

**ADAPTIVE DYNAMICS**  
**EXERCISE 1 – 4**

**Introduction:**

Each of the following exercises gives the population dynamics of a  $k$ -morphic resident population with strategies  $x_1, \dots, x_k \in \mathbb{X}$  and corresponding population densities  $n_1, \dots, n_k \in \mathbb{R}_+$ . For each of these exercises you are asked to do the following:

- (a) Give an ecological interpretation of the model.  
 (b) Rewrite the dynamics in the form

$$\begin{cases} \dot{n}_i = r(x_i, E)n_i & \forall i \in \{1, \dots, k\} \\ E = H_k(x_1, \dots, x_k, n_1, \dots, n_k) \end{cases}$$

or

$$\begin{cases} \dot{n}_i = r(x_i, E)n_i & \forall i \in \{1, \dots, k\} \\ \dot{E} = H_k(x_1, \dots, x_k, n_1, \dots, n_k, E) \end{cases}$$

- (c) Give the invasion fitness  $s_E(y)$  and determine the essential dimension of the environment. What is the maximum number of different resident strategies that can generically coexist in a log-bounded manner.  
 (d) Give an expression of the invasion fitness (or fitness proxy) explicitly in terms of the resident strategies if the resident environment is saturated (i.e., give  $s_{\mathbf{x}}(y)$ , or  $\tilde{s}_{\mathbf{x}}(y)$  for its proxy, where  $\mathbf{x}$  is a vector of coexisting resident strategies).  
 (e) Is there an optimisation principle, i.e., is there a function of the environment that is minimised or maximised by the strategy dynamics? What is it?

**Exercise 1:**

$$\begin{cases} \dot{S} = \lambda(N)S - \mu S - S \sum_j \beta(x_j)I_j \\ \dot{I}_i = S\beta(x_i)I_i - \mu I_i - \alpha(x_i)I_i \end{cases}$$

for  $i \in \{1, \dots, k\}$  and with  $N = S + \sum_j I_j$ .

**Exercise 2:**

$$\begin{cases} \dot{S} = \lambda N - \mu(N)S - S \sum_j \beta(x_j)I_j \\ \dot{I}_i = S\beta(x_i)I_i - \mu(N)I_i - \alpha(x_i)I_i \end{cases}$$

for  $i \in \{1, \dots, k\}$  and with  $N = S + \sum_j I_j$ .

**Exercise 3:**

$$\begin{cases} \dot{N}_i = \alpha(x_i)N_i \left(1 - \frac{\sum_j N_j}{K}\right) - \frac{\beta(x_i)N_i}{1 + \sum_j T(x_j)\beta(x_j)N_j} P \\ \dot{P} = P \left(\sum_i \frac{\beta(x_i)N_i}{1 + \sum_j T(x_j)\beta(x_j)N_j}\right) - \delta P \end{cases}$$

for  $i \in \{1, \dots, k\}$ . Does it matter for the strategy dynamics what the dynamics of  $P$  precisely looks like? Why not, or why and how?

**Exercise 4:**

$$\dot{n}_i = \alpha(x_i)n_i - \delta(x_i)n_i - \gamma \sum_j \left( \frac{x_i}{x_i + x_j} n_i n_j \right)$$

for  $i \in \{1, \dots, k\}$ .