

Ex 1

If  $V$  is a vector space, then  $V$  has a basis (Hamel basis)  $(e_x)_{x \in X}$  where  $X$  is some index set. So any element  $v \in V$  can be written as

$$v = \sum_{x \in X} \alpha_x e_x$$

where  $\alpha_x$  is non-zero for only finitely many  $x \in X$ . Therefore each  $V$  can be seen as a subspace of function space (more accurately isomorphic to a subspace of a function space).

(a) For  $f \in K^X, g \in K^Y$ , we set  $(f \otimes g)(x, y) = f(x)g(y)$  and  $V \otimes W = \text{span} \{f \otimes g : f \in V, g \in W\}$ .

Let  $(f_i)_{i \in I} \subset V$  and  $(g_j)_{j \in J} \subset W$  be linearly indep. collections. Let  $\alpha_{ij} \in K \quad \forall i \in I, j \in J$  be such that

$$\sum_{\substack{i \in I \\ j \in J}} \alpha_{ij} f_i \otimes g_j = 0 \quad \text{and} \quad \alpha_{ij} \neq 0 \text{ for only finitely many } i \text{ and } j$$

$$\Rightarrow 0 = \left( \sum_{\substack{i \in I \\ j \in J}} \alpha_{ij} f_i \otimes g_j \right)(x, y) = \sum_{\substack{i \in I \\ j \in J}} \alpha_{ij} f_i(x) g_j(y)$$

$$= \sum_{i \in I} \left[ \sum_{j \in J} \alpha_{ij} g_j(y) \right] f_i(x) \quad \forall x \in X, \forall y \in Y$$

If we consider this for fixed  $y$  as a function of  $x$ , then by independence of  $(f_i)_{i \in I}$

$$\Rightarrow \sum_{j \in J} \alpha_{ij} g_j(y) = 0 \quad \forall i, \forall y$$

$$\Rightarrow \alpha_{ij} = 0 \quad \forall i, \forall j$$

Therefore  $(f_i \otimes g_j)_{i \in I, j \in J}$  is linearly independent.

$$(b) \quad V = \text{span} \{ (f_i)_{i \in I} \}, \quad W = \text{span} \{ (g_j)_{j \in J} \}$$

If  $h \in V \otimes W$ , then exist  $\tilde{f}_k \in V$  and  $\tilde{g}_k \in W$   
 $k=1, 2, \dots, n$  for some  $n$  such that

$$h = \sum_{k=1}^n \tilde{f}_k \otimes \tilde{g}_k$$

Now we can write  $\tilde{f}_k = \sum_{i \in I} c_{ki} f_i$ ,  $\tilde{g}_k = \sum_{j \in J} d_{kj} g_j$   
 where  $c_{ki} \in K$  and  $d_{kj} \in K$  are non-zero only for finitely many indices.

$$\Rightarrow h(x, y) = \sum_{k=1}^n \tilde{f}_k(x) \tilde{g}_k(y) = \sum_{k=1}^n \left[ \sum_{i \in I} c_{ki} f_i(x) \right] \left[ \sum_{j \in J} d_{kj} g_j(y) \right]$$

$$= \sum_{k=1}^n \sum_{i \in I} \sum_{j \in J} c_{ki} d_{kj} f_i(x) g_j(y)$$

$$= \sum_{\substack{i \in I \\ j \in J}} \left[ \sum_{k=1}^n c_{ki} d_{kj} \right] f_i(x) g_j(y)$$

Therefore any  $h \in V \otimes W$  can be written as (finite) linear combination of  $(f_i \otimes g_j)_{i \in I, j \in J}$ .

(c) Basis = linearly independent subset which spans the vector space  
 (a), (b)  $\Rightarrow (f_i \otimes g_j)$  is a basis if  $(f_i)$  and  $(g_j)$  are.

Let  $\phi(f, g) = f \otimes g$  which is a bilinear map from  $V \times W$  to  $V \otimes W$ . If  $\beta: V \times W \rightarrow U$  is bilinear, then set

$\beta_{ij} = \beta(f_i, g_j) \in U$  and define linear  $\tilde{\beta}: V \otimes W \rightarrow U$  by

$\tilde{\beta}(f_i \otimes g_j) = \beta_{ij}$  and by linear extension. Then

$$\text{if } f = \sum_i c_i f_i, \quad g = \sum_j d_j g_j$$

$$\beta(f, g) = \sum_{i,j} c_i d_j \beta(f_i, g_j) = \sum_{i,j} c_i d_j \tilde{\beta}(f_i \otimes g_j)$$

$$= \tilde{\beta} \left( \left( \sum_i c_i f_i \right) \otimes \left( \sum_j d_j g_j \right) \right) = \tilde{\beta}(\phi(f, g))$$

## Ex 2

(a) Clearly  $v \mapsto \varphi(v)w$  is a linear map from  $V$  to  $W$  and hence defines an element of  $\text{Hom}(V, W)$ .

Since  $(w, \varphi) \mapsto \varphi(\cdot)w$  is bilinear from  $W \times V^*$  to  $\text{Hom}(V, W)$ , it defines a linear map from  $W \otimes V^*$  to  $\text{Hom}(V, W)$  by the universal property of tensor product.

If this map is not injective, then  $\exists h \in W \otimes V^*$   
 $h = \sum_{i=1}^r w_i \otimes \varphi_i$ , where  $r = \text{rank}(h)$ , such that  $h$  is mapped on  $0 \in \text{Hom}(V, W)$ .

$$\Rightarrow 0 = \sum_{i=1}^r \varphi_i(v) w_i \quad \forall v \in V$$

By a lemma from the lectures,  $(w_i)$  is linearly independent.  $\Rightarrow \varphi_i(v) = 0 \quad \forall v \Rightarrow h = 0$

Hence the above map is injective.

(b) When  $V$  and  $W$  are finite dimensional, then the vector spaces  $W \otimes V^*$  and  $\text{Hom}(V, W)$  are finite dimensional. Hence it is enough to note that dimensions of these spaces are equal. Namely,  $\dim(W \otimes V^*) = \dim(W) \dim(V^*) = \dim(W) \dim(V)$  by Ex 1 and by  $V \cong V^*$  and  $\dim(\text{Hom}(V, W)) = \dim(V) \dim(W)$ , which can be assumed to be known from linear algebra. Hence the mapping in (a) is a bijection.

Let  $h = \sum_{i=1}^r w_i \otimes \varphi_i$ , where  $r = \text{rank}(h)$ . Since  $(\varphi_i)_{i=1}^r$  are linearly independent, we can choose a basis  $(e_j)_{j=1}^{\dim(V)}$  for  $V$  so that  $\varphi_i(e_j) = \delta_{ij}$  for  $1 \leq i \leq r$  and  $1 \leq j \leq \dim(V)$ . Then for any  $v = \sum_{j=1}^{\dim(V)} c_j e_j$ ,

$$\sum_{i=1}^r \varphi_i(v) w_i = \sum_{i=1}^r c_i w_i$$

Therefore if  $A_h \in \text{Hom}(V, W)$  is the image of  $h$  under the mapping of (a), then  $\text{Im}(A_h) = \text{span}(\{w_i\}_{i=1}^r)$ . Since  $\{w_i\}$  are lin. ind.,  $\text{rank}(A_h) = \dim(\text{Im}(A_h)) = r$ .

c) Recall that  $g \cdot (v \otimes w) = (g \cdot v) \otimes (g \cdot w)$  and  $(g \cdot \varphi)(v) = \varphi(g^{-1} \cdot v)$  for any  $g \in G, v \in V, w \in W, \varphi \in V^*$ .

In the mapping of (a),  $g \cdot (w \otimes \varphi) = (g \cdot w) \otimes (g \cdot \varphi)$  is mapped to  $v \mapsto (g \cdot \varphi)(v) g \cdot w = \varphi(g^{-1} \cdot v) g \cdot w$  which agrees with the other definition of representation on  $\text{Hom}(V, W)$ :  $g \cdot T = \rho_2(g) \circ T \circ \rho_1(g^{-1})$  where  $T \in \text{Hom}(V, W)$  and  $\rho_1: G \rightarrow GL(V), \rho_2: G \rightarrow GL(W)$ .

### Ex 3

(a)  $G$  abelian. Let  $g \in G$ . Since  $gg' = g'g$  for any  $g' \in G$ , for any representation  $\rho: G \rightarrow GL(V)$   $\rho(g)$  is a  $G$ -module map. By Schur's lemma, in irreducible representation  $\rho(g) = \lambda(g) \text{id}$  for some  $\lambda(g) \in \mathbb{C}$ .  
Now also by irreducibility  $\dim(V) = 1$ .

(b)  $C_n$  cyclic group of order  $n$ .  $C^n = e$

$C_n$  is abelian  $\Rightarrow$  irreducible representations are one-dimensional, i.e.  $\rho(g) \in \mathbb{C}$  and  $\rho(g)^n = 1$ .

# Ex 4

If  $V, V', W, W'$  are vector spaces and  $A: V \rightarrow W$  and  $B: V' \rightarrow W'$  are linear mappings, then  $(A \otimes B)(v \otimes w) \stackrel{d}{=} (Av) \otimes (Bw)$  defines a linear mapping  $V \otimes V' \rightarrow W \otimes W'$ . Suppose for simplicity that  $V = V' = W = W' = \mathbb{C}^2$  and write  $A$  and  $B$  as matrices then in the basis  $(e_1 \otimes e_1, e_1 \otimes e_2, e_2 \otimes e_1, e_2 \otimes e_2)$  the matrix

$$A \otimes B = \begin{pmatrix} A_{11} B & A_{12} B \\ A_{21} B & A_{22} B \end{pmatrix}$$

[Kronecker product of matrices]

Either by above or direct calculation using  $g.(v \otimes v') = (g.v) \otimes (g.v')$

$$\rho(r) = \begin{bmatrix} & & & 1 \\ & & -1 & \\ & -1 & & \\ 1 & & & \end{bmatrix}, \quad \rho(m) = \begin{bmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & 1 \end{bmatrix}$$

Where  $\rho: D_4 \rightarrow GL(V \otimes V)$  is the tensor representation and the matrices are written in the basis  $(e_1 \otimes e_1, e_1 \otimes e_2, e_2 \otimes e_1, e_2 \otimes e_2)$ . For example

$$r.(e_1 \otimes e_1) = (r.e_1) \otimes (r.e_1) = e_2 \otimes e_2$$

$$m.(e_1 \otimes e_1) = (m.e_1) \otimes (m.e_1) = (-e_1) \otimes (-e_1) = e_1 \otimes e_1$$

$$\text{Let } \begin{cases} v_1 = e_1 \otimes e_1 + e_2 \otimes e_2 \\ v_2 = e_1 \otimes e_1 - e_2 \otimes e_2 \\ v_3 = e_1 \otimes e_2 + e_2 \otimes e_1 \\ v_4 = e_1 \otimes e_2 - e_2 \otimes e_1 \end{cases}$$

Then

$$\left\{ \begin{array}{l} r.v_1 = v_1, \quad m.v_1 = v_1 \quad \text{i.e. } r=1, m=1 \\ r.v_2 = -v_2, \quad m.v_2 = v_2 \quad \text{i.e. } r=-1, m=1 \\ r.v_3 = -v_3, \quad m.v_3 = -v_3 \quad \text{i.e. } r=-1, m=-1 \\ r.v_4 = v_4, \quad m.v_4 = -v_4 \quad \text{i.e. } r=1, m=-1 \end{array} \right.$$