

Note that this exercise has more than one page.

Please complete the theoretical exercises (marked with T) before the exercise session and be prepared to present your solution there.

- T1. Consider the inverse problem defined by the measurement model  $m = Ax$  in the cases

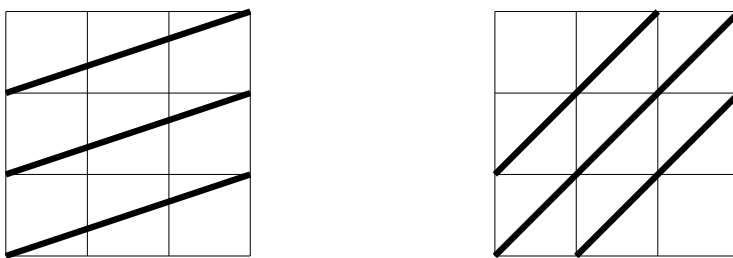
$$(a) A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, m = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad (b) A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \\ 13 & 31 \end{bmatrix}, m = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}.$$

Here the *input* is the measurement  $m$ , and the *solution* (also called *output*) is any  $\tilde{x}$  such that  $m = A\tilde{x}$ .

Which of Hadamard's conditions is violated, if any? (Hadamard's conditions are (i) solution must exist, (ii) solution must be unique, and (iii) the output should depend continuously on the input.)

- T2. Assume that the  $n \times n$  matrix  $U : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is orthogonal:  $UU^T = I = U^TU$ . Show that  $\|U^T y\| = \|y\|$  for any  $y \in \mathbb{R}^n$ .

- T3. Thin lines depict pixels and thick lines X-rays in this image:



Give a numbering to the nine pixels ( $f \in \mathbb{R}^9$ ) and to the six X-rays ( $m \in \mathbb{R}^6$ ), and construct the matrix  $A$  for the measurement model  $m = Af$ . The length of the side of a pixel is one.

You can work on these Matlab exercises (marked with M) in the exercise session.

- M1. Run the file `DC1_cont_data_comp.m`. Set the number of discretization points to 100 by writing `n = 100`; on line 12 in the file `DC2_discretedata_comp.m`. Then run the file `DC2_discretedata_comp.m` to produce discrete convolution data.

Compute the singular value decomposition of the  $100 \times 100$  measurement matrix  $A$  using the code in the file `DC4_truncSVD_comp.m`. Determine the *condition number* of  $A$ , defined as the first (largest) singular value divided by the last (smallest) singular value.

Repeat the above with resolutions  $n = 200, 300, 400$ . What happens to the condition number when  $n$  grows?

- M2. Find out the minimum relative error achievable by choosing the optimal number of singular values in the truncated SVD routine `DC4_truncSVD_comp.m`. Compute the minimal error for all four resolution values  $n = 100, 200, 300, 400$ .

You can work on these L<sup>A</sup>T<sub>E</sub>X exercises (marked with L) in the exercise session, or you can complete them beforehand.

- L1. Include in your L<sup>A</sup>T<sub>E</sub>X document all the plots produced by Exercise M2.
- L2. Add the following list of references (actually a list with only one entry) to your L<sup>A</sup>T<sub>E</sub>X document:

```
\begin{thebibliography}{99}
\bibitem{kurssikirja}
Mueller, J.L. and Siltanen, S: {\em Linear and Nonlinear Inverse
Problems with Practical Applications.}
SIAM 2012. ISBN 978-1-611972-33-7
\end{thebibliography}
```

Include in the text a reference to the book using the command

```
\cite{kurssikirja}
```