

Quantum Probability: Solution to Exercise 8.1

1. Let $\Phi : B(\mathcal{H}) \rightarrow B(\mathcal{H})$, with $\dim(\mathcal{H}) = n$, be a completely positive superoperator. Show that two Krauss representations

$$\Phi(\rho) = \sum_{\alpha=1}^a M_{\alpha} \rho M_{\alpha}^{\dagger} = \sum_{\beta=1}^b N_{\beta} \rho N_{\beta}^{\dagger},$$

are related by an unitary matrix $U \in \mathbb{C}^{n^2 \times n^2}$ so that

$$M_{\alpha} = \sum_{\beta=1}^{n^2} U_{\alpha\beta} N_{\beta},$$

where $M_{\alpha} = N_{\beta} = 0$ for $\alpha \geq a+1$ and $\beta \geq b+1$. Since the dimension of unitary matrices in \mathbb{C}^n is n^2 this shows that there can not be more than n^4 Krauss representations for Φ .

Let $\{s_j\}$ and $\{e_j\}$ be arbitrary but fixed ON-bases of \mathcal{H}_S and \mathcal{H}_E respectively. Define and unnormalized maximally entangled vector:

$$\Psi := \sum_i |s_i, e_i\rangle$$

By using the two Krauss decompositions one gets

$$\rho_{SE} := (\Phi \otimes 1_E) |\Psi\rangle\langle\Psi| = \sum_{\alpha=1}^a |\tilde{\Psi}_{\alpha}\rangle\langle\tilde{\Psi}_{\alpha}| = \sum_{\alpha=1}^b |\tilde{\Omega}_{\beta}\rangle\langle\tilde{\Omega}_{\beta}|,$$

where $\tilde{\Psi}_{\alpha}, \tilde{\Omega}_{\beta} \in \mathcal{H}_S \otimes \mathcal{H}_E$ are defined by

$$\tilde{\Psi}_{\alpha} := (M_{\alpha} \otimes 1_E) \Psi \quad \text{and} \quad \tilde{\Omega}_{\beta} := (N_{\beta} \otimes 1_E) \Psi.$$

These are not assumed to be normalized nor even linearly independent.

Now, there is the general trick: Any operator A acting on \mathcal{H}_S satisfies

$$A\phi = (1_S \otimes \langle\phi^*|)(A \otimes 1_E)\Psi,$$

where $\phi^* := \sum_i \phi_i^* e_i \in \mathcal{H}_E$ for $\phi = \sum_i \phi_i s_i \in \mathcal{H}_S$. We will use the this trick to write

$$M_{\alpha}\phi = (1_S \otimes \langle\phi^*|)\tilde{\Psi}_{\alpha} \quad \text{and} \quad N_{\beta}\phi = (1_S \otimes \langle\phi^*|)\tilde{\Omega}_{\beta}. \quad (0.1)$$

Let us purify these be in terms of the vectors in $\mathcal{H}_S \otimes \mathcal{H}_E \otimes \mathcal{H}_R$:

$$\mathcal{A} := \sum_{\alpha=1}^a \tilde{\Psi}_{\alpha} \otimes r_{\alpha} \quad \text{and} \quad \mathcal{B} := \sum_{\beta=1}^b \tilde{\Omega}_{\beta} \otimes r_{\beta},$$

Here $\{r_{\gamma}\}$ is a ON-basis for a Hilbert space \mathcal{H}_R . Since $a, b \leq n^2$ we may take $\dim(\mathcal{H}_R) = n^2$ and define $|\tilde{\Psi}_{\alpha}\rangle = |\tilde{\Omega}_{\beta}\rangle = 0$ for $\alpha \geq a+1$ and $\beta \geq b+1$. Since $\rho_{SE} = \text{Tr}_R(|\mathcal{A}\rangle\langle\mathcal{A}|) = \text{Tr}_R(|\mathcal{B}\rangle\langle\mathcal{B}|)$ there exists an unitary transformation U acting on \mathcal{H}_R such that

$$\mathcal{A} = (1_{SE} \otimes U)\mathcal{B},$$

where $1_{SE} := 1_S \otimes 1_E$. Now expressing $U = \sum_{\alpha,\beta} U_{\alpha\beta} |r_\alpha\rangle\langle r_\beta|$ one gets

$$\begin{aligned} \sum_{\alpha} \tilde{\Psi}_\alpha \otimes r_\alpha &= \mathcal{A} = (1_{SE} \otimes U) \mathcal{B} = (1_{SE} \otimes U) \sum_{\beta} \tilde{\Omega}_\beta \otimes r_\beta \\ &= \sum_{\alpha} \left\{ \sum_{\beta} U_{\alpha\beta} \tilde{\Omega}_\beta \right\} \otimes r_\alpha. \end{aligned}$$

By the ON property of $\{r_\alpha\}$ each α term above is orthogonal to the others. Thus we get

$$\tilde{\Psi}_\alpha = \sum_{\beta} U_{\alpha\beta} \tilde{\Omega}_\beta \quad \text{for each } \alpha = 1, 2, \dots, n^2$$

By using the representation trick, i.e., (0.1), this implies

$$M_\alpha \phi = (1_S \otimes \langle \phi^* |) \tilde{\Psi}_\alpha = \sum_{\beta} U_{\alpha\beta} (1_S \otimes \langle \phi^* |) \tilde{\Omega}_\beta = \sum_{\beta} U_{\alpha\beta} N_\beta \phi.$$

Since $|\phi\rangle \in \mathcal{H}_S$ was arbitrary this completes the proof.

8.2

(a) The basis $\{|l\rangle\}$ spans $\mathcal{H}_S \Rightarrow$ operators fully characterized on \mathcal{H}_S now they act on the vectors $|l\rangle$:

$$\begin{aligned} a_I |l\rangle &= e^{i\omega t M} a e^{-i\omega t M} |l\rangle \quad | \text{NUMBER OPERATOR } M |l\rangle = l |l\rangle \\ &= e^{i\omega t l} a e^{-i\omega t l} |l\rangle \\ &= e^{-i\omega t l} e^{i\omega t M} a |l\rangle \\ &= e^{-i\omega t l} e^{i\omega t M} \sqrt{l} |l-1\rangle = \sqrt{l} e^{-i\omega t l} e^{i\omega t (l-1)} |l-1\rangle \\ &= e^{-i\omega t} a |l\rangle \quad (\forall l \in \mathbb{N}_0) \end{aligned}$$

$\Rightarrow a_I(t) = e^{-i\omega t} a$

(b) - Let's denote $U_0 \equiv U_0(t) = e^{-i\omega t H_0}$
 $\Rightarrow i\partial_t U_0 = H_0 U_0$ (fundamental solution to Schrödinger's eq.)

- Now, $P_I \equiv P_I(t) = U_0^{-1}(t) P(t) U_0(t)$

or $P(t) = U_0(t) P_I(t) U_0^{-1}(t)$

- Let's substitute this into (0.1): LHS gives:

$$\begin{aligned} \dot{P} &\equiv \partial_t P = \partial_t (U_0 P_I U_0^{-1}) = \underbrace{\dot{U}_0 P_I U_0^{-1}}_{\text{"}} + U_0 P_I (\partial_t U_0^{-1}) + \underbrace{U_0 \dot{P}_I U_0^{-1}}_{\text{"}} + \underbrace{U_0 P_I \dot{U}_0^{-1}}_{\text{The rest.}} \\ &= -i [H_0, P] + U_0 \dot{P}_I U_0^{-1} \left. \begin{array}{l} -i H_0 U_0 P_I U_0^{-1} \\ \text{"} \\ -i H_0 P \end{array} \right\} \begin{array}{l} \text{"} \\ \partial_t U_0^{-1} \\ \text{"} \\ (\partial_t U_0)^{\dagger} \\ \text{"} \\ +i H_0 U_0^{-1} \end{array} \end{aligned}$$

- Now, RHS of 0.1 gives:

$$\begin{aligned} \dot{P} &= -i [H_0, P] \\ &+ \gamma a P a^{\dagger} - \frac{\gamma}{2} a^{\dagger} a P - \frac{\gamma}{2} P a^{\dagger} a \end{aligned}$$

- Comparing LHS and RHS we get:

$$P_I = U_0^{-1} \left\{ \gamma a P a^{\dagger} - \frac{\gamma}{2} a^{\dagger} a P - \frac{\gamma}{2} P a^{\dagger} a \right\} U_0$$

- The first term goes:

$$\begin{aligned} U_0^{-1} a P a^{\dagger} U_0 &= (U_0^{-1} a U_0) (U_0^{-1} P U_0) (U_0^{-1} a^{\dagger} U_0)^{\dagger} \\ &= a_I P_I a_I^{\dagger} \\ &\stackrel{(a)}{=} a P_I a^{\dagger} \end{aligned}$$

- Other terms go similarly $\Rightarrow \dot{P}_I = \gamma \left\{ a P_I a^{\dagger} - \frac{1}{2} (a^{\dagger} a P_I + P_I a^{\dagger} a) \right\}$

8.2 CONTINUOUS...

(C) LET'S DEFINE $\tilde{a}(t) := U_0(t) a U_0^{-1}(t)$

USE: $\text{Tr}(ABC) = \text{Tr}(CAB)$

$$\begin{aligned} \text{THEN } f(t) &:= \text{Tr}[\tilde{a}(t) P_I] = \text{Tr}[\tilde{a} U_0 P_I U_0^{-1}] \\ &= \text{Tr}[U_0^{-1} \tilde{a} U_0 P_I] = \text{Tr}[a P_I(t)] \end{aligned}$$

- Now, using $[a, a^T] = \mathbb{1}$ and cyclic identity

$$\begin{aligned} \frac{d}{dt} f(t) &= \text{Tr} \left\{ \dot{a} P_I \right\} \\ &= \frac{\delta}{2} \text{Tr} \left\{ 2 a^T \dot{a} a^T - a \dot{a}^T a - a P_I \dot{a} \right\} \\ &= \frac{\delta}{2} \left\{ 2 \text{Tr}[a^T \dot{a} a^T] - \text{Tr}[a \dot{a}^T a] - \text{Tr}[a^T \dot{a} a] \right\} \\ &= \frac{\delta}{2} \left\{ 2 \text{Tr}[a^T \dot{a} a^T] - \text{Tr}[a \dot{a}^T a] - \text{Tr}[a^T \dot{a} a] \right\} \\ &= \frac{\delta}{2} \text{Tr} \left(\underbrace{[a^T, a]}_{-\mathbb{1}} a P_I \right) = -\frac{\delta}{2} \text{Tr}(a P_I) \\ &= -\frac{\delta}{2} f(t) \end{aligned}$$

- Clearly, this is solved by $f(t) = e^{-\frac{\delta}{2} t} f(0)$

(D) DEFINE $g(t) := \text{Tr}(a^T a P_I(t))$

$$\begin{aligned} &= \text{Tr} \left(\overbrace{a^T}^{\text{tr}} \overbrace{a}^{\text{tr}} U_0 P_I U_0^{-1} \right) = \text{Tr} \left((U_0^{-1} a^T U_0) (U_0^{-1} a U_0) P_I \right) \\ &= \text{Tr}(a^T a P_I) \end{aligned}$$

THEN

$$\begin{aligned} g'(t) &= \frac{\delta}{2} \text{Tr} \left(a^T a \left\{ 2 a P_I \dot{a} - a^T \dot{a} P_I - P_I \dot{a}^T a \right\} \right) \\ &= \frac{\delta}{2} \left\{ 2 \text{Tr}(a^T a \dot{a} a P_I) - 2 \text{Tr}(a^T a \dot{a}^T a P_I) \right\} \\ &= \delta \text{Tr} \left(a^T \underbrace{[a^T, a]}_{-\mathbb{1}} a P_I \right) = -\delta \text{Tr}(a^T a P_I) \\ &= -\delta g(t) \end{aligned}$$

- This is solved by $g(t) = e^{-\delta t} g(0)$

8.3

a) Let's start by OPENING DEFINITIONS:

$$(0) \mathcal{M}_I(a, \bar{a}, t) := \text{Tr}(\rho_I(t) e^{a^\dagger t} e^{-\bar{a} a}) \quad , \quad a, \bar{a} \in \mathbb{C} \quad (\text{WE TAKE } \bar{a} = a^* \text{ LATER})$$

$$(1) \partial_t \rho_I = \frac{\delta}{2} (2 \partial \rho_I a^\dagger - a^\dagger \partial \rho_I - \rho_I a^\dagger \partial)$$

- Let's express $\partial_t \mathcal{M}_I$ with these by using $\text{Tr}(ABC) = \text{Tr}(CAB) = \text{Tr}(BCA)$:

$$(2) \frac{2}{\delta} \partial_t \mathcal{M}_I = \underbrace{2 \text{Tr}(\rho_I a^\dagger e^{a^\dagger t} \partial e^{-\bar{a} a})}_{=(2a)} - \underbrace{\text{Tr}(\rho_I e^{a^\dagger t} e^{-\bar{a} a} a^\dagger \partial)}_{=(2b)} - \underbrace{\text{Tr}(\rho_I a^\dagger \partial e^{a^\dagger t} e^{-\bar{a} a})}_{=(2c)}$$

- ON THE OTHER HAND:

$$(3) \frac{\partial}{\partial a} \mathcal{M}_I = \text{Tr}(\rho_I a^\dagger e^{a^\dagger t} e^{-\bar{a} a})$$

$$(4) \frac{\partial}{\partial \bar{a}} \mathcal{M}_I = \text{Tr}(\rho_I e^{a^\dagger t} (-\partial) e^{-\bar{a} a})$$

- OUR STRATEGY TO DERIVE THE PDE FOR \mathcal{M}_I IS NOW TO BRING ALL TERMS (2a), (2b), (2c), (3), (4) INTO THE STANDARD FORM:

$$(5) \text{Tr}(\rho_I (a^\dagger)^m e^{a^\dagger t} (-\partial)^m e^{-\bar{a} a}) \quad , \quad m, m \in \mathbb{N}_0 \equiv \{0, 1, 2, 3, \dots\}$$

by using the formula:

$$(6) e^{\dagger A} B e^{-\dagger A} = B + [A, B] + \frac{1}{2} [A, [A, B]] + \dots$$

where $f(0, t) = 0$.

- TERMS (2a), (3) and (4) are already in the std. form.

- Let's put (2b) into form (5):

$$\begin{aligned} e^{-\bar{a} a} \partial e^{a^\dagger t} &= (e^{-\bar{a} a} \partial e^{\bar{a} a}) e^{-\bar{a} a} \quad (\text{NOTE: } e^{\dagger A} e^{-\dagger A} = \mathbb{1} \text{ BY POWER SERIES EXPANSION}) \\ &= \left\{ \partial + [a, \partial] (-\bar{a}) + 0 \right\} e^{-\bar{a} a} \mathbb{1} \\ (7) &= \underbrace{\partial e^{-\bar{a} a}}_{=(7a)} - \bar{a} \cdot e^{-\bar{a} a} \quad \leftarrow [x, [a, \partial]] = 0, \forall x \end{aligned}$$

- Similarly,

$$\begin{aligned} (8) \quad a e^{a^\dagger t} &= e^{a^\dagger t} (e^{-a^\dagger t} a e^{a^\dagger t}) = e^{a^\dagger t} \left\{ a + [a^\dagger, a] (-t) + 0 \right\} \\ &= \underbrace{e^{a^\dagger t} a}_{=(7b)} + a e^{a^\dagger t} \end{aligned}$$

- Substituting these into (2) and using cyclicity of trace yield (7a) and (7b) cancel term (2a) and thus we get:

$$\begin{aligned} (9) \quad \partial_t \mathcal{M}_I &= - \frac{\delta}{2} \left\{ \bar{a} \cdot \text{Tr}(\rho_I e^{a^\dagger t} (-\partial) e^{-\bar{a} a}) + a \cdot \text{Tr}(\rho_I a^\dagger e^{a^\dagger t} e^{-\bar{a} a}) \right\} \\ &= - \frac{\delta}{2} \left\{ \bar{a} \frac{\partial}{\partial \bar{a}} \mathcal{M}_I + a \frac{\partial}{\partial a} \mathcal{M}_I \right\} \end{aligned}$$

$$\text{- Now, } \frac{\partial}{\partial (i\bar{a})} = \frac{\partial a}{\partial (i\bar{a})} \frac{\partial}{\partial a} = \left(\frac{\partial (i\bar{a})}{\partial \bar{a}} \right)^{-1} \frac{\partial}{\partial \bar{a}} = a \frac{\partial}{\partial a} \quad \text{and} \quad \frac{\partial}{\partial (i\bar{a})} = \bar{a} \frac{\partial}{\partial \bar{a}}$$

- Thus (9) is equivalent to the PDE:

$$(10) \left[\frac{\partial}{\partial t} + \frac{\delta}{2} \left(\frac{\partial}{\partial (i\bar{a})} + \frac{\partial}{\partial (i\bar{a})} \right) \right] \mathcal{M}_I = 0$$

2.3 b) Method of characteristics is an overkill for our problem. Anyway, MC for a general linear PDE:

$$LM(x) \equiv b(x) \cdot DM + c(x)M(x) = 0, \quad x \in (x^1, \dots, x^d) \in \mathbb{R}^d, \quad D = \left(\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^d} \right)$$

yields (details: L.C. EVANS, Partial Diff. Equations AMS, p. 99-100)

$$(1) \quad \begin{cases} \frac{d}{ds} x(s) = b(x(s)) \\ \frac{d}{ds} z(s) = -c(x(s))z(s) \end{cases} \quad \text{TIMELINE}$$

where s is a technical parameter that parametrizes a curve $s \mapsto (x(s), z(s))$ on the solution manifold $\{(x, M(x)) : LM(x) = 0, x \in K\}$ of the PDE. Here $K \subset \mathbb{R}^d$ is the domain where PDE is to be solved. By solving (1) one hopes to be able to relate the general value of $M(x)$ to a known boundary value of $M(x_0) \in \partial K$ by connecting

$$\begin{aligned} (x(0), z(0)) &= (x_0, M(x_0)) \\ (x(s), z(s)) &= (x, M(x)) \end{aligned}$$

In our case, $x = (x^1, x^2, x^3) = (t, A, \bar{A})$
 $b(x) = \left(1, \frac{\delta}{2} x^1, \frac{\delta}{2} x^2 \right)$
 $c(x) = 0$
 $K = \{(x^1, x^2, x^3) \in \mathbb{R}^3 : x^1 \geq 0\}$
 $\Rightarrow \partial K = \{0\} \times \mathbb{R}^2$

NOTE: WE could also choose $x = (t, \ln A, \ln \bar{A})$ etc. and obtain the same result.

ALSO NOTE: WE consider initially \mathbb{R}^d but everything goes smoothly in \mathbb{R}^d as well...

- OF COURSE, WE WANT TO

- LET'S CHOOSE PARAMETER s SUCH THAT: $x^1(s) = s$.

- THEN (1) yields:

$$\left. \begin{aligned} \dot{x}(s) &= \frac{\delta}{2} x(s) \\ \dot{\bar{A}}(s) &= \frac{\delta}{2} \bar{A}(s) \\ \dot{z}(s) &= 0 \end{aligned} \right\} \Rightarrow \begin{cases} A(s) = A_0 \cdot e^{\frac{\delta}{2}s} \\ \bar{A}(s) = \bar{A}_0 \cdot e^{\frac{\delta}{2}s} \\ z(s) = z_0 \end{cases} \quad \text{for all } A_0, \bar{A}_0, z_0 \in \mathbb{R}.$$

- Let $\mathcal{Y}_{\mathbb{I}}(0, A, \bar{A}) =: \mathcal{Y}(A, \bar{A}) \equiv \text{Tr}(P(0) e^{A\delta t} e^{-\bar{A}\delta t})$.

- THEN:

$$\mathcal{Y}(A_0, \bar{A}_0) = z(0) = z(s) = \mathcal{Y}_{\mathbb{I}}(x(s)) = \mathcal{Y}_{\mathbb{I}}(s, A_0 e^{\frac{\delta}{2}s}, \bar{A}_0 e^{\frac{\delta}{2}s})$$

- NO SETTING $A = A_0 \cdot e^{\frac{\delta}{2}s}, \bar{A} = \bar{A}_0 \cdot e^{\frac{\delta}{2}s}$ AND $t = s$:

$$\mathcal{Y}_{\mathbb{I}}(t, A, \bar{A}) = \mathcal{Y}(A e^{-\frac{\delta}{2}t}, \bar{A} e^{-\frac{\delta}{2}t})$$

- IT'S OF COURSE ESS TO CHECK BY SUBSTITUTING INTO PDE THAT THIS IS SOLUTION FOR $A, \bar{A} \in \mathbb{R}$ AS WELL.

8.3 c) Let $f_S(x, A, \bar{A}) = Tt(\rho(x) e^{A\alpha t} e^{-\bar{A}\alpha})$

- THIS SOLVES PDE:

$$\left[\frac{\partial}{\partial t} + \left(\frac{\delta}{2} - i\omega\right) \frac{\partial}{\partial \ln A} + \left(\frac{\delta}{2} + i\omega\right) \frac{\partial}{\partial \ln \bar{A}} \right] f_S = 0$$

- TO OBTAIN THIS ONE WORKS JUST LIKE IN a);

INDEED, THERE IS A ONE EXTRA TERM IN (2) COMING

FROM $Tt(-\lambda [H_0] \rho) e^{A\alpha t} e^{-\bar{A}\alpha} = \underbrace{-\lambda \omega Tt(\rho e^{A\alpha t} e^{-\bar{A}\alpha})}_{=(17b)} + \lambda \omega Tt(\rho e^{A\alpha t} e^{-\bar{A}\alpha})_{=(17c)}$

- TERMS (17b) AND (17c) ARE HANDLED JUST LIKE TERMS (2b) AND (2c) RESPECTIVELY.

- SOLUTION IS OBTAINED BY USING MC AS BEFORE AS WELL:

$$f_S(t, A, \bar{A}) = f\left(A \cdot e^{-(\frac{\delta}{2} - i\omega)t}, \bar{A} \cdot e^{-(\frac{\delta}{2} + i\omega)t}\right)$$