Ex. 1
Continue from exercise 4.1. Download data linear-model-data-1.dat from the course webpage. Complete the following task by writing yourself the functions/procedures needed. At this point, do not use existing regression analysis packages that might be available on your computing platform. From the fitted model $\hat{y}=2.874-5.08162 x+0.763641 x^{2}$,
a) Compute standardized residuals (from Eq. (3.27)) and plot against $x$.
b) Form diagnostic parameter table from model variables as in page 3-13 in the lecture material. What can be deducted regarding the model variables from the parameter table?

Ex. 2
We have two sets of observations, linear-model-data-2a.dat and linear-model-data-2b.dat (on course webpage). We know that both should have dependency $y=\beta_{0}+\beta_{1} x^{2}$, but we do not know if the constant $\beta_{0}$ is the same for both groups. Study this and make decision based on joined linear model for both sets together, with categorical variable included to separate the sets, i.e. $y_{i}=$ $\beta_{0}+\beta_{c} g_{i}+\beta_{1} x_{i}^{2}$, where $g_{i}=0 / 1$ is the categorical variable marking the group, and $\beta_{c}$ is its coefficient.

## Ex. 3

Load observations from linear-model-data-3.dat. First two columns are explanatory variables $x_{1}, x_{2}$, third is dependent variable $y$. Find suitable model between $y$ and $x_{i}$. You can test functions of $x_{i}$ 's and interaction. Test at least two different models and choose best according to model selection criterion of your choice. Check if parameters in the model are significant and that residuals against predicted $\hat{y}$ seem unbiased and homoscedastic. You can use ready-made regression package or write your own procedures.

## Ex. 4

Fit nonlinear model to observed degree of linear polarization of comet Hale-Bopp in red wavelength filter. Download data from course webpage (dataRed.dat). Use trigonometric model

$$
\begin{equation*}
y_{i}=\mathrm{f}_{i}(\boldsymbol{\beta})=\beta_{1} \sin \left(x_{i}\right)^{\beta_{2}} \cos \left(x_{i} / 2\right)^{\beta_{3}} \sin \left(x_{i}-\beta_{4}\right) . \tag{1}
\end{equation*}
$$

a) Program function $S\left(b_{1}, b_{2}, b_{3}, b_{4}\right)=\sum^{n}\left(y_{i}-\mathrm{f}_{i}\left(b_{1}, b_{2}, b_{3}, b_{4}\right)\right)^{2}$ in your computing environment. Use minimization procedure to find best estimates $b_{1}, b_{2}, b_{3}, b_{4}$. (If you cannot use minimization, test few choices for parameters yourself and choose the best ones).
b) Plot data together with the best fit function.
c) Compute sum of squared residuals, $S S E$, and residual variance $s^{2}$.
d) Compute test statistics $t_{i}=\frac{b_{i}}{s \sqrt{m^{i i}}}$ for the parameters. For $m^{i i}=\left[M^{-1}\right]_{i i}$ you need the matrix $\mathbf{F}(\boldsymbol{b})$ as in Eq. (4.15). Partial derivatives of $f$ are given in the end of this page.
e) Which parameter is the most uncertain, i.e., has smallest value of test statistics? Test its $p$-value for the hypothesis $H_{0}$ that it could be removed from the model.

$$
\begin{align*}
& \frac{\partial \mathrm{f}}{\partial b_{1}}=-\sin (x)^{b_{2}} \cos \left(\frac{x}{2}\right)^{b_{3}} \sin \left(b_{4}-x\right)  \tag{2}\\
& \frac{\partial \mathrm{f}}{\partial b_{2}}=-b_{1} \sin (x)^{b_{2}} \cos \left(\frac{x}{2}\right)^{b_{3}} \sin \left(b_{4}-x\right) \log (\sin (x))  \tag{3}\\
& \frac{\partial \mathrm{f}}{\partial b_{3}}=-b_{1} \sin (x)^{b_{2}} \cos \left(\frac{x}{2}\right)^{b_{3}} \sin \left(b_{4}-x\right) \log \left(\cos \left(\frac{x}{2}\right)\right)  \tag{4}\\
& \frac{\partial \mathrm{f}}{\partial b_{4}}=-b_{1} \sin (x)^{b_{2}} \cos \left(\frac{x}{2}\right)^{b_{3}} \cos \left(b_{4}-x\right) \tag{5}
\end{align*}
$$

