_x & u_y & u_z \\ v_x & v_y & v_z \\ w_x & w_y & w_z \end{pmatrix}$$

with respect to the variables on the row i. Since the Euler-Lagrange equations are always satisfied, L is a null Lagrangian.

**Exercise 2.** [Evans, Problem 8.7.7] Prove that  $L(P) := trace(P^2) - trace(P)^2$  is a null Lagrangian. Here the trace of an  $n \times n$  matrix  $A = (a_{i,j})_{i,j=1}^n$  is defined  $trace(A) = \sum_{j=1}^n a_{jj}$ .

**Solution 2.** Let us first expand the formula, denoting  $P = (p_{ij})$ :

$$\operatorname{tr}(P^2) - \operatorname{tr}(P)^2 = \sum_{i,j=1}^n p_{ij}p_{ji} - \left(\sum_{i=1}^n p_{ii}\right)^2 = \sum_{i,j=1}^n p_{ij}p_{ji} - p_{ii}p_{jj}$$

The expression  $p_{ij}p_{ji} - p_{ii}p_{jj}$  is a 2 × 2 subdeterminant of the matrix  $\begin{pmatrix} p_{ii} & p_{ij} \\ p_{ji} & p_{jj} \end{pmatrix}$  obtained from the matrix P by removing all rows and columns except i and j. It happens that

each of these subdeterminants is a null Lagrangian, much to the same reason as why the expression of Exercise 1 was one (in fact, subdeterminants are always null Lagrangians). To prove this, we compute the Euler-Lagrange equations for  $L_{ij} = p_{ij}p_{ji} - p_{ii}p_{jj}$  as

$$\begin{aligned} -\nabla \cdot D_{P^{k}} L_{ij}(Df) + D_{z^{k}} L_{ij}(Df) &= 0, \quad \text{when } k \neq i, j \\ -\nabla \cdot D_{P^{i}} L_{ij}(Df) + D_{z^{i}} L_{ij}(Df) &= -f_{z^{j}z^{i}}^{j} + f_{z^{i}z^{j}}^{j} = 0 \\ -\nabla \cdot D_{P^{j}} L_{ij}(Df) + D_{z^{j}} L_{ij}(Df) &= f_{z^{j}z^{i}}^{i} - f_{z^{i}z^{j}}^{i} = 0. \end{aligned}$$

**Exercise 3.** [Evans, Problem 8.7.4] Assume  $\eta : \mathbb{R}^n \to \mathbb{R}$  is  $C^1$ .

- (i) Show that  $L(P, z, x) := \eta(z) \det P$  is a null Lagrangian; here  $P \in \mathbb{M}^{n \times n}, z \in \mathbb{R}^n$ .
- (ii) Deduce that if  $f : \mathbb{R}^n \to \mathbb{R}^n$  is  $C^1$ , then

$$\int_{\Omega} \eta(f) \det(Df) dx$$

depends only on  $f_{|\partial\Omega}$ .

Solution 3. a) We compute again by Euler-Lagrange equations.

$$\begin{aligned} -\nabla_x \cdot D_{P^k} L(Df, f) &+ D_{z^k} L(Df, f) \\ &= -\nabla_x \cdot (\eta(f) D_{P^k} \det Df) + (D_{z^k} \eta)(f) \det Df \\ &= -\eta(f) \nabla_x \cdot D_{P^k} \det Df - \nabla_x \eta(f) \cdot D_{P^k} \det Df + (D_{z^k} \eta)(f) \det Df \end{aligned}$$

The first term is just  $\eta(f)$  times the Euler-Lagrange equation for the Jacobian det Df. The Jacobian is known to be a null Lagrangian, so we do not repeat the proof here. One may compute

$$\nabla_x \eta(f) = \left(\sum_{j=1}^n \eta_{z^j}(f) f_i^j\right)_{i=1}^n$$

We use the cofactor expansion for the determinant with row k:

$$\det Df = \sum_{i=1}^{n} (-1)^{i+k} f_i^k M_{ki},$$

where  $M_{ki}$  denotes the determinant of the matrix we get by removing row k and column i from Df. Thus

$$D_{P^k} \det Df = \left( (-1)^{i+k} M_{ki} \right)_{i=1}^n$$

This finally gives

$$-\nabla_x \eta(f) \cdot D_{P^k} \det Df = -\sum_{i=1}^n \sum_{j=1}^n \eta_{z^j}(f) f_i^j (-1)^{i+k} M_{ki}$$

Note that the term in the above sum with j = k is exactly  $(D_{z^k}\eta)(f) \det Df$ , which cancels out the similar term in the Euler-Lagrange equation. The rest is equal to

$$-\sum_{j \neq k} \eta_{z^{j}}(f) \sum_{i=1}^{n} f_{i}^{j}(-1)^{i+k} M_{ki}$$

We now expand each subdeterminant  $(cof Df)_{ki}$  with respect to the *j*th row, which gives

$$(\cot Df)_{ki} = \sum_{l \neq i} (-1)^{l+j} (-1)^{\chi(l>i) + \chi(j>k)} f_l^j M_{ki,jl},$$

where  $M_{ki,jl}$  denotes the determinant of the matrix we get by removing rows k and j and columns i and l from Df. Here also  $\chi(a > b)$  is equal to 1 if a > b and 0 otherwise. The factor  $(-1)^{\chi(l>i)+\chi(j>k)}$  comes from the fact that when we remove row k and column i, we have to swap all the  $\pm$ -signs that come after. Thus what remains of the Euler-Lagrange equation reads

$$-\sum_{j\neq k}\eta_{z^{j}}(f)\sum_{i=1}^{n}\sum_{l\neq i}(-1)^{i+k+l+j}(-1)^{\chi_{(l>i)}+\chi_{(j>k)}}f_{l}^{j}f_{i}^{j}M_{ki,jl}$$

Obviously  $M_{ki,jl} = M_{kl,ji}$ . But this means that in the last two sums, the terms (i, l) and (l, i) cancel each other out because of the factor  $(-1)^{\chi(l>i)}$ . This shows that the whole expression is zero, and hence that L is a null Lagrangian.

b) Follows from the alternate characterization of null Lagrangians, and the fact that the above computation may be generalized to  $f \in C^1$  in the weak sense.

**Exercise 4.** [Evans, Problem 8.7.5] If  $f : \mathbb{R}^n \to \mathbb{R}^n$  is as in Problem 3, fix  $x_0 \notin f(\partial\Omega)$ . If r is so small that  $B(x_0, r) \cap f(\partial\Omega) = \emptyset$ , choose a  $C^1$ -map  $\eta$  so that  $\int_{\mathbb{R}^n} \eta(z) dz = 1$  and  $\eta(x) = 0$  when  $|x - x_0| \ge r$ .

Define

$$deg(f, x_0) = \int_{\Omega} \eta(f) \det(Df) dx,$$

the *degree* of f relative to  $x_0$ . Prove that the degree is an integer.

Solution 4. Solution will be added a bit later.

**Exercise 5.** In geometric function theory one studies the *distortion* of a map  $f : \mathbb{R}^2 \to \mathbb{R}^2$ . Writing f = (u, v) and assuming that the Jacobian  $\det(Df(x)) > 0$  is positive almost everywhere, the distortion is defined by

$$K(f) := \frac{|\partial_x u|^2 + |\partial_y u|^2 + |\partial_x v|^2 + |\partial_y v|^2}{\det(Df)}$$

Show that the functional L(Df) := K(f) is polyconvex; do this by first showing that  $F(x, y) = x^2/y$  is convex on  $(0, \infty) \times (0, \infty)$ .

[Hint: You need to show that  $F(x, y) - F(a, b) \ge 2ab^{-1}(x - a) - ab^{-2}(y - b)$ ]

**Note**. In higher dimensions the distortion of a map  $f : \mathbb{R}^n \to \mathbb{R}^n$  is defined by

$$K(f) := \frac{\left[\sum_{j,k=1}^{n} |\partial_{x_j} f^k|^2\right]^{n/2}}{\det(Df)}$$

so that K(tf) = K(f) for all  $t \in \mathbb{R}$ . Also in higher dimensions the distortion is polyconvex, but the algebra to prove this is a little more difficult.

**Solution 5.** Let us first show that  $F(x, y) = x^2/y$  is convex as a function of two real variables. Let 0 < t < 1. We want to prove that

$$F(tx + (1 - t)a, ty + (1 - t)b) \le tF(x, y) + (1 - t)F(a, b)$$

This reduces to

$$\Leftrightarrow \quad \frac{t^2 x^2 + 2t(1-t)ax + (1-t)^2 a^2}{ty + (1-t)b} \leq \frac{tx^2}{y} + \frac{(1-t)a^2}{b} \\ \Leftrightarrow \quad t^2 x^2 yb + 2t(1-t)axyb + (1-t)^2 a^2 yb \leq (ty + (1-t)b)(tx^2b + (1-t)a^2y) \\ \Leftrightarrow \quad 2t(1-t)axyb \leq t(1-t)(x^2b^2 + a^2y^2) \\ \Leftrightarrow \quad 0 \leq t(1-t)(xb - ay)^2.$$

Thus our expression is convex. Now let us consider the distortion as a function

$$K(P,r) = \frac{p_{11}^2 + p_{12}^2 + p_{21}^2 + p_{22}^2}{r} = \frac{|P|^2}{r}.$$

Here  $|P| = (p_{11}^2 + p_{12}^2 + p_{21}^2 + p_{22}^2)^{1/2}$ , and we remark that  $|P|^2$  is a convex function of the matrix P because the function  $f(x) = x^2$  is convex as well. Then if 0 < t < 1,

$$\begin{split} K(tP_1 + (1-t)P_2, tr_1 + (1-t)r_2) &= \frac{|tP_1 + (1-t)P_2|^2}{tr_1 + (1-t)r_2} \\ &\leq \frac{t|P_1|^2 + (1-t)|P_2|^2}{tr_1 + (1-t)r_2} \\ &\leq \frac{t|P_1|^2}{r_1} + \frac{(1-t)|P_2|^2}{r_2} \\ &= tK(P_1, r_1) + (1-t)K(P_2, r_2) \end{split}$$

This proves the polyconvexity.