

131-1-2012

12

Previous lecture we derived
the population model

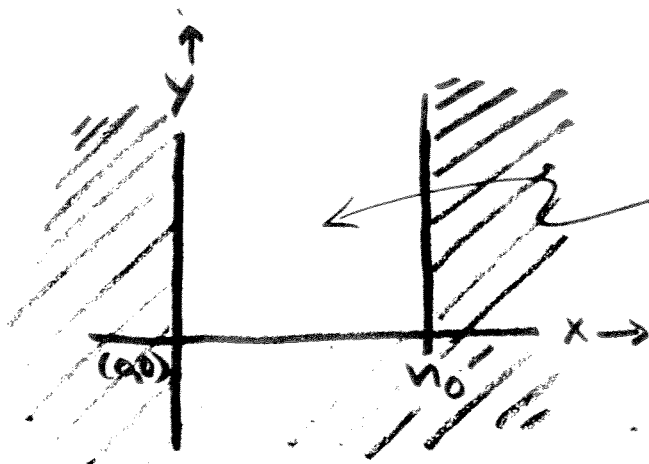
$$\begin{cases} \frac{dx}{dt} = +\beta(n_0 - x)y - \mu x \\ \frac{dy}{dt} = -\beta(n_0 - x)y + \alpha x - \nu y \end{cases}$$

(see prev. lecture for interpretation).

Here we analyze the model
using the phase-plane method.

The phase-plane (or population
state space) is the set of all
feasible values of (x, y) ;

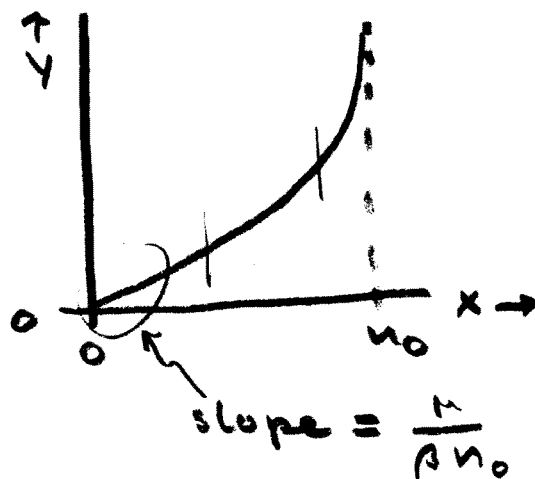
here $\{(x, y) : 0 \leq x \leq n_0 \text{ \& } 0 \leq y\}$.



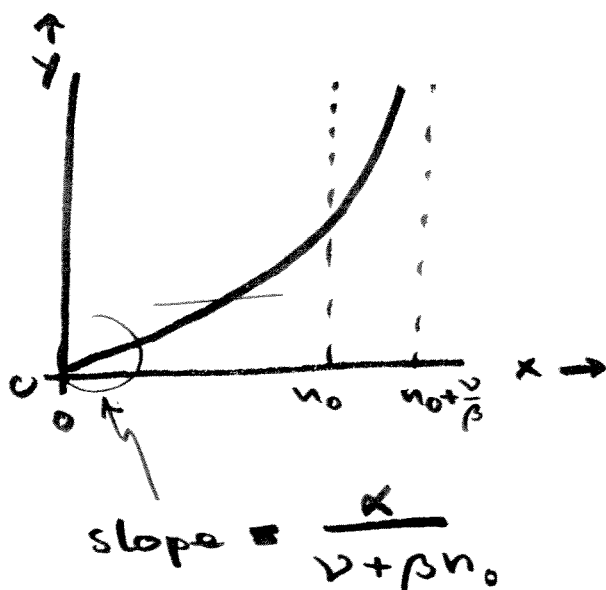
only this
white region
is interpretable.

The zero-cline for x in the set $\{(x, y) : \frac{dx}{dt} = 0\}$ and is crossed vertically from above or from below:

$$\frac{dx}{dt} = 0 \iff y = \frac{\alpha}{\beta} \cdot \frac{x}{n_0 - x}$$

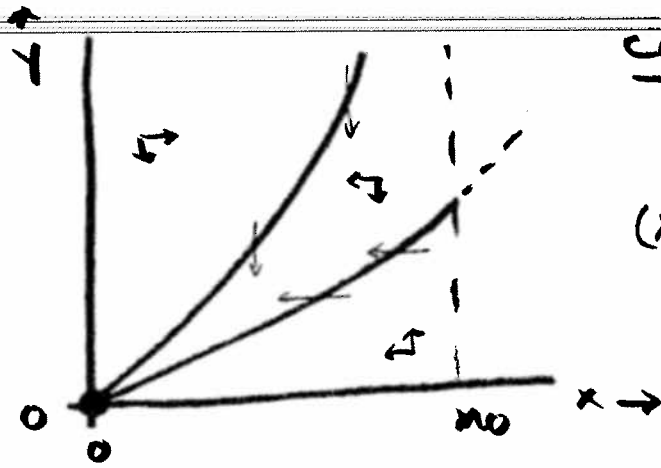


The zero-cline for y in the set $\{(x, y) : \frac{dy}{dt} = 0\}$ and is crossed horizontally from the left or from the right.



$$\frac{dy}{dt} = 0 \iff y = \frac{\alpha}{\beta} \cdot \frac{x}{\frac{v}{\beta} + n_0 - x}$$

Combining the zero-clines in one picture gives

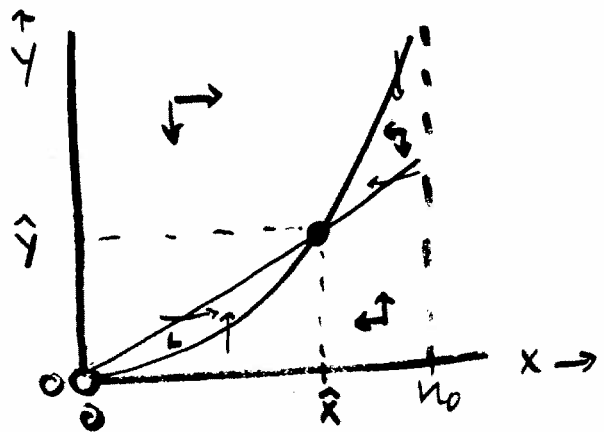


case $\frac{\alpha}{\nu + \beta n_0} \leq \frac{\mu}{\beta n_0}$

$(x, y) = (0, 0)$
globally
attracting
equilibrium

case: $\frac{\alpha}{\nu + \beta n_0} > \frac{\mu}{\beta n_0}$

$(x, y) = (0, 0)$
unstable
equilibrium



$(x, y) = (\hat{x}, \hat{y})$
globally
attracting
equilibrium

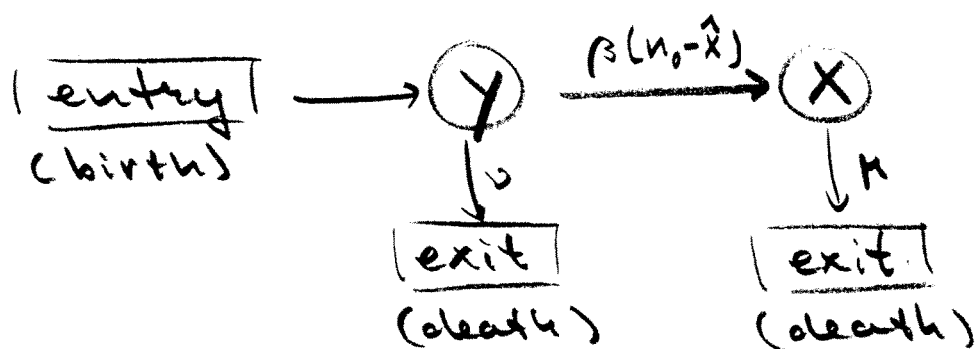
$$\hat{x} = n_0 - \frac{\mu \nu}{\beta(\alpha - \mu)}$$

$$\hat{y} = \frac{n_0(\alpha - \mu)}{\nu} - \frac{\mu}{\beta}$$

An equilibrium is any point (x, y)
where $\frac{dx}{dt} = 0$ and $\frac{dy}{dt} = 0$
(i.e., any intersection of the zero-clines)

What is the expected life time of a newborn at the positive equilibrium?

Rewrite the reaction network as

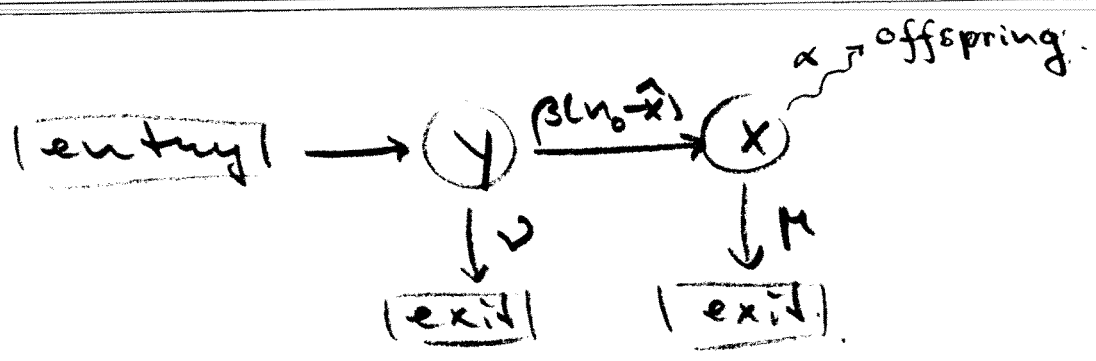


The transitions at equilibrium are all Poisson processes with a constant rate.

Expected lifetime of newborn:

$$T = \underbrace{\left| \frac{1}{\nu + \beta(n_0 - \hat{x})} \right|}_{\substack{\uparrow \\ \text{expected time} \\ \text{spent in state } Y}} + \underbrace{\left| \frac{\beta(n_0 - \hat{x})}{\nu + \beta(n_0 - \hat{x})} \right|}_{\substack{\uparrow \\ \text{probability} \\ \text{transition} \\ Y \rightarrow X}} \cdot \underbrace{\left| \frac{1}{\mu} \right|}_{\substack{\uparrow \\ \text{expected time} \\ \text{spent in } X}}$$

What is the expected lifetime number of offspring for a newborn at equilibrium?



Expected number of offspring:

$$E = \left[\frac{\beta(n_0 - \hat{x})}{\nu + \beta(n_0 - \hat{x})} \right] \cdot \left[\frac{1}{\mu} \right] \cdot \alpha$$

\uparrow probability of reaching state X. \uparrow expected time in state X. \uparrow expected number of offspring per unit of time while in X.

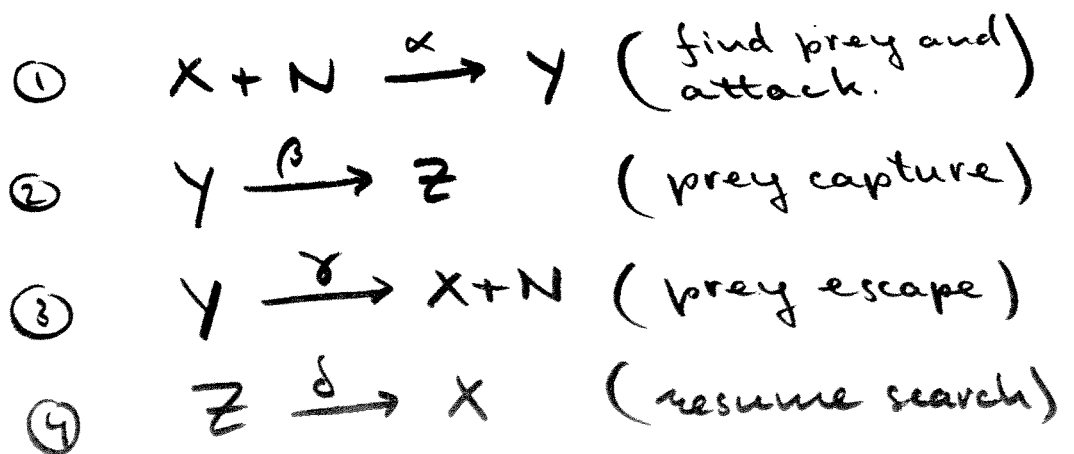
The present modelling approach readily leads to large systems of differential equations that are often difficult to analyze.

Example

i-states:

- N prey individual.
- X searching predator.
- Y attacking pred-prey pair.
- Z resting predator.

i-level processes



continued \rightarrow

⇒ p-level equations:

	(1)	(2)	(3)	(4)	
{	$\frac{dn}{dt} =$	$-\alpha x n$	$+$	γy	
	$\frac{dx}{dt} =$	$-\alpha x n$	$+$	γy	$+$ δz
	$\frac{dy}{dt} =$	$+\alpha x n$	$-\beta y$	$-\gamma y$	
	$\frac{dz}{dt} =$	$+$	βy	$-\delta z$	

4D
system

Conservation rule:

Total predator density
 $x + y + z = x_0$ is constant.
 Use this to eliminate z :

{*} {	$\frac{dn}{dt} =$	$-\alpha x n$	$+$	γy
	$\frac{dx}{dt} =$	$-\alpha x n$	$+$	$\gamma y + \delta (x_0 - x - y)$
	$\frac{dy}{dt} =$	$+\alpha x n - \beta y - \gamma y$		

This is still a 3D system:
 awkward to analyze.

→ Remedy: Time-scale separation.

- ~~Suppose that the is level processes of prey capture ② and prey escape ③ are fast compared to the other processes.~~
- ~~Suppose that the prey population is large compared to that of the predator.~~

(These are more or less realistic assumptions, by the way)

Then we can split the 3D system into two smaller systems of fast and slow variables and study them separately.

How this is done, we'll see in the next lecture.