

Differential Equations II

Exercise 4

3.4. 2014 (16-18 o'clock in CK111)

1. Compute the derivative $\bar{x}'(t)$, when the functions $\bar{x}(t)$ are defined by

$$(i) \bar{x}(t) = (e^{-2t}, te^t)^T, \quad (ii) \bar{x}(t) = (1, e^t \cos t, e^t \sin t)^T.$$

2. Verify that $(\bar{x}^1(t), \bar{x}^2(t))$, where $\bar{x}^1(t) = e^{7t}(2, 1)^T$ and $\bar{x}^2(t) = e^{-5t}(-2, 1)^T$, forms a fundamental system of solutions of the homogeneous system

$$\bar{x}'(t) = \begin{pmatrix} 1 & 12 \\ 3 & 1 \end{pmatrix} \bar{x}(t).$$

3. Verify that $(\bar{x}^1(t), \bar{x}^2(t), \bar{x}^3(t))$ forms a fundamental system of solutions of

$$\bar{x}'(t) = \begin{pmatrix} 1 & -1 & 0 \\ 1 & 2 & 1 \\ -2 & 1 & -1 \end{pmatrix} \bar{x}(t),$$

where $\bar{x}^1(t) = e^t(1, 0, -1)^T$, $\bar{x}^2(t) = e^{2t}(1, -1, -1)^T$ and $\bar{x}^3(t) = e^{-t}(1, 2, -7)^T$.

4. Let $\bar{u} = (u_1, \dots, u_n)^T \in \mathbf{R}^n$ be a given non-zero vector. Determine if the vector functions

$$(i) \bar{x}(t) = t\bar{u}, \quad t \in \mathbf{R}, \quad (ii) \bar{x}(t) = \log(t)\bar{u}, \quad t \in (0, \infty),$$

can be a solution of a system $\bar{x}'(t) = A\bar{x}(t)$ of differential equations for some $n \times n$ -matrix $A = (a_{ij}) \in \mathbf{R}^{n \times n}$ having constant coefficients.

5. Let $\alpha > 0$, $\beta > 0$ be constants. The system

$$\begin{aligned} x_1'(t) &= -\alpha x_2(t) \\ x_2'(t) &= -\beta x_1(t) \end{aligned}$$

describes the amount of bacteria $x_1(t)$ and $x_2(t)$ at time $t \geq 0$ in a population where the species of bacteria consume each other without any regeneration. Compute $\frac{x_1(0)}{x_2(0)}$ when it is known that $x_1(t) > 0$ and $x_2(t) > 0$ for all $t \geq 0$.

6. Let $\bar{x}(t)$ be a solution of the homogeneous linear system

$$\bar{x}'(t) = A(t)\bar{x}(t)$$

in the open interval $I \subset \mathbf{R}$, where $A(t) = (a_{ij}(t)) \in \mathbf{R}^{n \times n}$. Show: if $\bar{x}(t_0) \neq \bar{0}$ for some $t_0 \in I$, then $\bar{x}(t) \neq \bar{0}$ for all $t \in I$. *Suggestion:* use the uniqueness theorem for linear systems.