



Learning outcomes

- Continuing to learn to master but also to apply the concepts discussed during the last two weeks
- Understand how and why full MHD solvers can be useful to understand stellar magnetism
- Basic principles of the numerical methods
- Restrictions of the methods
- Most prominent results
- Recap of the whole contents of the MHD module

Magnetohydrodynamics: basic equations

 $\frac{\partial \boldsymbol{A}}{\partial t} = \boldsymbol{U} \times \boldsymbol{B} - \eta \mu_0 \boldsymbol{J},$ $\frac{D\ln\rho}{Dt} = -\nabla \cdot \boldsymbol{U},$ $\frac{\mathrm{D}\boldsymbol{U}}{\mathrm{D}t} = \boldsymbol{g} - 2\boldsymbol{\Omega}_0 \times \boldsymbol{U} - \frac{1}{\rho} (\boldsymbol{\nabla} p + \boldsymbol{J} \times \boldsymbol{B} + \boldsymbol{\nabla} \cdot 2\nu\rho \boldsymbol{\mathsf{S}}),$ $T\frac{\mathrm{D}s}{\mathrm{D}t} = \frac{1}{o} \left[\eta \mu_0 \boldsymbol{J}^2 - \boldsymbol{\nabla} \cdot (\boldsymbol{F}^{\mathrm{rad}} + \boldsymbol{F}^{\mathrm{SGS}}) - \boldsymbol{\Gamma}_{\mathrm{cool}} \right] + 2\nu \boldsymbol{\mathsf{S}}^2$

 $\nabla \cdot \boldsymbol{B} = 0$

Magnetohydrodynamics: non-dimensional parameters

$$\begin{split} \left| \frac{\boldsymbol{u} \cdot \boldsymbol{\nabla} \boldsymbol{u}}{\partial \boldsymbol{u} / \partial t} \right| &\approx \frac{u^2 \tau}{ul} = \frac{u \tau}{l} \equiv \mathrm{St}, & \mathrm{Ma} = \frac{u}{c_s}, \\ \left| \frac{\boldsymbol{u} \cdot \boldsymbol{\nabla} \boldsymbol{u}}{2 \, \Omega \times \boldsymbol{u}} \right| &\approx \frac{u^2}{2 \, \Omega l \boldsymbol{u}} = \frac{u}{2 \, \Omega l} \equiv \mathrm{Ro} = \mathrm{Co}^{-1}, & \mathrm{Pm} \equiv \frac{\mathrm{Rm}}{\mathrm{Re}} = \frac{\nu}{\eta}, \\ \left| \frac{\boldsymbol{u} \cdot \boldsymbol{\nabla} \boldsymbol{u}}{g} \right| &\approx \frac{u^2}{lg} \equiv \mathrm{Fr} = \mathrm{Ri}^{-1}, & \mathrm{Pr} \equiv \frac{\nu}{\chi}, \\ \left| \frac{\boldsymbol{u} \cdot \boldsymbol{\nabla} \boldsymbol{u}}{\nu \boldsymbol{\nabla}^2 \boldsymbol{u}} \right| &\approx \frac{u^2 l^2}{\nu l \boldsymbol{u}} = \frac{ul}{\nu} \equiv \mathrm{Re}, & \mathrm{Rm} \equiv \frac{ul}{\eta}, \end{split}$$

Big dynamic picture



Even larger DYNAMICAL picture



Schematic dynamic dynamo



Dynamic dynamo with equation

$$\frac{\partial \boldsymbol{B}}{\partial t} = \boldsymbol{\nabla} \times [\overline{\boldsymbol{U}} \times \overline{\boldsymbol{B}} + \alpha \overline{\boldsymbol{B}} - (\eta + \eta_{\mathrm{t}})\overline{\boldsymbol{J}}] ,$$

$$\frac{\mathrm{d}\alpha}{\mathrm{d}t} = -2\eta_{\mathrm{t}}k_{\mathrm{f}}^{2} \left(\frac{\alpha \langle \overline{\boldsymbol{B}}^{2} \rangle - \eta_{\mathrm{t}} \langle \overline{\boldsymbol{J}} \cdot \overline{\boldsymbol{B}} \rangle}{B_{\mathrm{eq}}^{2}} + \frac{\alpha - \alpha_{\mathrm{K}}}{\tilde{R}_{\mathrm{m}}}\right) \quad \text{No flux}$$

$$\frac{\partial \alpha}{\partial t} = -2\eta_{\rm t} k_{\rm f}^2 \left(\frac{\alpha \overline{B}^2 - \eta_{\rm t} \overline{J} \cdot \overline{B} + \frac{1}{2} k_{\rm f}^{-2} \nabla \cdot \overline{\mathscr{F}}_{\rm C}}{B_{\rm eq}^2} + \frac{\alpha - \alpha_{\rm K}}{R_{\rm m}} \right)$$
Fluxes

In MF models all these effects need to be parameterized – in DNS they can arise self-consistently

Poloidal field in the $(r, \theta)/(x,z)$ -plane Toroidal field in the ϕ/y direction.

Coordinate systems



Ω

Spherical coordinate system counterparts

Wedges

Coordinate systems



Spherical coordinates, but both latitudinal and longitudinal directions are shrunk.
 Longitude: for convenience, if the system is axisymmetric.
 Latitude: to avoid polar singularity

Full MHD models: basic idea



Nondimensionalization

$$C_{lpha}=rac{lpha_0 R}{\eta_0}, \ \ C_{\Omega}=rac{\Omega_0 R^2}{\eta_0}, \ \ ext{and} \ \ C_U=rac{u_0 R}{\eta_0}$$

 $Re = \frac{u \ell}{v}, Rm = \frac{u \ell}{\eta}$

- Computers deal with numbers
- They cannot keep track on units
- Before numerical solutions are attempted, the equations must be non-dimensionalised
- One ends up with non-dimensional control parameters...
- ...which are the familiar Reynolds numbers for the full MHD equations
- ...and dynamo numbers for the MF induction equation

Local convection simulations

- Maximise resolution for accuracy
- Study key processes in isolation
- Reduce the complexity of the full system
- Do not tell the full story









Movie from a local simulation near the surface

Local convection simulations

- Testing theories for convection
- Angular momentum transport
- Dynamo driving
 - Large-scale dynamo







Leptocline and meridional flow required





Local convection simulations

- Testing theories for convection
- Angular momentum transport
- Dynamo driving
 - Large-scale dynamo
 - Small-scale dynamo



Stellar convection zones have small magnetic Prandtl numbers (*Pm*)



Few years ago SSD seemed to be impossible...





Improved computational resources changed the picture







Speed

Magnetic energy



Global convection simulations

- Suffer in accuracy
- Allow studies on the full story

Can you yet trust the results?

Solar-like cycles, but differential rotation profile is not matching







Active rapid rotators



MF predictions and models agree very well



Highest resolution wedge models capture SSD and LSD at Pm=1



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Most prominent results from full MHD

- Local models predict that
 - Parker dynamo is a functioning concept
 - SSD should exist in stellar convection zones
- Global models
 - Can produce solar-like cycles
 - Cannot produce the correct differential rotation in the Sun
 - When applied to active stars, reproduce theoretical (MF predictions)
 - Very recently capture SSD in Pm=1 fluids