

# 1 Introduction

These notes follow chapter 6 of [2].

## 2 Stopping time

**Definition 2.1** (*Stopping time*). A random variable

$$\tau: \Omega \rightarrow [0, \infty]$$

is called a stopping time with respect to a filtration of  $\sigma$ -algebras  $\{\mathcal{F}_t | t \geq 0\}$  provided

$$\{\tau \leq t\} \in \mathcal{F}_t \quad \text{for all } t \geq 0$$

In other words, the set of all  $\omega \in \Omega$   $\tau(\omega) \leq t$  is  $\mathcal{F}_t$ -measurable. The stopping time  $\tau$  is allowed to take on the value  $+\infty$ , and also that any constant  $\tau = t_0$  is a stopping time. Furthermore it enjoys the following properties

**Proposition 2.1** (*Properties of a stopping time*). Let  $\tau_1$  and  $\tau_2$  stopping times with respect to  $\{\mathcal{F}_t | t \geq 0\}$ . Then

i  $\{\tau < t\} \in \mathcal{F}_t$  and  $\{\tau = t\} \in \mathcal{F}_t$  for all  $t \geq 0$

ii  $\tau_1 \wedge \tau_2$  and  $\tau_1 \vee \tau_2$  are stopping times

*Proof.* We set

$$\{\tau < t\} = \bigcup_{k=1}^{\infty} \left\{ \tau \leq t - \frac{1}{k} \right\}$$

i.e.  $\{\tau < t\}$  occurs if there exists a  $k \geq 1$  such that the event  $\{\tau \leq t - 1/k\}$  occurs. But

$$\{\tau \leq t - 1/k\} \in \mathcal{F}_{t - \frac{1}{k}} \subseteq \mathcal{F}_t$$

Similarly

$$\{\tau_1 \wedge \tau_2 \leq t\} = \{\tau_1 \leq t\} \cup \{\tau_2 \leq t\} \in \mathcal{F}_t$$

and

$$\{\tau_1 \vee \tau_2 \leq t\} = \{\tau_1 \leq t\} \cap \{\tau_2 \leq t\} \in \mathcal{F}_t$$

□

The following theorem evinces the relevance of stopping times for the study of stochastic differential equations

**Theorem 2.1** (*Set hitting by a diffusion*). Let  $\xi_t$  solution of the stochastic differential equation

$$d\xi_t = \mathbf{b}(\xi_t, t) dt + \sigma[dw_t]$$

$$\xi_{t_0} = \mathbf{x}_0$$


satisfying the hypotheses of the theorem of existence and uniqueness. Let also  $\mathbb{A}$  be a non-empty open or closed subset of  $\mathbb{R}^d$ . Then

$$\tau := \inf \{t | \xi_t \in \mathbb{A}\}$$

is a stopping time with the convention  $\tau = \infty$  if  $\xi_t \notin \mathbb{A}$  for all  $t$ .

*Proof.* Let  $t \geq 0$  we need to show that  $\{\tau \leq t\} \in \mathcal{F}_t$ . To that goal we introduce the sequence  $\{t_i\}_{i=1}^\infty$  dense on  $\mathbb{R}_+$  and consider separately the cases when  $\mathbb{A}$  is close and open.

- $\mathbb{A}$  is **open**. The event that there exists a  $t_i$  less than  $t$  such that  $\xi_{t_i}$  belongs to  $\mathbb{A}$  reads

$$\{\tau \leq t\} = \bigcup_{t_i \leq t} \{\xi_{t_i} \in \mathbb{A}\}$$


and is therefore the union of events belonging to  $\mathcal{F}_t$ , thus proving the claim.

- $\mathbb{A}$  is **closed**. Let

$$d(\mathbf{x}, \mathbb{A}) := \text{distance}(\mathbf{x}, \mathbb{A})$$

and define the open sets

$$\mathbb{A}_n = \left\{ \mathbf{x} \mid d(\mathbf{x}, \mathbb{A}) < \frac{1}{n} \right\}$$

The event

$$\{\tau \leq t\} = \bigcap_{k=1}^\infty \bigcup_{t_i \leq t} \{\xi_{t_i} \in \mathbb{A}_k\}$$

also belongs to  $\mathcal{F}_t$  as the  $\{\xi_{t_i} \in \mathbb{A}_k\}$ 's do.

□

**Remark 2.1.** The random variable

$$\tilde{\tau} = \sup \{t \mid \xi_t \in \mathbb{A}\}$$

is not in general a stopping time as in general it is not  $\mathcal{F}_t$  measurable but may depend on the history of  $\xi$  for times later than  $t$ .

### 3 Applications of the stopping time

Let  $\phi_t$  be the fundamental solution of the stochastic differential equation

$$d\xi_t^i = b^i(\xi_t, t) dt + \sigma^{ij}(\xi_t, t) dw_t^j \quad (3.1)$$

which we assume to globally satisfy the hypotheses of the theorem existence and uniqueness of solutions. In other words for any initial data  $(\mathbf{x}_o, t_o)$  we have that

$$\xi_t = \phi_t(\mathbf{x}_o, t_o)$$

for  $t \geq t_o$  solves (3.1). To (3.1) also we associate the generator

$$\mathfrak{L}_x := \mathbf{b}(\mathbf{x}, t) \cdot \partial_x + \frac{1}{2} g^{ij}(\mathbf{x}, t) \partial_{x^i} \partial_{x^j}$$

with

$$g^{ij} = \sigma^{ik} \sigma^{jk}$$

### 3.1 Exit time form a domain

Let  $\mathbb{A}$  a smooth bounded open subset of  $\mathbb{R}^d$ . Let us suppose that the drift and diffusion fields in (3.1) are **time-independent**

$$\mathbf{b}(\mathbf{x}, t) = \mathbf{b}(\mathbf{x}) \quad \& \quad \boldsymbol{\sigma}(\mathbf{x}, t) = \boldsymbol{\sigma}(\mathbf{x})$$

and let  $\mathbf{x} \in \mathbb{R}^d$ . Then the stopping time

$$\tau_{\mathbf{x}} = \inf \{t \geq 0 | \phi_t(\mathbf{x}, 0) \in \partial\mathbb{A}\} \quad (3.2)$$

specifies the first exit time from  $\mathbb{A}$ .

**Proposition 3.1 (Average exit time).** *Under the above hypotheses, for any  $\mathbf{x} \in \mathbb{A}$  we have*

$$\langle \tau_{\mathbf{x}} \rangle = f(\mathbf{x})$$

for

$$\mathfrak{L}_{\mathbf{x}} f(\mathbf{x}) = -1$$

$$f(\mathbf{x})|_{\mathbf{x} \in \mathbb{A}} = 0$$

More generally for we have

$$\langle \tau_{\mathbf{x}}^n \rangle = g_n(\mathbf{x})$$

for  $g_0(\mathbf{x}) = 1$

$$\mathfrak{L}_{\mathbf{x}} g_n(\mathbf{x}) = -n g_{n-1}(\mathbf{x})$$

$$g_n(\mathbf{x})|_{\mathbf{x} \in \mathbb{A}} = 0$$

*Proof.* Let

$$f(\phi_{\tau_{\mathbf{x}}}) = f(\mathbf{x}) + \int_0^{\tau_{\mathbf{x}}} ds \mathfrak{L}_{\phi_s} f(\phi_s) + \int_0^{\tau_{\mathbf{x}}} dw_s^j \sigma^{ij}(\phi_s) \partial_{\phi_s^i} f(\phi_s)$$

if

$$\mathfrak{L}_{\phi_s} f(\phi_s) = -1$$

and

$$f(\mathbf{x})|_{\mathbf{x} \in \mathbb{A}} = 0$$

we have

$$\tau_{\mathbf{x}} = f(\mathbf{x}) + \int_0^{\tau_{\mathbf{x}}} dw_s^j \sigma^{ij}(\phi_s) \partial_{\phi_s^i} f(\phi_s)$$

Taking averages yields the claim. More generally for any  $t \leq \tau_{\mathbf{x}}$

$$g_n(\phi_t) = - \int_t^{\tau_{\mathbf{x}}} ds \mathfrak{L}_{\phi_s} g_n(\phi_s) - \int_t^{\tau_{\mathbf{x}}} dw_s^j \sigma^{ij}(\phi_s) \partial_{\phi_s^i} g_n(\phi_s)$$

$$\mathfrak{L}_{\mathbf{x}} g_n(\mathbf{x}) = -n g_{n-1}(\mathbf{x})$$

$$g_{n-1}(\mathbf{x})|_{\mathbf{x} \in \partial \mathbb{A}} = 0$$

generates the recursion for

$$g_n(\phi_0) = g_n(\mathbf{x})$$

whence

$$\begin{aligned} g_n(\mathbf{x}) &= n \int_0^{\tau_{\mathbf{x}}} ds \int_s^{\tau_{\mathbf{x}}} ds_1 \mathfrak{L}_{\phi_{s_1}} g_{n-1}(\phi_{s_1}) \\ &\quad + n \int_0^{\tau_{\mathbf{x}}} ds \int_s^{\tau_{\mathbf{x}}} dw_{s_1} \sigma^{ij}(\phi_{s_1}) \partial_{\phi_{s_1}^i} g_{n-1}(\phi_{s_1}) - \int_0^{\tau_{\mathbf{x}}} dw_s^j \sigma^{ij}(\phi_s) \partial_{\phi_s^i} g_n(\phi_s) \end{aligned}$$

Upon iterating  $n$ -times, we get into

$$\begin{aligned} g_n(\mathbf{x}) &= \Gamma(n+1) \int_0^{\tau_{\mathbf{x}}} ds_1 \prod_{k=1}^{l-2} \int_{s_k}^{\tau_{\mathbf{x}}} ds_{k+1} \int_{s_{n-1}}^{\tau_{\mathbf{x}}} ds_n \\ &\quad - \sum_{l=1}^n \frac{\Gamma(n+1)}{\Gamma(n-l+1)} \int_0^{\tau_{\mathbf{x}}} ds \prod_{k=1}^{l-2} \int_0^{s_k} ds_{k+1} \int_{s_{l-1}}^{\tau_{\mathbf{x}}} dw_{s_l} \sigma^{ij}(\phi_{s_l}) \partial_{\phi_{s_l}^i} g_{n-l}(\phi_{s_l}) - \int_0^{\tau_{\mathbf{x}}} dw_s^j \sigma^{ij}(\phi_s) \partial_{\phi_s^i} g_n(\phi_s) \end{aligned}$$

Taking the average we get into

$$\langle \tau_{\mathbf{x}}^n \rangle = g_n(\mathbf{x})$$

whence the claim.  $\square$

In order to encompass the time-inhomogeneous case, we can compute the statistics of the first exit time from an open subset of  $\mathbb{R}^d$  starting from the forward Kolmogorov equation (Fokker-Planck equation). Consider for any  $\mathbf{x}_o \in \mathbb{A}$  the problem with *absorbing boundary conditions*

$$\partial_t p + \partial_{x^i} (b^i p) = \frac{1}{2} \partial_{x^i} \partial_{x^j} (g^{ij} p) \quad (3.6a)$$

$$p|_{\mathbf{x} \in \partial \mathbb{A}} = 0 \quad (3.6b)$$

$$\lim_{t \downarrow t_o} p = \delta^{(d)}(\mathbf{x} - \mathbf{x}_o) \quad (3.6c)$$

The interpretation of absorbing boundary conditions is of removing from the transition probability all those trajectories that for times  $s \in [t_o, t]$  reached the boundary. Thus if we define

$$\tau_{\mathbf{x}, t} = \inf_{t_1} \{t \leq t_1 | \phi_{t_1}(\mathbf{x}, t) \in \partial \mathbb{A}\} \quad (3.7)$$

we get into

$$P(\tau_{\mathbf{x}_o, t_o} \geq t) = \int_{\mathbb{A}} d^d x p_{\xi}(\mathbf{x}, t | \mathbf{x}_o, t_o)$$

whence we infer

$$p_{\tau_{\mathbf{x}_o, t_o}}(t) = -\partial_t \int_{\mathbb{A}} d^d x p_{\xi}(\mathbf{x}, t | \mathbf{x}_o, t_o)$$

It follows immediately that

$$\prec (\tau_{\mathbf{x}_o, t_o} - t_o)^n \succ = \int_{t_o}^{\infty} dt (t - t_o)^n p_{\tau_{\mathbf{x}_o, t_o}}(t) = - \int_0^{\infty} dt t^n \partial_t \int_{\mathbb{A}} d^d x p_{\xi}(\mathbf{x}, t + t_o | \mathbf{x}_o, t_o)$$

and therefore

$$\prec (\tau_{\mathbf{x}_o} - t_o)^n \succ = n \int_0^{\infty} dt t^{n-1} \int_{\mathbb{A}} d^d x p_{\xi}(\mathbf{x}, t + t_o | \mathbf{x}_o, t_o) = g_n(\mathbf{x}_o, t_o) \quad (3.8)$$

for  $\chi$  the characteristic function of the set  $\mathbb{A}$ . We can derive the evolution equation for the average by differentiating with respect to  $t_o$ :

$$\partial_{t_o} g_n(\mathbf{x}_o, t_o) = n \int_0^{\infty} dt t^{n-1} (\partial_t - \mathfrak{L}_{\mathbf{x}_o}) \int_{\mathbb{A}} d^d x p_{\xi}(\mathbf{x}, t + t_o | \mathbf{x}_o, t_o)$$

Inspection of the result allows us to recognize that

$$\partial_{t_o} g_n(\mathbf{x}_o, t_o) = -n g_{n-1}(\mathbf{x}_o, t_o) - \mathfrak{L}_{\mathbf{x}_o} g_n(\mathbf{x}_o, t_o) \quad (3.9)$$

which is the result we set ut to obtain. Note that the solution of (3.9) can be rewritten as

$$g_n(\mathbf{x}_o, t_o) = \int_0^{\infty} ds \int_{\mathbb{R}^d} d^d x n g_{n-1}(\mathbf{x}, s + t_o) p_{\xi}(\mathbf{x}, s + t_o | \mathbf{x}_o, t_o)$$

since we can always assume

$$g_n(\mathbf{x}_o, t_o) = 0 \quad \forall \mathbf{x}_o \in \mathbb{R}^d / \mathbb{A} \quad (3.10)$$

### 3.2 Hitting one part of a boundary first

Suppose now that the boundary  $\partial\mathbb{A}$  of a  $\mathbb{A}$  a **smooth bounded open** subset of  $\mathbb{R}^d$  can be decomposed as



with  $\mathbb{B}_i$   $i = 1, 2$  smooth. To any  $\mathbf{x}_o \in \mathbb{A}$  we can associate the stopping time

$$\tau_{\mathbb{B}_i | \mathbf{x}_o} = \inf \{t \geq 0 | \phi_t(\mathbf{x}_o) \in \mathbb{B}_i\} \quad i = 1, 2 \quad (3.11)$$

through the mapping defined by the fundamental solution of (3.1).

**Proposition 3.2.** *The probability that  $\phi_t(\mathbf{x}_o)$  hits first  $\mathbb{B}_1$  is specified by the solution of*

$$\mathfrak{L}_{\mathbf{x}} u(\mathbf{x}) = 0$$

$$u(\mathbf{x}) |_{\mathbf{x} \in \mathbb{B}_1} = 1 \quad \& \quad u(\mathbf{x}) |_{\mathbf{x} \in \mathbb{B}_2} = 0$$

*Proof.* Let

$$u(\phi_t(\mathbf{x}_o)) = u(\mathbf{x}_o) + \int_0^t ds \mathcal{L}_{\phi_s} u(\phi_s) + \int_0^t dw_s^j \sigma^{ij}(\phi_s) \partial_{\phi_s^i} u(\phi_s)$$

If we require

$$\mathcal{L}_{\mathbf{x}} u(\mathbf{x}) = 0$$

together with the hypothesized boundary conditions, taking the average yields for  $t = \tau_{\mathbb{B}_1} : \mathbf{x}$

$$P(\phi_{\tau_{\mathbb{B}_1} | \mathbf{x}_o} \in \mathbb{B}_1) = u(\mathbf{x})$$

□

### 3.2.1 Recurrence of the Wiener process

Let  $\mathbf{w}_t$  a  $d$ -dimensional Wiener motion

$$\xi_t = \|\mathbf{w}_t^2\|$$

then

$$d\xi_t = dt + 2\sqrt{\xi_t} \frac{\mathbf{w}_t \cdot d\mathbf{w}_t}{\|\mathbf{w}_t\|}$$

The stochastic process

$$\eta_t = \int_0^t \frac{\mathbf{w}_s \cdot d\mathbf{w}_s}{\|\mathbf{w}_s\|}$$

enjoys the following properties

- Vanishing first moment

$$\langle \eta_t \rangle = 0$$

- Second moment linearly growing in time

$$\langle \eta_t^2 \rangle = \int_0^t ds = t$$

- Gaussian statistics.
- Independent increments

$$\eta_{t+t_o} - \eta_{t_o} = \int_{t_o}^{t+t_o} \frac{\mathbf{w}_s \cdot d\mathbf{w}_s}{\|\mathbf{w}_s\|}$$

Hence  $\eta_t$  is statistically equivalent to a Wiener process:

$$d\xi_t = dt + 2\sqrt{\xi_t} d\mathbf{w}_t$$

We can ask whether the Wiener process leaves a ball of radius  $R$  around the origin before hitting the origin itself. To answer such question we need to solve for some  $0 < \varepsilon < 1$

$$0 = d \partial_x u + 2 x \partial_x^2 u \quad (3.13a)$$

$$u(\varepsilon) = 0 \quad \& \quad u(R) = 1 \quad (3.13b)$$

A straightforward calculation yields

$$u(x) = P(\tau_{\varepsilon|x} \leq \tau_{R|x}) = \begin{cases} \frac{R^{1-\frac{d}{2}} - x^{1-\frac{d}{2}}}{R^{1-\frac{d}{2}} - \varepsilon^{1-\frac{d}{2}}} & d \neq 2 \\ \frac{\ln R - \ln x}{\ln R - \ln \varepsilon} & d = 2 \end{cases}$$

We observe

$$\lim_{\varepsilon \downarrow 0} P(\tau_{\varepsilon|x} \leq \tau_{R|x}) = \begin{cases} 1 - \left(\frac{x}{R}\right)^{1/2} & d = 1 \\ 0 & d \geq 2 \end{cases}$$

In *two dimensions*, nevertheless

$$\lim_{R \uparrow \infty} P(\tau_{\varepsilon|x} \leq \tau_{R|x}) = 1$$

meaning that the process is *recurrent* in the sense that if  $\mathbb{G}$  is any open set

$$P(\|\mathbf{w}_t\|^2 \in \mathbb{G}) = 1$$

## Appendix

### A Alternative check of the recursion relations for exit times

Iterating the recursion equations as

$$g_n(\mathbf{x}_o, t_o) = \prod_{i=1}^2 \int_0^\infty ds_i \int_{\mathbb{R}^d} d^d x_i n(n-1) g_{n-2}(\mathbf{x}_2, s_2 + s_1 + t_o) p_\xi(\mathbf{x}_2, s_2 + s_1 + t_o | \mathbf{x}_1, s_1 + t_o) p_\xi(\mathbf{x}_1, s_1 + t_o | \mathbf{x}_o, t_o)$$

we get by Chapman-Kolmogorov

$$g_n(\mathbf{x}_o, t_o) = \prod_{i=1}^2 \int_0^\infty ds_i \int_{\mathbb{R}^d} d^d x_2 n(n-1) g_{n-2}(\mathbf{x}_2, s_2 + s_1 + t_o) p_\xi(\mathbf{x}_2, s_2 + s_1 + t_o | \mathbf{x}_o, t_o)$$

Upon setting

$$s = s_1 + s_2$$

the time integral becomes

$$\begin{aligned} g_n(\mathbf{x}_o, t_o) &= \int_0^\infty ds_1 \int_{s_1}^\infty ds \int_{\mathbb{R}^d} d^d x n(n-1) g_{n-2}(\mathbf{x}, s+t_o) p_\xi(\mathbf{x}, s+t_o | \mathbf{x}_o, t_o) \\ &= n(n-1) \int_0^\infty ds s \int_{\mathbb{R}^d} d^d x g_{n-2}(\mathbf{x}, s+t_o) p_\xi(\mathbf{x}, s+t_o | \mathbf{x}_o, t_o) \end{aligned}$$

Repeating the calculation until

$$g_o(\mathbf{x}, t) = \chi_{\mathbb{A}}(\mathbf{x})$$

we recover (3.8).

## References

- [1] M. Avellaneda, *Ito processes, continuous-time martingales and Girsanov's Theorem*, lecture notes, <http://www.math.nyu.edu/faculty/avellane/rm3.ps>
- [2] L.C. Evans, *An Introduction to Stochastic Differential Equations*, lecture notes, <http://math.berkeley.edu/~evans/>