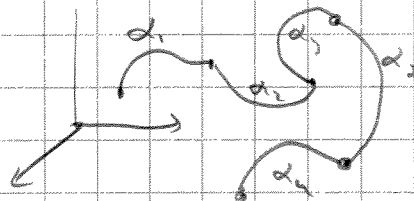


Chain complexes

11

Motivation

Suppose $\omega \in C^0(\Gamma^1(\mathbb{R}^n))$
and $\alpha_i: [0,1] \rightarrow \mathbb{R}^n$ C^1 -paths s.t. $\alpha_i(1) = \alpha_{i+1}(0)$.



$$\text{Then } \int_{\alpha_1 \times \alpha_2 \times \alpha_3 \times \alpha_4} \omega = \sum_{i=1}^4 \int_{\alpha_i} \omega.$$

Similarly, if $\tau \in C^0(\Gamma^2(\mathbb{R}^n))$
and $\sigma_i: [0,1]^2 \rightarrow \mathbb{R}^n$



$$\text{We have } \sum_{i=1}^4 \int_{\sigma_i} \tau := \sum_{i=1}^4 \int_{[0,1]^2} \sigma_i^* \tau.$$

Q: What is the counterpart for $\alpha_1 \times \dots \times \alpha_n$?



Side remark:

Suppose $\alpha_1 \times \alpha_2$ then

$$\int_{\alpha_1 \times \alpha_2} \omega = \int_{\alpha_1 \times \alpha_2} \omega$$

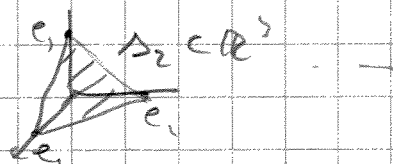
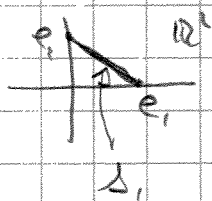
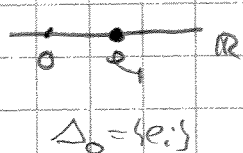
$\Rightarrow$ order of concatenation does not really matter

$$\Rightarrow \text{Wea. } \int_{\alpha_1 \times \alpha_2 \times \alpha_3 \times \alpha_4} \omega = \sum_{i=1}^4 \int_{\alpha_i} \omega$$

Singular simplices

Def: The standard k -simplex is

$$\Delta_k = \left\{ \sum_{i=1}^{k+1} t_i e_i : 0 \leq t_i \leq 1, \sum_{i=1}^{k+1} t_i = 1 \right\} \subset \mathbb{R}^{k+1}$$



(in top space X)

Def: A singular k -simplex is a continuous map $\sigma : \Delta_k \rightarrow X$.

Def: An affine k -simplex in $U \subset \mathbb{R}^n$ is

$$\sigma : \Delta_k \rightarrow U$$

s.t. σ is affine ($\sigma(tx + (1-t)y) = t\sigma(x) + (1-t)\sigma(y)$)

Def: A C^1 -smooth k -simplex (in $U \subset \mathbb{R}^n$) is

$$\sigma : \Delta_k \rightarrow U$$

s.t. σ is C^1 -smooth.

Notations $\sigma : \Delta_k \rightarrow \mathbb{R}^n$ affine is also denoted.

$$[v_1, \dots, v_k] : \Delta_k \rightarrow \mathbb{R}^n \text{ where}$$

$$v_i = \sigma(e_i) \quad \text{Then } [v_1, \dots, v_k] \left(\sum_{i=1}^{k+1} t_i e_i \right) = \sum_{i=1}^{k+1} t_i v_i$$

Notation: Denote $S_k(X) = \{ \sigma : \Delta_k \rightarrow X : \sigma \text{ cont.} \}$ $k \geq 0$

Convention: $S_{-1}(X) = \emptyset = S_k(X) \quad \forall k < 0$

Chains:

Def: The space of k -chains in X is

$$C_k(X) = \mathbb{F}_Z(S_k(X)) = \text{span}_{\mathbb{Z}} \{ \chi_{\sigma} : \sigma \in S_k(X) \}$$

(the free $\mathbb{Z}$ -module over $S_k(X)$)

Rule: Elements of $C_k(X)$ are finite sums

$$\sum_{i=1}^m a_i \chi_{\sigma_i} \quad \text{where } a_i \in \mathbb{Z} \text{ and } \sigma_i \in S_k(X)$$

- $C_k(X)$ is an abelian group in $\mathbb{R}^{S_k(X)}$
- $C_{-1}(X) = \{0\} = C_k(X) \quad \forall k < 0$
- We denote (as every body)

$$\sum_{i=1}^m a_i \chi_{\sigma_i} =: \sum_{i=1}^m a_i \sigma_i$$

- Note: $\sigma_i \in S_k(\mathbb{R}^d) : \sigma_0 + \sigma_1 = \chi_{\sigma_0} + \chi_{\sigma_1} \neq \chi_{\{\sigma_0 + \sigma_1\}}$
 $\uparrow \qquad \qquad \qquad \uparrow$
in $C_k(\mathbb{R}^d)$ $\qquad \qquad \qquad$ in $\mathbb{R}^d$

Def: Given $\sigma \in S_k(\mathbb{R}^d)$ and $\tau \in S_l(\mathbb{R}^d)$, we define

$$\sigma \circ \tau = \sum_{\sigma' \in S_{k+l}} \langle \sigma, \tau, \sigma' \rangle \chi_{\sigma'}$$

where $\langle \sigma, \tau, \sigma' \rangle$

Ex: Take $\sigma = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$ and $\tau = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$ where $\sigma, \tau \in S_2(\mathbb{R}^2)$

Then $\sigma \circ \tau = \sum_{\sigma' \in S_4} \langle \sigma, \tau, \sigma' \rangle \chi_{\sigma'}$

Chain complex

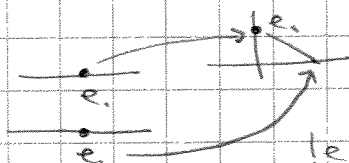
41

The boundary operator

Def: We call the map $[e_1, \dots, \hat{e}_i, \dots, e_k] : \Delta_{k-1} \rightarrow \Delta_k$ as the i th face of Δ_k .

Ex: $k=1$: $i=1$: $[e_2]$

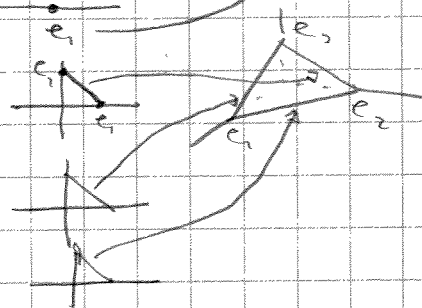
$i=2$: $[e_1]$



$k=2$: $i=1$: $[e_1, e_3]$

$i=2$: $[e_1, e_2]$

$i=3$: $[e_2, e_3]$



Def: The boundary operator

$$\partial : C_k(X) \rightarrow C_{k-1}(X)$$

is the homomorphism

$$\partial(\sigma) = \sum_{i=1}^k (-1)^{i-1} \sigma \circ [e_1, \dots, \hat{e}_i, \dots, e_k]$$

$$\sigma = \sum a_i \sigma_i \Rightarrow$$

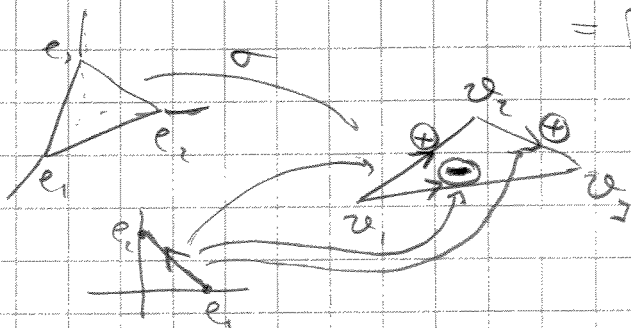
$$\sigma \circ f = \sum a_i (\sigma_i \circ f)$$

Ex: $k=2$: $\partial[v_1, v_2, v_3] = [v_1, v_2, v_3] \circ [e_2, e_3]$

$$- [v_1, v_2, v_3] \circ [e_1, e_3]$$

$$+ [v_1, v_2, v_3] \circ [e_1, e_2]$$

$$= [v_2, v_3] - [v_1, v_3] + [v_1, v_2]$$



Lemma: Let $f : X \rightarrow Y$ continuous map. The

$$f_* : C_k(X) \rightarrow C_k(Y)$$

$$f_* \left(\sum a_i \sigma_i \right) = \sum a_i f_* \sigma_i$$

is a homomorphism.

Pf: Note that $\sigma_i = X_{\{f(\sigma_i)\}}$ and $f_* \sigma_i = X_{\{f(\sigma_i)\}} \in C_k(Y)$ $\square$

Lemma: $\partial \circ f_\sigma = f_\sigma \circ \partial$

Pf: Suffices to show $\partial f_\sigma \sigma = f_\sigma \partial \sigma$ for $\sigma \in S_k(X)$.
Since $f_\sigma \sigma = f \circ \sigma$, we have that

$$\begin{aligned} \partial f_\sigma \sigma &= \partial (f \circ \sigma) = \sum_{i=1}^k (-1)^{i-1} (f \circ \sigma) \circ [e_1, \dots, \hat{e}_i, \dots, e_{k+1}] \\ &= \sum_{i=1}^k (-1)^{i-1} f \circ (\sigma \circ [e_1, \dots, \hat{e}_i, \dots, e_{k+1}]) \\ &= f_\sigma \left(\sum_{i=1}^k (-1)^{i-1} \sigma \circ [e_1, \dots, \hat{e}_i, \dots, e_{k+1}] \right) \\ &= f_\sigma \partial \sigma. \quad \square \end{aligned}$$

Lemma: $\partial \circ \partial = 0$

Pf: Since ∂ is a homomorphism, suffices to show $\partial^2 \sigma = 0$ for $\sigma \in S_k(X)$. Since $\sigma = \sigma_X [e_1, \dots, e_{k+1}]$,

$$\partial^2 \sigma = \sigma_X \partial^2 [e_1, \dots, e_{k+1}]$$

For $k=0,1$, $\partial^2 [e_1, \dots, e_{k+1}] = 0$. (Then $\partial^2 \sigma = 0$ for $\sigma \in S_k(X)$ $k=0,1$)
Suppose that holds for $k-1$. Then

$$\begin{aligned} \partial^2 [e_1, \dots, e_{k+1}] &= \partial \left(\sum_{i=1}^{k+1} (-1)^{i-1} \overbrace{[e_1, \dots, e_{k+1}]}^{\text{id}} \circ [e_1, \dots, \hat{e}_i, \dots, e_{k+1}] \right) \\ &= \partial \left(\sum_{i=1}^{k+1} (-1)^{i-1} [e_1, \dots, \hat{e}_i, \dots, e_{k+1}] \right) \\ &= \partial \left(\sum_{i=1}^{k+1} (-1)^{i-1} [e_1, \dots, e_i, e_i, \dots, e_{k+1}] \right) \\ &= \sum_{i=1}^{k+1} (-1)^{i-1} \left(\sum_{j=1}^{i-1} (-1)^{j-1} [e_1, \dots, \hat{e}_j, \dots, \hat{e}_i, \dots, e_{k+1}] \right. \\ &\quad \left. + \sum_{j=i}^k (-1)^{j-1} [e_1, \dots, \hat{e}_i, \dots, \hat{e}_{j+1}, \dots, e_{k+1}] \right) \\ &= \sum_{j < i} (-1)^{i+j} [e_1, \dots, \hat{e}_j, \dots, \hat{e}_i, \dots, e_{k+1}] \\ &\quad + \sum_{j > i} (-1)^{i+j} [e_1, \dots, \hat{e}_i, \dots, \hat{e}_{j+1}, \dots, e_{k+1}] = 0 \\ &= \sum_{j < i} (-1)^{i+j-1} [e_1, \dots, \hat{e}_i, \dots, \hat{e}_j, \dots, e_{k+1}] \quad \square \end{aligned}$$

Integration of forms over chains

Q: How to define $\int_{\sigma} \omega$ when ω is a k -form in $U \subset \mathbb{R}^n$ and $\sigma: \Delta_k \rightarrow U$ a k -simplex (or more generally a chain)?

Approach 1: If there exists a neighborhood W of Δ_k and a C^1 -extension of σ to $\tilde{\sigma}: V \rightarrow U$ then $\sigma^* \omega$ is a continuous k -form on V . Then

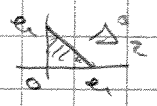
$$\int_{\Delta_k} \sigma^* \omega = \int_{(P_k, \xi_k)} X_{\Delta_k} \sigma^* \omega$$

is well defined, where $P_k = e_1 + \text{span}\{e_2 - e_1, \dots, e_{k+1} - e_1\} = e_1 + W_k$

is the affine k -plane containing Δ_k , and ξ_k is the orientation $\xi_k = (e_2 - e_1) \wedge \dots \wedge (e_{k+1} - e_1)$.

Approach 2: Let $\Delta_k^0 = \{(x_1, \dots, x_k) \in \mathbb{R}^k : 0 \leq x_j \leq 1, \sum x_j \leq 1\}$

Orient $\mathbb{R}^k$ with $e_1 \wedge \dots \wedge e_k$



Take $p_k: \Delta_k^0 \rightarrow \Delta_k$ the affine map

$$p_k(0) = e_1, \quad p_k(e_i) = e_{i+1}$$

$$\text{i.e. } p_k(x_1, \dots, x_k) = e_1 + \sum_{j=1}^k x_j (e_{j+1} - e_1)$$

Then the linear part of p_k is $(p_k)_0(x) = p_k(x) - p_k(0)$

$$\text{Thus } (p_k)_* e_1 \wedge \dots \wedge e_k = (e_2 - e_1) \wedge \dots \wedge (e_{k+1} - e_1) = \left[\sum_{j=1}^k x_j (e_{j+1} - e_1) \right]$$

Hence p_k is orientation preserving

Let $\omega \in C^0(\Gamma^k(U))$ and $\sigma \in S_k(U)$

so that $\sigma \circ p_k: \Delta_k^0 \rightarrow U$ is continuous and

C^1 -smooth in the interior of $\Delta_k^0 \subset \mathbb{R}^k$

We define

$$\int_{\sigma} \omega = \int_{\Delta_k^0} (\sigma \circ p_k)^* \omega$$

Rule: Under assumption of ①, we have

$$\int_{P_k} \chi_{\Delta_k} \sigma^* \omega = \int_{\Delta_k^0} p_k^* (\sigma^* \omega) = \int_{\Delta_k^0} (\sigma \circ p_k)^* \omega.$$

Conclusion: For the purpose of integration,
consider maps $\Delta_k^0 \rightarrow U$
instead of $\Delta_k \rightarrow U$.

To formulate Stokes's theorem, we need chains
and boundary operation for maps $\Delta_k^0 \rightarrow U$.

Whole theory can
be developed:

$$\begin{aligned} \tilde{S}_k(U) &= \{ \sigma : \Delta_k^0 \rightarrow U : \sigma \text{ cont} \} \\ \tilde{C}_k(U) &= \left\{ \sum_{i=1}^m a_i \tilde{\sigma}_i : a_i \in \mathbb{R}, \tilde{\sigma}_i \in \tilde{S}_k(U) \right\} \subset \mathbb{R}^{\tilde{S}_k(U)} \end{aligned}$$

$$\begin{aligned} \text{Denote } \tilde{p}_k : C_k(U) &\rightarrow \tilde{C}_k(U) \\ \tilde{p}_k \left(\sum_{i=1}^m a_i \sigma_i \right) &= \sum_{i=1}^m a_i (\sigma_i \circ p_k). \end{aligned}$$

$$\begin{aligned} \text{and } \tilde{p}_k^{-1} : \tilde{C}_k(U) &\rightarrow C_k(U) \\ \tilde{p}_k^{-1} \left(\sum_{i=1}^m a_i \tilde{\sigma}_i \right) &= \sum_{i=1}^m a_i \tilde{\sigma}_i \circ \tilde{p}_k^{-1} \end{aligned}$$

$$\begin{aligned} \text{Define } \tilde{\partial}_k : \tilde{C}_k(U) &\rightarrow \tilde{C}_{k-1}(U) \text{ by} \\ \tilde{\partial}_k \tilde{\sigma} &= \tilde{p}_{k-1} \partial_k \tilde{p}_k^{-1} \tilde{\sigma}. \end{aligned}$$

$$\begin{aligned} \text{Then } \tilde{\partial}_{k-1} \circ \tilde{\partial}_k &= \tilde{p}_{k-2} \partial_{k-1} \tilde{p}_{k-1}^{-1} \tilde{p}_{k-1} \partial_k \tilde{p}_k^{-1} \\ &= \tilde{p}_{k-2} \partial^2 \tilde{p}_k^{-1} = 0. \end{aligned}$$

$$\text{We define } \int_{\tilde{\sigma}} \omega = \int_{\Delta_k^0} \tilde{\sigma}^* \omega \quad (U)$$

for $\omega \in C^0(\Gamma^k(U))$, $\tilde{\sigma} \in \tilde{S}_k(U)$ C-smooth.

We do not pursue this direction.

Then:
"Another
Stokes'
Theorem"

Suppose $\omega \in C^1(\Gamma^0(U))$ and $\sigma \in \Sigma_k(U)$ has a C^1 -extension to a neighborhood of Δ_k . Then

$$\int_{\sigma} d\omega = \int_{\partial\sigma} \omega$$

Pf. Denote another extension of $g_k: \Delta_k^0 \rightarrow \Delta_k$ to a neighborhood of Δ_k^0 also by g_k .

Step 1:
$$\int_{\sigma} d\omega = \int_{\Delta_k} \sigma^* d\omega = \int_{\Delta_k^0} g_k^* \sigma^* d\omega = \int_{\Delta_k^0} d(g_k^* \sigma^* \omega)$$

$$\int_{\partial\sigma} \omega = \sum_{i=1}^{k+1} (-1)^{i-1} \int_{\sigma \circ [e_1, \dots, \hat{e}_i, \dots, e_{k+1}]} \omega = \sum_{i=1}^{k+1} (-1)^{i-1} \int_{\Delta_{k-1}^0} g_{k-1}^* [e_1, \dots, \hat{e}_i, \dots, e_{k+1}]^* \sigma^* \omega$$

$$\int_{\Delta_{k-1}^0} g_{k-1}^* [e_1, \dots, \hat{e}_i, \dots, e_{k+1}]^* \sigma^* \omega$$

$$= \int_{\Delta_{k-1}^0} g_{k-1}^* [e_1, \dots, \hat{e}_i, \dots, e_{k+1}]^* (g_k^{-1})^* g_k^* \sigma^* \omega$$

Step 2: We observe that
$$g_{k-1}^* [e_1, \dots, \hat{e}_i, \dots, e_{k+1}]^* \sigma^* \omega = g_{k-1}^* [e_1, \dots, \hat{e}_i, \dots, e_{k+1}]^* (g_k^{-1})^* g_k^* \sigma^* \omega$$

$$\begin{aligned} \text{Then } \sum_{i=1}^{k+1} (-1)^{i-1} \int_{\Delta_{k-1}^0} g_{k-1}^* [e_1, \dots, \hat{e}_i, \dots, e_{k+1}]^* \sigma^* \omega \\ = \sum_{i=1}^{k+1} (-1)^{i-1} \int_{\Delta_{k-1}^0} g_{k-1}^* [e_1, \dots, \hat{e}_i, \dots, e_{k+1}]^* (g_k^{-1})^* g_k^* \sigma^* \omega \end{aligned}$$

We denote $F_i: \Delta_{k-1}^0 \rightarrow \Delta_k^0$ the map

$$F_i = g_k^{-1} \circ [e_1, \dots, \hat{e}_i, \dots, e_{k+1}] \circ g_{k-1}$$

$$\text{Then } \int_{\sigma} d\omega = \sum_{i=1}^{k+1} (-1)^{i-1} \int_{\Delta_{k-1}^0} F_i^* g_k^* \sigma^* \omega$$

$$\begin{aligned} \text{Moreover, } F_i(x_1, \dots, x_{k-1}) &= g_k^{-1} [e_1, \dots, \hat{e}_i, \dots, e_{k+1}] (e_1 + \sum_{j=1}^k x_j (e_{j+1} - e_j)) \\ \text{for } i > 1 &= g_k^{-1} [e_1, \dots, \hat{e}_i, \dots, e_{k+1}] \left((1 - \sum_{j=1}^{i-1} x_j) e_1 + \sum_{j=1}^i x_j e_j \right) \\ &= g_k^{-1} \left((1 - \sum_{j=1}^{i-1} x_j) e_1 + \sum_{j=1}^{i-1} x_j e_j + \sum_{j=i}^k x_j e_{j+1} \right) \end{aligned}$$

Since $p_k^{-1} = [0, e_1, \dots, e_k] : \Delta_k \rightarrow \Delta_k^0$

$$\begin{aligned} & \text{(check: } [0, e_1, \dots, e_{k-1}] \circ p_k (x_1, \dots, x_k) \\ &= [0, e_1, \dots, e_{k-1}] \left((1 - \sum_{j=1}^k x_j) e_1 + \sum_{j=2}^{k+1} x_{j-1} e_j \right) \\ &= \sum_{j=2}^{k+1} x_{j-1} e_{j-1} = \sum_{j=1}^k x_j e_j = (x_1, \dots, x_k) \end{aligned}$$

we have

$$\begin{aligned} F_i(x_1, \dots, x_{k-1}) &= [0, e_1, e_2, \dots, e_k] \left((1 - \sum_{j=1}^k x_j) e_1 + \sum_{j=2}^{k+1} x_{j-1} e_j + \sum_{j=1}^k x_j e_j \right) \\ &= \sum_{j=2}^{k+1} x_{j-1} e_{j-1} + \sum_{j=1}^k x_{j-1} e_j \\ &= (x_1, \dots, x_{i-2}, \underbrace{0}_{(i-1)\text{th}}, x_{i-1}, \dots, x_{k-1}) \end{aligned}$$

Thus $F_i^*(dy_1, \dots, dy_2, \dots, dy_k)$

$$= \begin{cases} dx_1, \dots, dx_{k-1} & \text{if } l = i-1 \\ 0, & \text{otherwise.} \end{cases}$$

for $i > 1$.

$$\begin{aligned} \text{If } i=1, \quad F_1(x_1, \dots, x_{k-1}) &= p_k^{-1} [e_2, \dots, e_k] p_k (x_1, \dots, x_{k-1}) \\ &= p_k^{-1} [e_2, \dots, e_k] \left((1 - \sum_{j=1}^{k-1} x_j) e_1 + \sum_{j=2}^k x_{j-1} e_j \right) \\ &= p_k^{-1} \left((1 - \sum_{j=1}^{k-1} x_j) e_2 + \sum_{j=2}^k x_{j-1} e_{j+1} \right) \\ &= [0, e_1, \dots, e_k] \left((1 - \sum_{j=1}^{k-1} x_j) e_2 + \sum_{j=2}^{k+1} x_{j-2} e_j \right) \\ &= (1 - \sum_{j=1}^{k-1} x_j) e_1 + \sum_{j=2}^{k+1} x_{j-2} e_{j-1} \\ &= (1 - \sum_{j=1}^{k-1} x_j) e_1 + \sum_{j=2}^k x_{j-1} e_j \\ &= \left((1 - \sum_{j=1}^{k-1} x_j), x_1, x_2, \dots, x_{k-1} \right) \end{aligned}$$

Thus $F_1^*(dy_1, \dots, dy_2, \dots, dy_k)$

$$= \begin{cases} dx_1, \dots, dx_{k-1}, & l=1 \\ -\sum_{j=1}^{k-1} dx_j \wedge dx_1, \dots, \widehat{dx_2}, \dots, dx_{k-1} & l>1 \end{cases}$$

$$\begin{aligned}
 \text{Thus } F_i^* (dy_1 \wedge \dots \wedge \widehat{dy_i} \wedge \dots \wedge dy_k) \\
 &= \begin{cases} dx_1 \wedge \dots \wedge dx_{k-1}, & i=1 \\ (-1)^{k-1} dx_1 \wedge \dots \wedge dx_{k-1}, & i \geq 2. \end{cases} \\
 &= (-1)^{k-1} dx_1 \wedge \dots \wedge dx_{k-1}
 \end{aligned}$$

Step 3: Let $p_k^* \sigma^* \omega = \sum_{l=1}^k f_l dy_1 \wedge \dots \wedge \widehat{dy_l} \wedge \dots \wedge dy_k$

Then

$$\begin{aligned}
 \int_{\partial \sigma} \omega &= \sum_{i=1}^{k+1} (-1)^{i-1} \int_{\Delta_{k+1}^0} F_i^* p_k^* \sigma^* \omega \\
 &= \sum_{i=1}^{k+1} (-1)^{i-1} \int_{\Delta_{k+1}^0} F_i^* \left(\sum_{l=1}^k f_l dy_1 \wedge \dots \wedge \widehat{dy_l} \wedge \dots \wedge dy_k \right) \\
 &= \int_{\Delta_{k+1}^0} F_i^* \left(\sum_{l=1}^k f_l dy_1 \wedge \dots \wedge \widehat{dy_l} \wedge \dots \wedge dy_k \right) \\
 &\quad + \sum_{i=2}^{k+1} (-1)^{i-1} \int_{\Delta_{k+1}^0} F_i^* \left(\sum_{l=1}^k f_l dy_1 \wedge \dots \wedge \widehat{dy_l} \wedge \dots \wedge dy_k \right) \\
 &\quad \begin{matrix} l=i-1 \text{ missing} \\ \Rightarrow i=l+1 \text{ missing} \end{matrix} \\
 &= \sum_{l=1}^k (-1)^{l-1} \int_{\Delta_{k+1}^0} f_l \circ F_1 dx_1 \wedge \dots \wedge dx_{k-1} \\
 &\quad + \sum_{l=1}^k (-1)^l \int_{\Delta_{k+1}^0} f_l \circ F_{l+1} dx_1 \wedge \dots \wedge dx_{k-1} \\
 &= \sum_{l=1}^k (-1)^{l-1} \int_{\Delta_{k+1}^0} (f_l \circ F_1 - f_l \circ F_{l+1}) dx_1 \wedge \dots \wedge dx_{k-1}
 \end{aligned}$$

Step 4:

$$\begin{aligned}
 & (-1)^{l-1} \int_{\Delta_{l-1}^0} (f_l \circ F_l - f_l \circ F_{l+1}) dx_1, \dots, dx_{l-1} \\
 &= (-1)^{l-1} \int_{\Delta_{l-1}^0} \left(f_l \left(1 - \sum_{j=1}^{l-1} x_j, x_1, \dots, x_{l-1} \right) - f_l \left(x_1, \dots, x_{l-1}, \underbrace{0}_{\substack{\uparrow \\ l\text{'s}}} \right) \right) dx_1, \dots, dx_{l-1} \\
 &\stackrel{\text{Change of variables}}{=} (-1)^{l-1} \int_{\Delta_{l-1}^0} \left(f_l \left(x_1, \dots, x_{l-1}, 1 - \sum_{j=1}^{l-1} x_j \right) - f_l \left(x_1, \dots, x_{l-1}, 0 \right) \right) dx_1, \dots, dx_{l-1} \\
 &= (-1)^{l-1} \int_{\Delta_{l-1}^0} \left(\int_0^{1 - \sum_{j=1}^{l-1} x_j} \frac{\partial f_l}{\partial x_l} (x_1, \dots, x_{l-1}, t, x_l, \dots, x_{l-1}) dt \right) dx_1, \dots, dx_{l-1} \\
 &= (-1)^{l-1} \int_{\Delta_{l-1}^0} \frac{\partial f_l}{\partial x_l} dx_1, \dots, dx_{l-1} = \int_{\Delta_l^0} d(f_l dx_1, \dots, dx_{l-1})
 \end{aligned}$$

$$\begin{aligned}
 \text{Hence } \int_{\sigma} \omega &= \sum_{l=1}^k (-1)^{l-1} \int_{\Delta_{l-1}^0} (f_l \circ F_l - f_l \circ F_{l+1}) dx_1, \dots, dx_{l-1} \\
 &= \sum_{l=1}^k \int_{\Delta_l^0} d(f_l dx_1, \dots, dx_{l-1}) = \int_{\Delta_k^0} d f_k^* \sigma^* \omega \\
 &= \int_{\Delta_k^0} f_k^* \sigma^* d\omega = \int_{\sigma} d\omega
 \end{aligned}$$

Corollary Suppose ω closed k -form, σ a k -cycle, τ a $(k+1)$ -form and γ $(k+1)$ -chain. Then

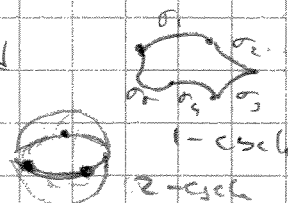
$$\int_{\sigma + d\tau} \omega = \int_{\sigma} \omega$$

$$\begin{aligned}
 \text{Pf: } \int_{\sigma + d\tau} \omega &= \int_{\sigma} \omega + \int_{d\tau} \omega + \int_{\sigma} d\tau + \int_{d\tau} d\tau \\
 &= \int_{\sigma} \omega + \int_{\tau} d\omega + \int_{d\tau} \tau + \int_{\tau} d^2\tau = \int_{\sigma} \omega \quad \square
 \end{aligned}$$

Let X be a top space

Def: $Z_k(X) = \{ \sigma \in C_k(X) : \partial \sigma = 0 \} = \ker(\partial: C_k \rightarrow C_{k-1})$
 $B_k(X) = \{ \partial \sigma \in C_k(X) : \sigma \in C_{k+1}(X) \} = \text{Im}(\partial: C_{k+1} \rightarrow C_k)$

Elements in $Z_k(X)$ are called k -cycles and elements in $B_k(X)$ k -boundaries.



If $X \subset \mathbb{R}^n$ open (or a manifold) we define

Def: $Z_k^\infty(X) = \{ \sigma \in Z_k(X) : \sigma \circ \rho_k \text{ is } C^\infty\text{-smooth} \}$
 and $B_k^\infty(X) = \{ \partial \sigma \in B_k(X) : \sigma \circ \rho_k \text{ is } C^\infty\text{-smooth} \}$

Since $\partial^2 = 0$, $B_k(X) \subset Z_k(X)$ for all k ,
 we define the homology of the complex $(C_k(X))_{k \geq 0}$ by

$$H_k(X) = Z_k(X) / B_k(X)$$

If $U \subset \mathbb{R}^n$ open (or a manifold) we define

$$H_k^\infty(U) = Z_k^\infty(U) / B_k^\infty(U)$$

In this case we also define the k^{th} de Rham cohomology of

$$H_{\text{dR}}^k(U) = \frac{\ker \{ d: \Omega^k(U) \rightarrow \Omega^{k+1}(U) \}}{\text{Im } \{ d: \Omega^k(U) \rightarrow \Omega^{k+1}(U) \}} \quad (= \frac{\{ \text{closed } k\text{-forms} \}}{\{ \text{exact } k\text{-forms} \}})$$

Then $H_{\text{dR}}^k(U)$ is a vector space and we have a reformulation of the previous conditions

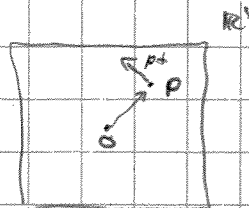
Cor: The pairing $Z_k^\infty(X) \times \Omega_{\text{closed}}^k(X) \rightarrow \mathbb{R}$
 $(\sigma, \omega) \mapsto \int_\sigma \omega$
 descends to a pairing

$$H_k^\infty(X) \times H_{\text{dR}}^k(X) \rightarrow \mathbb{R}$$

$$([\sigma], [\omega]) \mapsto \int_\sigma \omega$$

Example: $H^1(\mathbb{R}^2 \setminus \{0\}) \neq 0$ (- Exercise 1.1)

Take $\omega_p(v) = \langle v, \frac{p^\perp}{|p|^2} \rangle$



where $p^\perp = (p_1, p_2)^\perp = (-p_2, p_1)$

i.e. $\langle p^\perp, p \rangle = -p_2 \cdot p_1 - p_1 \cdot p_2 = 0$.

$$\begin{aligned} \text{Then } \omega_x(v) &= \frac{1}{|x|^2} \langle v, x^\perp \rangle = \frac{1}{|x|^2} (v_1 \cdot (-x_2) + v_2 x_1) \\ &= \frac{1}{|x|^2} (x_1 dx_2(v) - x_2 dx_1(v)) \\ &= \left(\frac{x_1}{|x|^2} dx_2 - \frac{x_2}{|x|^2} dx_1 \right)(v). \end{aligned}$$

Moreover, $d\omega = d\left(\frac{x_1}{|x|^2} dx_2 - \frac{x_2}{|x|^2} dx_1\right)$

$$\begin{aligned} &= \frac{1}{|x|^2} dx_1 \wedge dx_2 - 2 \frac{x_1^2}{|x|^4} dx_1 \wedge dx_2 \\ &\quad - \frac{1}{|x|^2} dx_2 \wedge dx_1 + 2 \frac{x_2^2}{|x|^4} dx_2 \wedge dx_1 \end{aligned}$$

$$= \frac{2}{|x|^2} dx_1 \wedge dx_2 - 2 \frac{x_1^2 + x_2^2}{|x|^4} dx_1 \wedge dx_2$$

$$= \frac{2}{|x|^2} dx_1 \wedge dx_2 - \frac{2}{|x|^2} dx_1 \wedge dx_2 = 0$$

$$\begin{aligned} d\left(\frac{1}{|x|^2}\right) &= d((x_1^2 + x_2^2)^{-1}) \\ &= (-1)(x_1^2 + x_2^2)^{-2} \\ &\quad \cdot (2x_1 dx_1 + 2x_2 dx_2) \\ &= -2 \frac{x_1}{|x|^4} dx_1 - 2 \frac{x_2}{|x|^4} dx_2 \end{aligned}$$

Then ω is closed.

Let $\gamma: [0,1] \rightarrow \mathbb{R}^2$ $\gamma(t) = (\cos 2\pi t, \sin 2\pi t)$

Then $\sigma: \Delta_1 \rightarrow \mathbb{R}^2$ $\sigma(t, s, t) = \gamma(t)$ is a 1-chain

and $\partial\sigma = \sigma(e_2) - \sigma(e_0) = \gamma(1) - \gamma(0) = (1,0) - (1,0) = 0$.

Thus σ is a cycle.

$$\begin{aligned} \text{Since } \int_{\sigma} \omega &= \int_{\sigma} \omega = \int_{[0,1]} \gamma^* \omega = \int_{[0,1]} \omega_{\gamma(t)}(\gamma'(t)) dt \\ &\quad \uparrow \text{check!} \quad \uparrow \text{check!} \\ &= \int_{[0,1]} 2\pi \langle (-\sin 2\pi t, \cos 2\pi t), (-\sin 2\pi t, \cos 2\pi t) \rangle dt \\ &= \int_{[0,1]} 2\pi dt = 2\pi \neq 0 \end{aligned}$$