

Intro2 in nutshell

Using posterior distribution $\pi(\theta|\text{data})$:

- Summarizes current uncertainty about unknown quantities θ , given observed (hence fixed) data.
- Can be approximated by histogram of simulated sample $\theta_1, \dots, \theta_n$.
- Likewise, posterior mean is approximated as the average $\Sigma\theta_i/n$.
- Posterior mean of any function $g(\theta)$ is approximated as $\Sigma g(\theta_i)/n$.

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- Can be used to compute **$P(H_0 \mid \text{data})$** , when H_0 is expressed as a function of θ . From simulated posterior distribution:
$$P(H_0 \mid \text{data}) \approx (\# \text{ iterations } H_0(\theta_i) \text{ is true})/n.$$
- Bayesian **Credible Intervals** (CI) for summaries of the uncertainty width. From simulated posterior: sort the sample $\theta_1, \dots, \theta_n$, take 2.5% of the smallest values, 2.5% of the largest values out, to get 95% credible interval. For HPD interval, you need to sort with respect to posterior density values $\pi(\theta_1 \mid \text{data}), \dots, \pi(\theta_n \mid \text{data})$ and take out 5% of the smallest.
- **Posterior predictive distributions.** From simulated posterior, generate predicted observation X_i from $\pi(X_i \mid \theta_i)$ for each θ_i .

Intro2 in nutshell

- Monte Carlo simulations: iid samples from the target density.
 - Efficient if every sample is drawn from the target density.
 - Rejection samplers: iid sampling, but only some draws are accepted.
- MCMC simulations: dependent samples from the target density. Need to check convergence.
 - If full conditionals can be solved \rightarrow Gibbs, every draw is accepted in 'alternating sampling'.
 - More generally: MH-algorithm with proposal density, but acceptance rate should not be too high, nor too low.
 - Single site updating vs. block updating.